

Confidential




ICT-2009.3.2-248603-IP



Modelling, Control and Management of Thermal Effects in Circuits of the Future



	WP no.	Deliverable no.	Lead participant
	WP7	D7.1.1	NXP-NL
Validation and standardization of thermal models			
Prepared by	M. Willemsen		
Issued by	THERMINATOR Project Office		
Document Number	THERMINATOR/D7.1.1/v1		
Dissemination Level	CONFIDENTIAL		
Date	01/02/2013		

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Document

Title	Validation and standardization of thermal models
Type	Deliverable CO
Ref	D7.1.1
Target version	V1_1
Current issue	V0_1
Status	released
File	
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Approver(s)	G.Gangemi(ST)
Approval date	01/02/2013
Release date	

Distribution of the release

Dissemination level	CO
Distribution list	

History

Rev.	DATE	Comment
0.1	22-01-2013	Initial version
1.0	29-01-2013	Revised version, approved by all partners
1.1	01/02/2013	Check and ship out

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- [4] Therminator Deliverable D1.1.1 "Preliminary measurement data for various types of devices"
- [5] Therminator Deliverable D2.1.2 "Model based comparison of temperature effects on device parameters for different technology nodes"
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1 Introduction

The main objective of WP7 is to validate the models, design techniques, and tools developed within the Therminator project. WP7 is divided into three tasks. In T7.1, validation of the thermal models of new devices, materials, and technologies will be done. The focus will be on device level, and the level of elementary building blocks to be used in large(r) circuits. The effectiveness and usability of design techniques is addressed in T7.2. In T7.2, larger building blocks, parts of circuits, and test chips are used as test cases. Finally, benchmarking and demonstration of the effectiveness of the developed EDA tools is done in T7.3. In this task, the validation addresses test chips and prototypes.

The validation results of T7.1 are presented in this deliverable. The validation activities are done with models and tools developed in WP2, 3, 4, 5, and 6. For demonstration, the test case of WP1 and examples provided by individual partners are used. The test cases of WP1 come from various fields relevant to today's European semiconductor industry. Examples are in digital, analog, RF, discrettes, and power technologies, covering a wide range of devices from advanced CMOS to high-voltage devices in automotive, and addressing different technologies from silicon-on-insulator (SOI) technologies to GaN HEMTs. Since the validation activities are carried out mainly on device level, major attention is given to demonstrating the accuracy and predictability of TCAD tools, and verification of the developed compact models for circuit design. The value of calibrating thermal models in TCAD tools on test cases, in particular measurements, is that these tools can then be used as a reliable source for future device improvements and roadmap activities. In other words, validated TCAD tools allow the European semiconductor industry to improve their devices and make realistic roadmaps for the future. Several examples of these calibration and validation activities between TCAD vendors and Research institutes together with partners from the industry are presented in this report. Examples include power MOSFET (SNPS-CH, ST), advanced CMOS (FHG, SNPS-CH, IMC), and bipolar (SNPS-CH, NXP-D). Verification of compact models is important, since these models are the starting point for circuit design. Inaccurate or improperly validated compact models will result in additional hardware spins and product delays. Examples of the validation of these models for circuit design are on advanced CMOS (IMC), discrettes (BME, NXP-D) and RF-LDMOS (NXP-NL). Devices of the future, such as FinFETs (UNIBO), advanced CMOS (FHG), 3D ICs (IMEC), and GaN-HEMTs (NXP-NL) are also addressed. Finally, the major industrial partners show the usefulness of the tools developed in Therminator by demonstrating the compatibility with their design flows.

In detail, the compact models for RF-LDMOS and GaN-HEMTs developed in WP2 by NXP-NL are validated in chapter 2. In chapter 3, the TCAD models developed by SNPS-CH are compared to measurement data provided by partners. The validation of the models developed in WP5 for discrete components for automotive is presented in chapter 4 by ST. NXP-D compares measurements on devices used in their contactless identification ICs with models from FHG in chapter 5. An overview of the PSP-based modelling of advanced CMOS is presented by IMC in chapter 6. TCAD of advanced CMOS and FinFETS compared to measurements is presented in chapters 7 and 8 by FHG and UNIBO, respectively. In chapter 9, the thermal models for 3D ICs developed by IMEC in WP6 are compared to and validated against measurements. BME compares their thermal measurements and compact models to packaged discrettes provided by NXP-D in chapter 10. The results of T7.1 are quantified in terms of measurable objectives. An overview of all of these measurable objectives is given in chapter 12 of this report. In this chapter, the measurable objectives are also linked to Therminator's project objectives. The novelty of the work is addressed in chapter 13, where all of the output in terms of journal papers and conference contributions is collected.

