

eu Robotics

coordination action

Main objectives

- 1. Improvement of cooperation between all robotics stakeholders and domains
- 2. Promotion of European robotics

This project's ambition is to create sustainable solutions to both goals through targeted stimulation of grass-roots initiatives of concern to all robotics stakeholders, especially the industrial and academic communities. Key players from both the industrially driven European Robotics Technology Platform EUROP and the academically driven European Robotics Research Network EURON are members of this consortium. The euRobotics consortium is furthermore supported by the membership of both networks, thus building on the expertise and experience of numerous European experts in robotics.

Main actions

Bridge the gap between academia and industry

- Identify hindering gaps and define Grand Challenges for European robotics
- Monitor, adapt and enable the implementation of the Strategic Research Agenda for European robotics
- Establish a European PhD School in Robotics
- Establish advanced training for the robotics industry
- Establish a common terminology and create the "robotics semantic web"

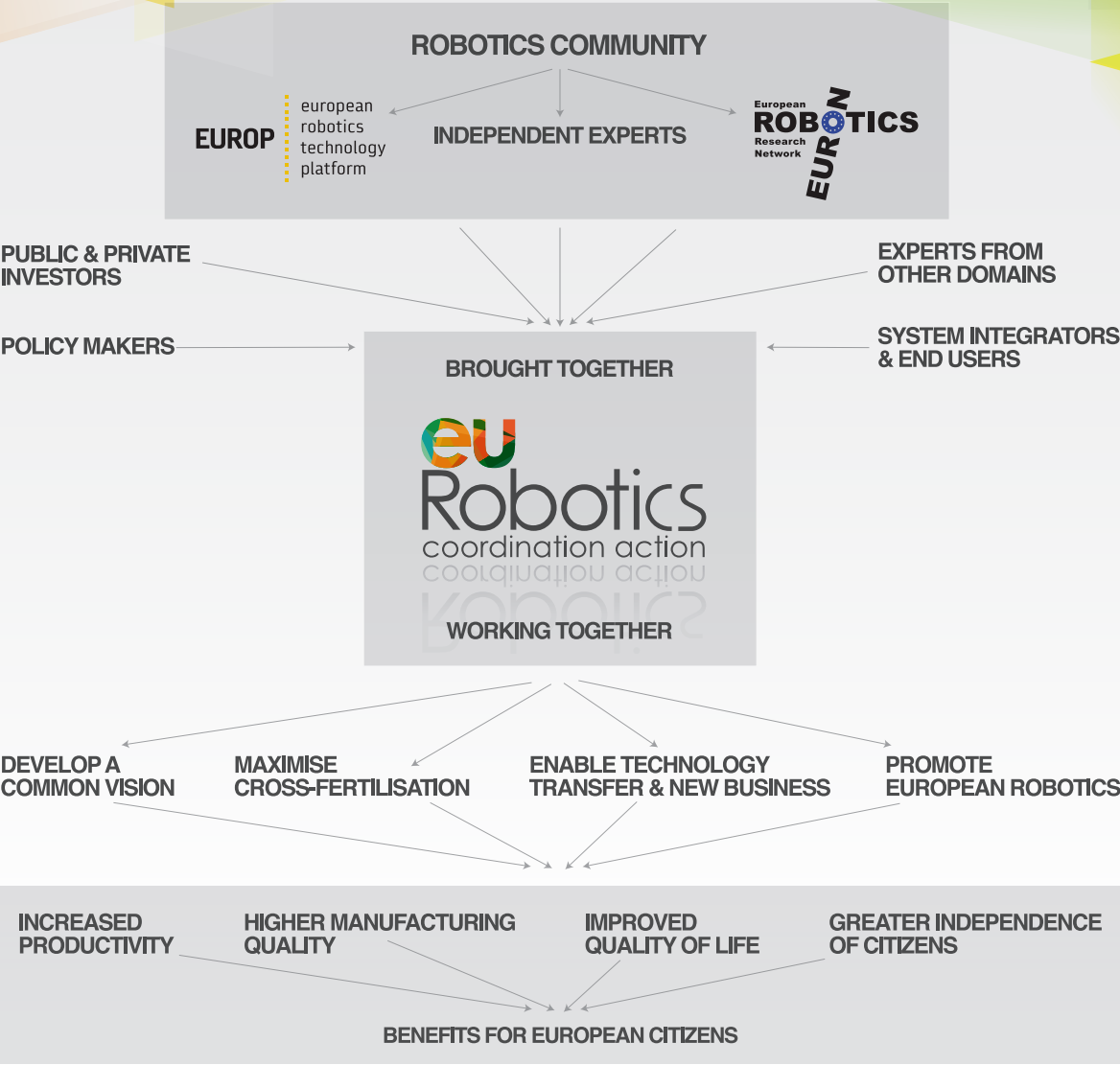
Promote European robotics

- Improve the public relations activities for European robotics
- Create a press centre

Facilitate exploitation of European robotics R&D

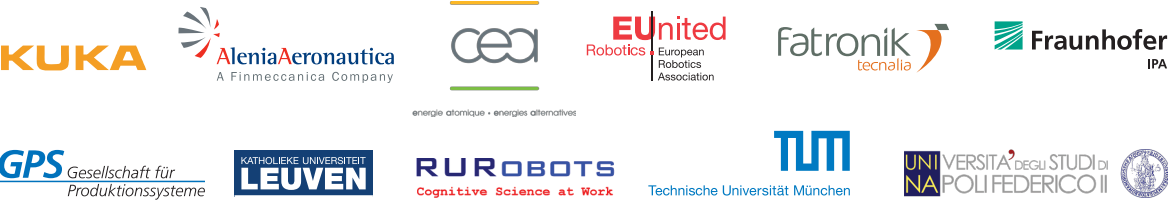
- Foster and promote entrepreneurship
- Analyse ethical, legal and societal issues
- Perform market studies
- Push standardisation activities

Strategic coordination and networking to strengthen the European robotics community



Contact:
EUROP Secretariat. c/o EUnited Robotics. Anne Wendel
Diamant Building. Boulevard A. Reyers, 80. 1030 Brussels. Belgium
Phone: +32 2706 8222. Email: secretariat@robotics-platform.eu

Project Partners:



The euRobotics Coordination Action is funded by the European Commission within the 7th Framework Programme un, Challenge 2: Cognitive Systems, Interaction, Robotics (FP7-ICT-248552; 01/2010 - 12/2013)

www.eurobotics-project.eu