

# Cognitive Vision – The Development of a Discipline

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## The Emerging Discipline of Cognitive Vision

Computer vision is an important and maturing engineering science. It underpins an increasing variety of applications that require the acquisition, analysis, and interpretation of visual information. However, despite recent success in such areas as computational projective geometry [1,2] and appearance-based recognition [3], contemporary computer vision is still a relatively brittle technology. Consequently, its successful exploitation has been limited to relatively narrow application domains such as machine vision for industrial inspection, the analysis of video data for remote monitoring, and the creation of special effects in the film industry. The focus of much recent research has been on finding ways to reduce this brittleness.

The term *cognitive vision* has been introduced in the past few of years to encapsulate an attempt to achieve more robust, resilient, and adaptable computer vision systems by endowing them with a cognitive faculty: the ability to learn, adapt, weigh alternative solutions, and develop new strategies for analysis and interpretation.

The key characteristic of a cognitive vision system is its capacity to exhibit robust performance even in circumstances that were not foreseen when it was designed [4]. Furthermore, a cognitive vision system should be able to anticipate events and adapt its operation accordingly. Ideally, a cognitive vision system should be able to recognize and adapt to novel variations in the current visual environment, generalize to new contexts and application domains, interpret the intent of underlying behaviour to predict future configurations of the visual environment, and communicate an understanding of the environment to other systems, including humans.

### A Definition of Cognitive Vision

A cognitive vision system can achieve the four levels of generic computer vision functionality of detection, localization, recognition, and understanding.

It can engage in purposive goal-directed behaviour, adapting to unforeseen changes of the visual environment, and it can anticipate the occurrence of objects or events.

It achieves these capabilities through learning semantic knowledge (*i.e.* contextualized understanding of form, function, and behaviour); through the retention of knowledge about the environment, about itself, and about its relationship with the environment; and through deliberation about objects and events in the environment (including itself).

Cognitive vision requires the melding of two areas: computer vision and cognition. However, rather than view cognitive vision as some sort of mid-point on a spectrum of theories, models, and techniques with computer vision at one end and cognitive systems at the other, it turns out to be more helpful to view cognitive vision as a particular (vision-oriented) projection of the more general space of cognitive systems that embraces all perceptual modalities (see Figure 2). This projection creates a sub-space of cognitive systems, leaving in those capabilities that are necessary to vision but excluding

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those that are not necessary or are less relevant (such as pure reasoning, for example). This viewpoint suggests then that a cognitive vision system can best be viewed as a *visually-enabled cognitive system*, rather than, say, a cognitively-enabled computer vision system. Such a viewpoint extends naturally to other perceptual faculties such as hearing, touch, smell, and modes of interaction such as speech, gesture, manipulation, and exploration. It also re-directs attention to the core attributes of cognitive systems: robust performance, the ability to learn, adapt, weigh alternative solutions, and develop new strategies for analysis and interpretation. The challenge then becomes one of trying to see how we can build a theory that produces systems with these attributes in the context of visual perception. This does not diminish the critical significance of advanced traditional computer vision nor does it relegate it to a position of lesser relative importance. It simply places it in the context of systems-oriented research in cognition and, in fact, serves to highlight the multidisciplinary nature of the area.

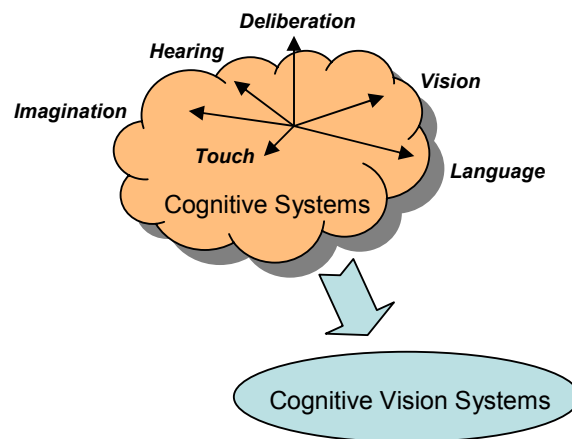


Figure 1: Cognitive Vision as a projection of the space of Cognitive Systems.