2 Compact electro-thermal modelling (NXP-NL)

2.1 Introduction

High-voltage transistors are used as RF-power amplifiers in wireless communication systems. Examples of these communication systems are TV broadcast, radar, and base-stations. In most of these communication systems, Silicon RF-LDMOS transistors are used for power amplification. For future systems, gallium-nitride (GaN) technology will be increasingly used; GaN has already been introduced in some high-performance systems. The advantages of gallium nitride in power applications are due to a combination of material properties and device architecture. The material advantages are a large band gap, high critical electrical breakdown field, and high electron velocity. In the high-electron-mobility-transistor (HEMT) architecture of GaN transistors no insulator is used, avoiding mobility reduction due to scattering at the insulator interface. The benefits in material properties and device architecture can be exploited to achieve higher switching speeds and lower losses in power amplification applications.

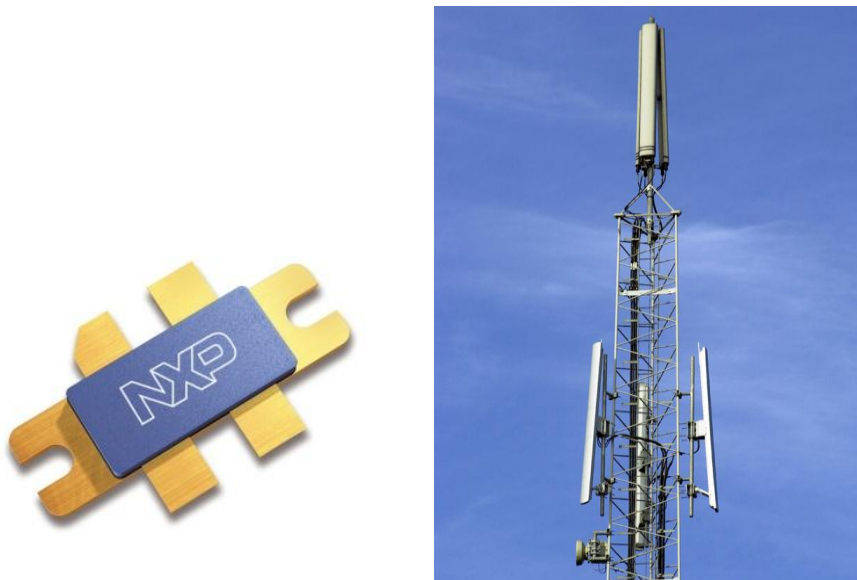


Figure 1 A packaged RF-LDMOS transistor is shown in the figure on the left. One of the major applications of RF-LDMOS transistors is wireless communication in base-stations. A base-station is shown in the figure on the right.

In both silicon RF-LDMOS and GaN-HEMT devices, the high applied voltages in combination with large currents lead to high dissipated powers, which in turn result in significant amounts of self-heating. In order to optimize the performance of these power amplifiers in applications, compact models for circuit simulation, accurately describing the electro-thermal behaviour, are needed. In deliverables D2.2.1 and D2.2.3, compact models for electro-thermal circuit simulation for silicon RF-LDMOS and GaN-HEMT (respectively) have been developed. The developed models are physics-based, using physical scaling rules. The advantage of these physics-based models is that the model extraction is done on a small device, while the physical scaling rules are used for larger devices. This approach allows one to extract all of the different device layouts in an efficient way. In this deliverable, these models will be validated using measurements and numerical calculations. More specifically, we will validate the electro-thermal compact models for circuit simulation developed in the

Therminator deliverables D2.2.1 and D2.2.3 using pulsed and non-pulsed IV measurements in Section 2.2.1. Furthermore, the integration of the electro-thermal models into the design flow will be demonstrated, and validation on measurement data under application conditions will be presented. In Section 2.2.2, the physical scaling of the thermal resistance in the compact thermal models will be validated against numerical calculations using a Green's function method. The results of applying the S-parameter method to determine the thermal resistance on different device types are given in Section 2.2.3. In this section, we apply the thermal characterization to different device types not studied in the previous Therminator deliverables, *i.e.* silicon-on-insulator (SOI) LDMOS and GaN Schottky diodes. The measurement results are compared to the developed models.

