

Call 6 INFORMATION DAY

14 January 2010

*Jean Monnet Building
Rooms M1, M3, M5 and M6
Luxembourg*

POSTER SESSION



1. AGELL Núria – Learning Actions Based on Human Sensory Abilities
2. BILSEN Greet – LICT: Leuven Center on ICT
3. BOURGUIGNON Eric – Cluster of Excellence CoTeSys (Cognition for Technical Systems)
4. BRENNER Claus – Spatio-Temporal Cognitive Systems
5. CORTÉS Ulises – I Like That (I Learn from Long-Term interaction with assistive robots)
6. DEL COSO Raul – Intelligent environments interacting with humans
7. DOMINGO Alicia – IBIT Foundation (recognition and human-computer interaction techniques)
8. ERDEM Arif Tanju – Artificial dialogue system via expressive speech and animation recognition and synthesis
9. ERLHAGEN Wolfram – Learning of Motor Intentions in Human Robot Interactions
10. FERRI Fernando – The Multimodal Platform
11. FRANCIS John Charles – Neural Router Cognitive Architecture
12. GERGELY Tamas – Cognitive Reasoning Framework
13. GOERKE Nils – Teaching Robots to be Autonomous
14. GONZALEZ Jose C. – Daedalus S.A
15. LEVAY Akos - Applied Logic Laboratory
16. MINGUEZ Javier – Robot learning using brain signals
17. MORGAVI Giovanna – Letole: Learning to learn
18. SCHOMMER Christoph - Data Mining/Knowledge Discovery
19. SCHRÖDER Marc – Self-Adaptive Learning Sensitive Artificial Listener
20. ZIEMKE Tom – Cognition & Interaction Lab

- 21.** BADII Atta – Intelligent Media Systems & Services Research Laboratories (IMSS)
- 22.** BALIYARASIMHUNI Sujit – Underwater Systems and Technologies Laboratory at Porto University
- 23.** BARROUIL Claude – ONERA : The French Aerospace Lab
- 24.** BEHNKE Sven – Networked Personal Robots
- 25.** BERRABAH Sid Ahmed – What is needed for autonomous navigation?
- 26.** BREUGELMANS Jeffrey – Northeastern University – Intelligent Human-Machine Systems Laboratory
- 27.** BOSETTI Paolo – Autonomous Machine Tools
- 28.** DITTMANN Florian – Human Well-Being Oriented Engineering of Robots and Artificial Semantic Systems
- 29.** GARCÍA VIEJO Faustino – Learning, reasoning and knowledge transmission system for mobile robots based on ontologies
- 30.** GROOTJEN Marc – Human-UUV Collaboration Ideas
- 31.** HAASS Uwe – CoTeSys – Cognition for Technical Systems
- 32.** HENDEBY Gustaf – Sensors networks, fusion and applications
- 33.** HENNIG Philipp – Probabilistic Methods for Control
- 34.** LIPNICKAS Arunas – Vehicle for a blind person
- 35.** LOPEZ DE VALLEJO Irene – Dependability and Safety in Complete Robotic Systems
- 36.** MICHEL Benoit – ROBIOSPHERE: A Heterogeneous Robotic System for Biosecurity
- 37.** MATTEUCCI Matteo – Low cost solutions to put service robots on the mass market
- 38.** METIN Huseyin – Robotics Research Groups from Turkey
- 39.** MOORE Roger K. - Conversational human robot interaction
- 40.** NORMAN Peter – Welding robots
- 41.** PULLES Kees – ISGGAR: Inspection System for Gas distribution Grids with Autonomous Robots
- 42.** RISTIC-DURRANT Danijela – Cognitive Processes in Mobile Robot-Assisted Gait Rehabilitation System
- 43.** SIMONOV Mikhail - Knowledge + ageing: how service robotics can act?
- 44.** SZUMILAS Lech – Autonomous Robot for Hazardous Industrial Environment
- 45.** VAN DER ZANT Tijn – PREMAS: Predicting and monitoring of human behaviour for activities and emergency situations
- 46.** VÖGELE Thomas – COURAGE (Cognitive Underwater Robots for Arctic and Generic Exploration) // SharedLab: Shared Use of Remotely Accessible Research Facilities
- 47.** WALKER Rich – The Shadow Robot Company
- 48.** WEISS Astrid – Studying Contextual Human-Robot Interaction: Usability and Beyond
- 49.** WIETFELD Christian - Communication Networks Institute of Dortmund University of Technology

50. RICHARDS Dale – QinetiQ: current activities and interests in Challenge 2

51. LJUNGGREN Inese - INTELLIGENT MACHINES STOCKHOLM AB