To study cognitive vision in depth and in all its guises, one must tackle a huge array of disciplines: computer vision, pattern recognition, artificial intelligence, cognitive science, perceptual psychology, developmental psychology, cognitive neuroscience, neurophysiology, cognitive robotics, semiotics, epistemology, systems sciences, cybernetics, autonomous systems theory, and probably others too. Add to this list the several branches of specialized mathematics that underpin many of these areas and you begin to see the breadth of the field. Of course, the focal point is still computer vision, but computer vision in a very multi-disciplinary context.

The multi-disciplinary nature of cognitive vision mirrors a general trend. Multi-disciplinary research and cross-disciplinary collaboration is becoming the new *modus operandi* in many branches of science today. Truly multi-disciplinary research institutes such as COGS - The Centre for Research in Cognitive Sciences at the University of Sussex,<sup>2</sup> CALD -- The Center for Automated Learning and Discovery in Carnegie Mellon University,<sup>3</sup> and the Santa Fe Institute,<sup>4</sup> which used to be viewed as exceptional in their outlook, are increasingly being looked at as models of how future research should be organized. Multi-disciplinary research is not straightforward, however. Apart from the problems associated with the disparate pre-dispositions of constituent disciplines and the need to achieve a shared understanding and language to facilitate a common research agenda, there is also the difficulty

<sup>2</sup> [www.informatics.sussex.ac.uk/cogs](http://www.informatics.sussex.ac.uk/cogs)

<sup>3</sup> [www.cald.cs.cmu.edu](http://www.cald.cs.cmu.edu)

<sup>4</sup> [www.santafe.edu](http://www.santafe.edu)

presented by having to integrate the ideas from both hard and soft sciences without losing the quantitative focus and the formal framework of mathematical modelling that are required for any computational emulation of a visually-enabled cognitive system.

## **The ECVision Network**

ECVision is a European research network for cognitive computer vision systems. It was inaugurated in March 2002 and is funded for three years by the European Commission under the Information Society Technologies (IST) Programme.

The brief of the network is to define, promote, develop, and disseminate information on cognitive vision systems rather than develop the underlying science and engineering. The network does its work under four main headings:

1. Research Planning;
2. Education & Training;
3. Information Dissemination;
4. Industrial Liaison.

The network pursues its objectives by a variety of means, most of which are based on facilitating peer-to-peer interaction amongst the foremost researchers in the area. Its two principal mechanisms are ‘specific actions’ and coordination workshops. Specific actions are mini-projects that are proposed by members of the network and, once they have been approved by both the ECVision Executive Committee and the European Commission Project Officer, are funded by ECVision. Examples of the type of specific action that have been supported by the network are provided below. The coordination workshops are typically round-table meetings between the leading European researchers in cognitive vision. Some are general meetings to plan activities; others are thematic networks devoted to focused topics in, for example, research<sup>5</sup> and education.

The following is a selection of some highlights of the work of the network over the past two-and-a-half years.

***The ECVision Research Roadmap:*** this is the network’s plan for the future of the discipline, a way of identifying what the critical issues are in the development of the scientific foundations of the discipline. Many of the ideas presented in this article were taken from it.

***The ECVision Annotated Bibliography:*** members of ECVision have created a web-based keyword-indexed bibliography of publications relevant to cognitive vision, complete with article abstracts.

***The ECVision Cognitive Vision Ontology:*** this is a catalogue of scientific topics and techniques that are used in some approaches to cognitive vision such as learning, knowledge representation, recognition, reasoning, and visual process control.

***Cognitive Vision Course Syllabus:*** an outline for a typical full-year course with 54 lecture hours. It includes a list of internet resources and published material.

***The ECVision Summer School:*** two week-long summer schools targeted at post-graduate students have been held near Bonn, one in 2003 and the other in 2004. These events, attended by some 50

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<sup>5</sup> Although the ECVision network puts a considerable amount of effort into the research area, it is important to note that the network itself does not conduct the actual research (this is a constraint of the type of contract under which the network is funded).

participants each year, have proved extremely effective in promoting the discipline to young researchers and thereby preparing for the next wave of research and development.