2.2 Technical results

2.2.1 Validation of the thermal models for RF-LDMOS and GaN-HEMT with measurements

The conventional approach in the development of electro-thermal compact models is to use a combination of pulsed and DC IV measurements in the temperature range of interest. Both pulsed and (non-pulsed) DC IV measurements are needed in order to be able to separate electrical, temperature-dependent, and self-heating effects. The pulsed measurements are done with pulses fast enough so that self-heating doesn't occur. For the parameter extraction in the compact model, the pulsed IV measurements are used to extract the electrical model parameters. Subsequently, the temperature sensitivities of these electrical parameters are obtained from the pulsed IV measurements at other temperatures. The final step is to fit the thermal resistance, and its temperature dependence, on (non-pulsed) DC IV measurements at different temperatures. Note that in this approach the thermal resistance is only a fitting parameter in the model that accounts for the differences between pulsed and (non-pulsed) DC IV measurements. Furthermore, there is no direct validation of the thermal resistance, since it is not measured directly.

In order to measure the thermal resistance of a device directly, S-parameter measurements can be used. Using this S-parameter measurement technique, pulsed IV measurements are also not needed in the parameter extraction of the model. The thermal resistance is measured directly, and can be set to the correct value in the compact model. The (non-pulsed) DC IV characteristics at different temperatures are used to extract the electrical model parameters and the corresponding temperature dependence. In Therminator deliverables D2.2.1 and D2.2.3, this novel S-parameter technique for direct extraction of the thermal resistance was applied to RF-LDMOS and GaN-HEMT power technologies. The thermal resistance was characterized directly. These S-parameter measurements were used to set the thermal resistance to the correct value in the corresponding compact models. Next, the model parameters were extracted on the (non-pulsed) DC IV characteristics.

In this part of the deliverable, we will validate the models developed in deliverable D2.2.3 and D2.2.1 using pulsed and (non-pulsed) DC IV measurements over a wide range of temperatures. Note that the pulsed IV measurements have not been used in the model development and parameter extraction.

The results of this validation for the RF-LDMOS technology are collected in

Figure 2, Figure 3, and Figure 4. The measured pulsed and DC $I_D V_{DS}$ characteristics of an RF-LDMOS transistor at different temperatures are compared to the compact electro-thermal model in

Figure 2. The pulsed measurements were done with a pulse width of 50 ns. It was checked, by variation of the pulse width, that the applied pulses were fast enough such that self-heating didn't occur. Comparison of pulsed measurement data at different temperatures shows that the amount of current decreases with increasing temperature (see left column of

Figure 2), and the developed RF-LDMOS model correctly describes this temperature dependence. In the right column of

Figure 2, the (non-pulsed) $I_D V_{DS}$ characteristics are shown. These IV characteristics clearly exhibit self-heating, as the current is smaller in comparison to pulsed IV characteristics, and the current decreases with increasing bias. The developed model accurately describes the DC IV measurement data.

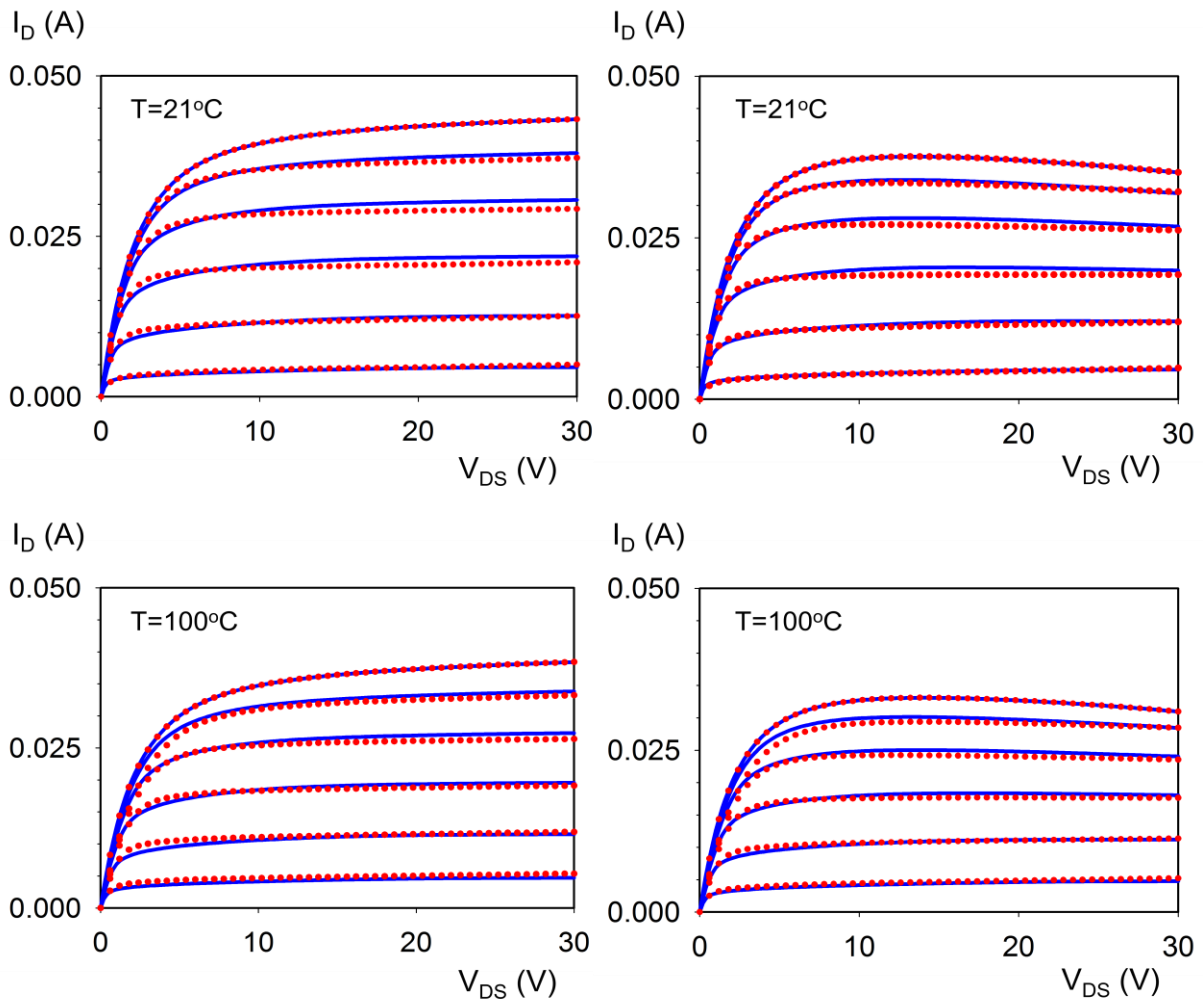


Figure 2 $I_D V_{DS}$ characteristics at $V_{GS} = 2.5, 3, 3.5, 4, 4.5,$ and 5 V of the RF-LDMOS device measured at temperatures of $T = 21$ and 100 °C. The figures in the left column show the pulsed IV characteristics, using a pulse width of 50 ns. The figures in the right column show

the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (blue solid lines) are in good agreement for the measured bias conditions and temperature range.

The IV characteristics of a larger RF-LDMOS device are shown in Figure 3 and Figure 4. The reason for showing these characteristics as well is that the compact thermal model, derived in deliverable D2.2.1, has physics-based scaling rules for the thermal resistance. Only S-parameter measurements of the smallest geometry, of which the IV characteristics are shown in

Figure 2, are needed to determine the thermal resistance. Using the physical scaling rules of our model, the thermal resistance for larger devices are calculated. Comparison of the measured pulsed and (non-pulsed) DC IV characteristics of such a larger device, shown in Figure 3 and Figure 4, to the model demonstrates that these scaling rules give the correct results. Furthermore, it should be noted that for larger devices, with larger currents, it becomes more difficult to supply fast pulses and measure the pulse IV characteristics without self-heating. Compare the small device of

Figure 2, where pulses of 50 ns are applied, to the larger device of Figure 3 and Figure 4, where pulses of 0.5 μ s had to be applied. Although in both cases the pulses were checked to be fast enough to eliminate self-heating, it is known that the equipment has difficulty in supplying these pulses, fast enough to prevent self-heating, to larger devices. The reasons are the higher currents of these larger devices and the lower impedances of these larger devices with respect to the reference impedance of 50 Ω used in the equipment. In the conventional modelling approach, in which pulsed and (non-pulsed) IV characteristics are used, this becomes a problem. However, in our S-parameter method, together with the physics-based scaling rules, characterization of a small device is sufficient. All of the devices in the power technology are characterized at once with the tools developed in WP2 of Therminator. The problems with characterization of larger devices are now circumvented.