**On-Line Education** is supported through the established CVonline repository. ECVision has facilitated both content provision and the re-organization of CVonline to highlight topics that are relevant to cognitive vision.

**Prize for Best Application Development:** the network has sponsored a prize for the company that has best adopted the cognitive vision philosophy of adaptive learning in its products. This prize was won by Inx Systems Corp., Finland for its Optigrader on-line volume and quality measurement timber inspection system. Figure 2 shows a picture of Risto Pettinen, Inx Systems Export Director, receiving the prize from Patrick Courtney, ECVision Area Coordinator for Industrial Liaison, at the prize-giving at ECCV 2004 in Prague in May 2004.



Figure 2: Patrick Courtney (left), ECVision Area Coordinator for Industrial Liaison, presents Risto Pettinen (right), Inx Systems Export Director, with the prize of the best application development in cognitive vision systems at ECCV 2004 in Prague in May 2004.

**Industrial Survey:** a survey of existing and emerging applications of cognitive vision technology in a range of industry sectors including surveillance, industrial inspection, stock photo databases, industrial robotics, film TV and media, life science, and aerospace.

Support for the development of the discipline is provided in a number of other ways too. These include best paper prizes, sponsorship of conference workshops & colloquia, and sponsorship of student and staff exchanges.

### **What's a Cognitive Vision System Useful For?**

Even though we focus primarily on the scientific development of cognitive vision systems in this article, it is important not to forget that the ultimate purpose of cognitive vision is to facilitate more robust commercial vision-based applications. Consequently, the involvement of industrial interests is crucial to the development of the area, both to provide focus on potential applications and identify essential functionality. Typically, cognitive vision systems will provide adaptable and adaptive interfaces between humans and machines. These interfaces will be part of applications that either monitor human behaviour or interact with humans, or both, especially in surroundings and situations

that cannot be modelled completely when the system is being designed. Example applications include surveillance and monitoring, for instance to provide 'home-help' for the elderly, for security purposes, or for assessing the behaviour of shoppers in retail outlets. Other applications include autonomous navigation, interactive toys, semantic annotation of image databases, and monitoring of adaptive advertisements.

In addition to providing application drivers for visually-enabled cognitive systems, industrial involvement in the network is important to ensure effective utilization of the techniques being developed: different aspects of the discipline mature at different times and by having industry involved it is easier to spot opportunities for timely commercial exploitation.

## The Last Word

The creation of cognitive systems depends to a great degree on inherent systemic development, through learning, development, and exploration. Cognitive systems - visual or otherwise - are shaped by their experiences. The ultimate aim and guiding principle in cognitive vision research is to seek for simple cognitive principles and mechanisms from which complex cognitive behaviour can emerge, in whatever paradigm one is operating. ECVision is helping to uncover these principles by acting to define the discipline of cognitive vision, by facilitating creative interaction between researchers, by developing educational material, and by fostering the involvement of industry so that the discipline emerges from application requirements as well as scientific innovation.

## To Find Out More

Details on every aspect of ECVision are contained on the website at [www.ecvision.org](http://www.ecvision.org). Requests for information should be sent to [coordinator@ecvision.org](mailto:coordinator@ecvision.org) or simply fill in the enquiry form on the website.

### Facts and Figures

IST Project number:	IST-2001-35454
Coordinating unit in the Commission:	Unit E5 - Cognition
Start date:	1 <sup>st</sup> March 2002
Duration:	3 Years
Total number of member institutes:	49
Number of member institutes joined since inception:	20
Number of specific actions launched:	25
Community Funding:	€1,176,600
Principal Contractor:	Computer Applied Techniques Ltd., Ireland
Coordinating members:	University of Bonn, Germany INPG, France INRIA, France KTH, Sweden University of Edinburgh, United Kingdom University of Sussex, United Kingdom PB Consulting, Germany

## A Brief Overview of Paradigms in Cognition and Cognitive Vision

There are several distinct approaches to the understanding and synthesis of cognitive systems. These include physical symbol systems, connectionism, artificial life, dynamical systems, and enactive systems [5,6]. Each of these makes significantly different assumptions about the nature of cognition, its purpose, and the manner in which cognition is achieved. Among these, however, we can discern two broad classes: the *cognitivist* approach based on symbolic information processing representational systems; and the *emergent systems* approach, embracing connectionist systems, dynamical systems, and enactive systems, and based to a lesser or greater extent on principles of self-organization.