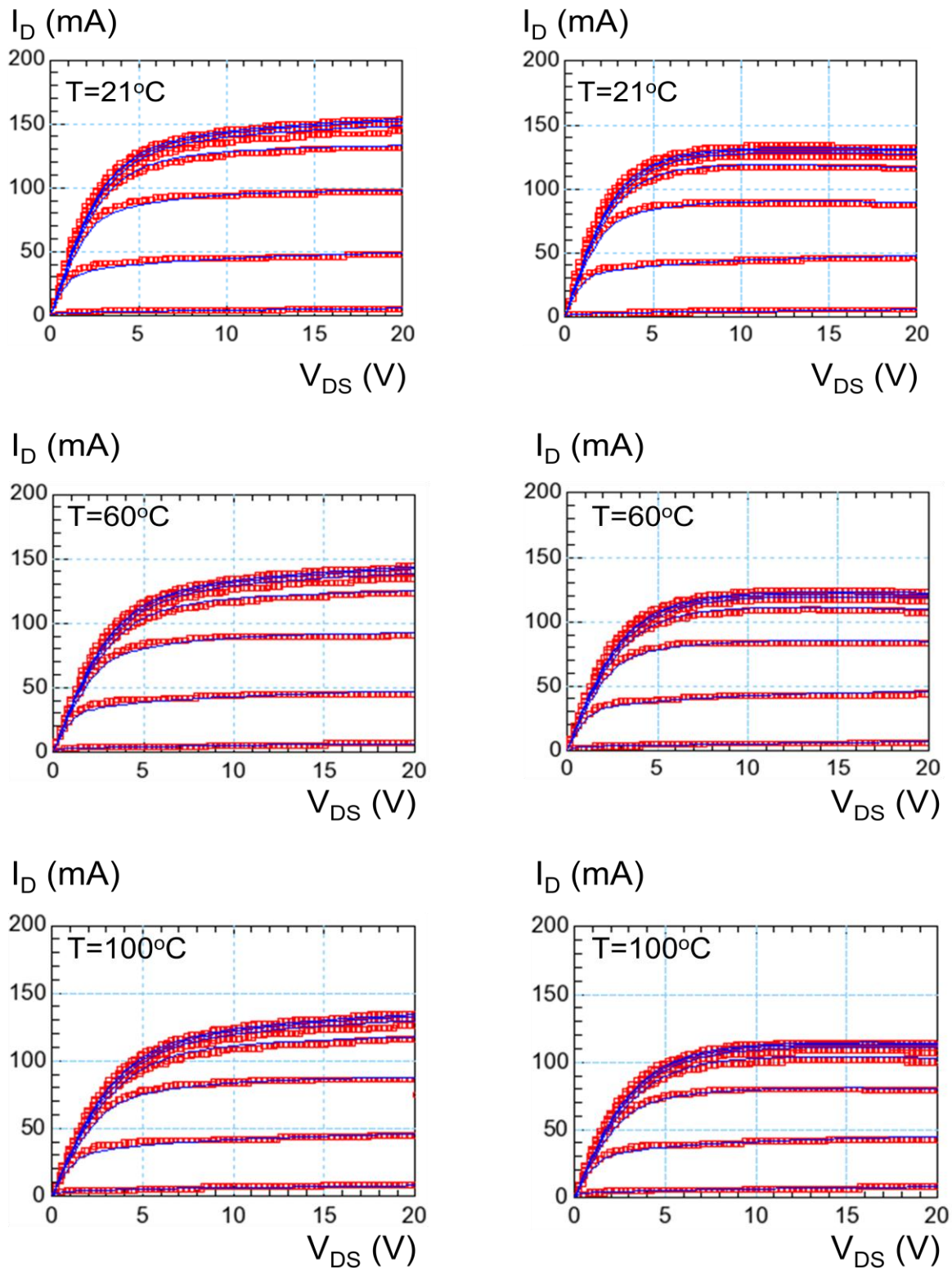


Figure 3 $I_D V_{DS}$ characteristics of a larger RF-LDMOS device measured at temperatures of $T = 21, 60,$ and $100\text{ }^\circ\text{C}$. The figures in the left column show the pulsed IV characteristics, using a pulse width of 500 ns. The figures in the right column show the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (blue solid lines) are in good agreement for the measured bias conditions and temperature range.