Cognitivism asserts that cognition involves computations defined over symbolic representations, in a process whereby information about the world is abstracted by perception, represented using some appropriate symbol set, reasoned about, and then used to plan and act in the world. This approach has also been labelled by many as the *information processing* approach to cognition [7,8,9,10,11,12,5]. Traditionally, this has been the dominant theme in cognitive science [8] but there are indications that the discipline is migrating away from its stronger interpretations [6].

For cognitivist systems, cognition is representational in a strong and particular sense: it entails the manipulation of explicit symbolic representations of the state and behaviour of an objective external world [13]. Reasoning itself is symbolic: a procedural process whereby explicit representations of an objective world are manipulated and possibly translated into language.

In most cognitivist approaches concerned with the creation of artificial cognitive systems, the symbolic representations are the product of a human designer. This is significant because it means that they can be directly accessed and understood or interpreted by humans and that semantic knowledge can be embedded directly into and extracted directly from the system. However, it has been argued that this is also the key limiting factor of cognitivist vision systems: these designer-dependent representations are the idealized descriptions of a human cognitive entity and, as such, they effectively bias the system (or 'blind' it [13]) and constrain it to an domain of discourse that is dependent on and, a consequence of, the cognitive effects of human activity. This approach works well as long as the system doesn't have to stray too far from the conditions under which these descriptions were formulated. The further one does stray, the larger the 'semantic gap' [14] between perception and possible interpretation, a gap that is normally plugged by embedding programmer knowledge or enforcing expectation-driven constraints [15] to render a system practicable in a given space of problems.

Emergent systems, embracing connectionist, dynamical, and enactive systems, take a very different view of cognition. Here, cognition is a process of self-organization whereby the system is continually re-constituting itself in real-time to maintain its operational identity through moderation of mutual system-environment interactions and co-determination [16]. Co-determination implies that the cognitive agent is specified by its environment and at the same time that the cognitive process determines what is real or meaningful for the agent. In a sense, co-determination means that the agent constructs its reality (its world) as a result of its operation in that world.

Co-determination is one of the key differences between the emergent paradigm and the cognitivist paradigm. For emergent systems, perception provides appropriate sensory data to enable effective action [16] but it does so as a consequence of the system's actions. In the emergent paradigm, cognition and perception is functionally-dependent on the richness of the action interface [17].

Dynamical systems theory is one of the most promising approaches to the realization of emergent cognitive systems. Advocates of the dynamical systems approach to cognition (*e.g.* [8,12,18]) argue that motoric and perceptual systems, as well as perception-action coordination, are dynamical systems, that self-organize into meta-stable patterns of behaviour.

Proponents of dynamical systems point to the fact that they directly provide many of the characteristics inherent in natural cognitive systems such as multi-stability, adaptability, pattern formation and recognition, intentionality, and learning. These are achieved purely as a function of dynamical laws and consequent self-organization. They require no recourse to symbolic representations, especially those that are the result of human design.

Enactive systems take the emergent paradigm even further. In contradistinction to cognitivism, which involves a view of cognition that requires the representation of a given objective pre-determined world [18,5], enaction [19,20,21,16,22,5,13] asserts that cognition is a process whereby the issues that are important for the continued existence of the cognitive entity are brought out or enacted: co-determined by the entity as it interacts with the environment in which it is embedded. Thus, nothing is 'pre-given', and hence there is no need for symbolic representations. Instead there is an enactive interpretation: a real-time context-based choosing of relevance. The advantage is that it focusses on the dynamics by which robust interpretation and adaptability arise.

Recently, effort has gone into developing approaches which combine aspects of the emergent systems and cognitivist systems [17,4,23]. These *hybrid* approaches have their roots in strong criticism of the use of explicit programmer-based knowledge in the creation of artificially-intelligent systems [24] and in the development of active 'animate' perceptual systems [25] in which perception-action behaviours become the focus, rather than the perceptual abstraction of representations. Such systems still use representations and representational invariances but it has been argued that these representations should only be constructed by the system itself as it interacts with and explores the world rather than through *a priori* specification or programming [17]. Thus, a system's ability to interpret objects and the external world is dependent on its ability to flexibly interact with it and interaction is an organizing mechanism that drives a coherence of association between perception and action. Action precedes perception and 'cognitive systems need to acquire information about the external world through learning or association' [4]. Hybrid systems are in many ways consistent with emergent systems while still exploiting programmer-centred (but not programmer-populated) representations (for example, see [26]).

It is important to be aware that the different paradigms of cognitive vision are not equally mature and it isn't clear which paradigm will ultimately be successful. The arguments in favour of dynamical systems and enactive systems are compelling but, though they offer great promise, the current capabilities of cognitivist systems are actually more advanced. However, they are also quite brittle and have achieved little in the cognitive capabilities associated with generalization. Enactive and dynamical systems should in theory be much less brittle because they emerge through mutual specification and co-development with the environment, but their cognitive capabilities are actually very limited at present. The extent to which this will change and the speed with which this change will occur is uncertain. Hybrid approaches seem to offer the best of both worlds but it is unclear how well one can combine what are ultimately highly antagonistic underlying philosophies.

**The Balance between Phylogeny and Ontogeny:  
Hard-Wired Functionality vs. Learned Capabilities**

In cognitive systems, one often distinguishes between *phylogeny* and *ontogeny*. Phylogeny refers to the initial configuration of the system and its evolution from generation to generation. On the other hand, ontogeny refers to the learning and development of a given system during its lifetime. The issue that arises in this context is the requirements for the minimal architecture for a cognitive vision system. There are two perspectives on this, depending on whether one takes a cognitivist stance or an emergent stance.

In the cognitivist stance, the issue comes down to the balance between required 'pre-knowledge' and acquirable knowledge. Or, put another way, how much does one need to know and to be able to do in order to be capable of learning new things, such as concepts or actions? That is, we need a clear cut set of conditions under which certain learning can take place.

In the emergent stance, there is a trade-off between phylogenic configuration and ontogenic development. Phylogeny determines the visuo-motor capability that a system is configured with at the outset and which facilitates the system's innate behaviours. Ontogenic development gives rise to the cognitive capabilities that we seek. Since we don't have the luxury of having evolutionary timescales to allow phylogenic emergence of a cognitive system - we can't wait around to evolve a cognitive system from nothing - we must somehow identify a minimal phylogenic state of the system. In practice, this means that we must identify and effect visuo-motor capabilities for the minimal reflex behaviours that ontogenic development will subsequently build on to achieve cognitive behaviour. Put simply: we need to decide what visual processing capabilities are needed for a minimal emergent cognitive vision system.



### The Necessity of Embodied Cognition

The question as to whether cognitive vision systems have to be physically embodied or not is one of the most contentious and divisive issues in the field. The divisiveness arises from the different stances taken by the different paradigms.

From the perspective of the cognitivist paradigm, there is actually no case for embodiment, at least none for it as a mandatory requirement of cognition. Cognitivist systems don't necessarily have to be embodied. The very essence of the cognitivist approach is that cognition comprises computational operations defined over symbolic representations and these computational operations are not tied to any given instantiation. They are abstract in principle. It is for this reason that it has been noted that cognitivism exhibits a form of mind-body dualism [12,27]. Symbolic knowledge, framed in the concepts of the designer, can be programmed in directly and doesn't have to be developed by the system itself through exploration of the environment. Some cognitivist systems do exploit learning to augment or even supplant the *a priori* designed-in knowledge and thereby achieve a greater degree of adaptiveness, reconfigurability, and robustness. Embodiment may therefore offer an additional degree of freedom to facilitate this learning, but it is by no means necessary. The clear advantage of this position is that a successful cognitivist model of cognition could be instantiated in any context and, theoretically at least, be ported to any application domain.

The perspective from emergent systems is diametrically opposed to the cognitivist position. Emergent systems, by definition, must be embodied and embedded in their environment in a situated historical developmental context [12]. To see why embodiment is a necessary condition of emergent cognition, consider what cognition means in the emergent paradigm. It is the process whereby an autonomous system becomes viable and effective in its environment. In this, there are two complementary things going on: one is the self-organization of the system as distinct entity<sup>6</sup>, and the second is the coupling of that entity with its environment. 'Perception, action, and cognition form a single process' [27] of self-organization *in the specific context of environmental perturbations of the system*. This gives rise to the co-development of the cognitive system and its environment and thereby to the ontogenic development of the system itself over its lifetime. This development is identically the cognitive process of establishing the space of mutually-consistent couplings. Put simply, the system's actions define its perceptions but subject to the strong constraints of continued dynamic self-organization. The space of perceptual possibilities is predicated not on an objective environment, but on the space of possible actions that the system can engage in whilst still maintaining the consistency of the coupling with the environment. These environmental perturbations don't control the system since they are not components of the system (and, by definition, don't play a part in the self-organization) but they do play a part in the ontogenic development of the system.

Through this ontogenic development, the cognitive system develops its own epistemology, *i.e.* its own system-specific knowledge of its world, knowledge that has meaning exactly because it captures the consistency and invariance that emerges from the dynamic self-organization in the face of environmental coupling. Thus, we can see that, from this perspective, cognition is inseparable from 'bodily action' [27]: *without physical embodied exploration, a cognitive system has no basis for development*.

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<sup>6</sup> The self-organization is achieved through an operationally-closed network of activities characterized by circular causality [8] and possibly modelled by a dynamical system defined over space of order parameters and control parameters.

### Advances in Related Disciplines

The discipline of cognitive vision is developing in the context of other disciplines which are themselves evolving and changing. New insights will come not only from the cognitive vision community but also from the broader multi-disciplinary community. We note here just two examples of how advances in related disciplines will have an impact on our own efforts to create the solid foundations of visually-enabled cognitive systems. The disciplines involved are cognitive science, neuroscience, and epigenetic robotics.

In the last 10 years or so, an ever growing number of cognitive scientists [28,29] have begun to appreciate the possibility of instantiating cognitive models in robotic systems. The space of research spanned is quite wide, starting from the locomotion and organizational behaviors of insects and early vertebrates [30,31] through models of high order cognitive skills in humans such as social behaviors [32], imitation [33,34,35], communication, and language [34,36,37,38,39]. More recently a new strain of research explicitly included developmental aspects and the modeling of development [40,41] and epigenetic robotics [40]. Examples are the work of Metta and Sandini [42,43,44,45], of the group of Pfeifer [46,47,48], and of Dautenhahn *et al.* [49,50].

Imitation is one of the key stages in the development of more advanced cognitive capabilities. While the study of infants and adults ability to imitate has remained foremost a field of the psychological literature, recently, it has found a ground in the neurological literature with the discovery of the mirror neuron system in monkeys [51]. The mirror neuron system is formed by pre-motor neurons discharging both when the animal acts and when it sees similar actions performed by other individuals. A system, similar to that found in monkeys, has been indirectly shown to exist also in humans by trans-cranial magnetic stimulation studies of the motor cortex during action observation [52]. Further investigations have shown that the mirror system can be activated not only by visually perceived actions but also by listening to action-related sounds [53] and, in humans, by speech listening [54]. In addition to these electrophysiological data, in humans, a number of brain imaging studies point all to a network of brain areas responsible for the visuo-motor transformation mechanism underlying action recognition [55,56]. It is plausible that the motor resonant system formed by mirror neurons is involved in someone else's action understanding and, at least in humans, imitation.

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