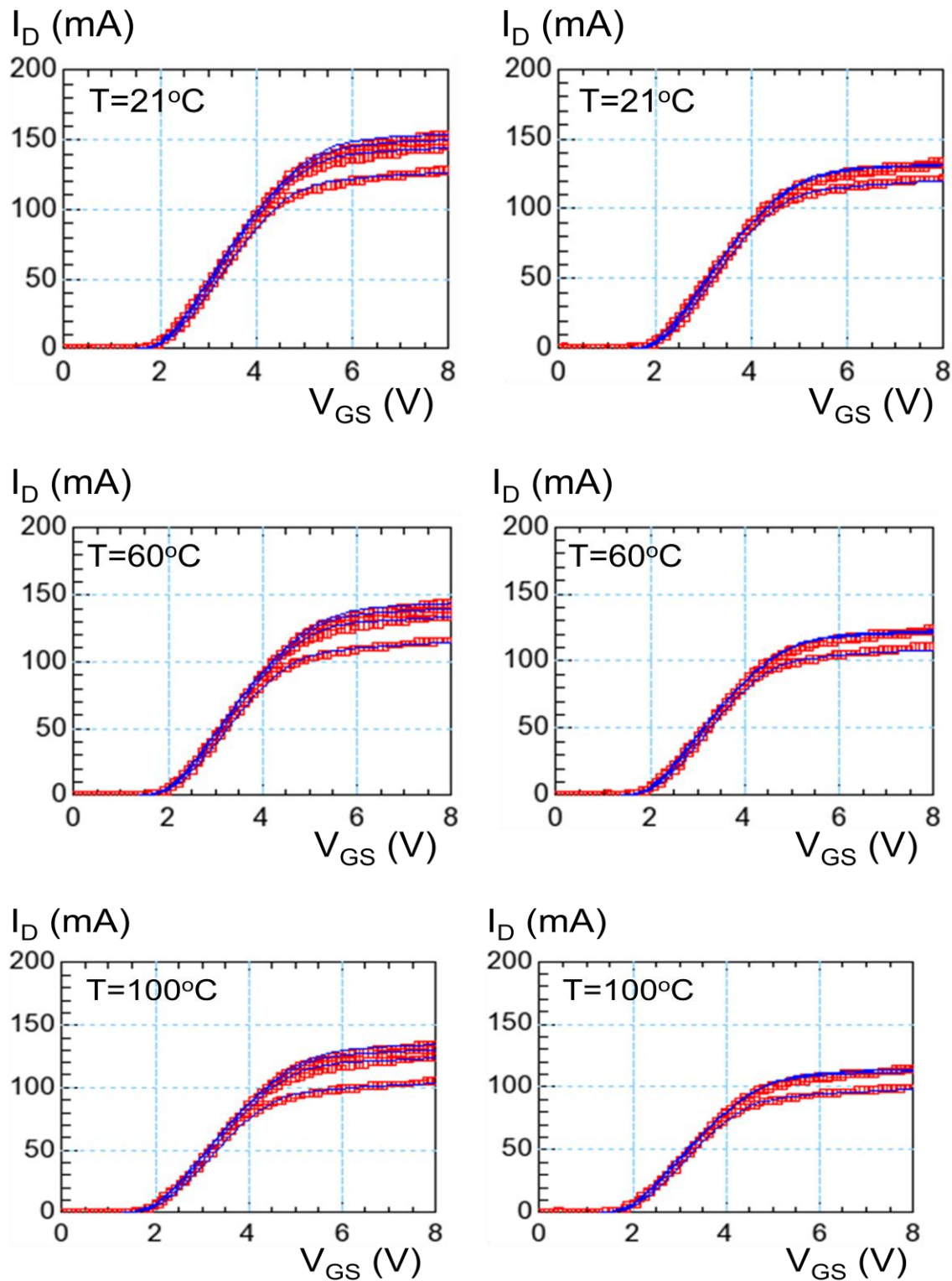


Figure 4 $I_D V_{GS}$ characteristics of a larger RF-LDMOS device measured at temperatures of $T = 21, 60,$ and 100°C . The figures in the left column show the pulsed IV characteristics, using a pulse width of 500 ns. The figures in the right column show the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (blue solid lines) are in good agreement for the measured bias conditions and temperature range.

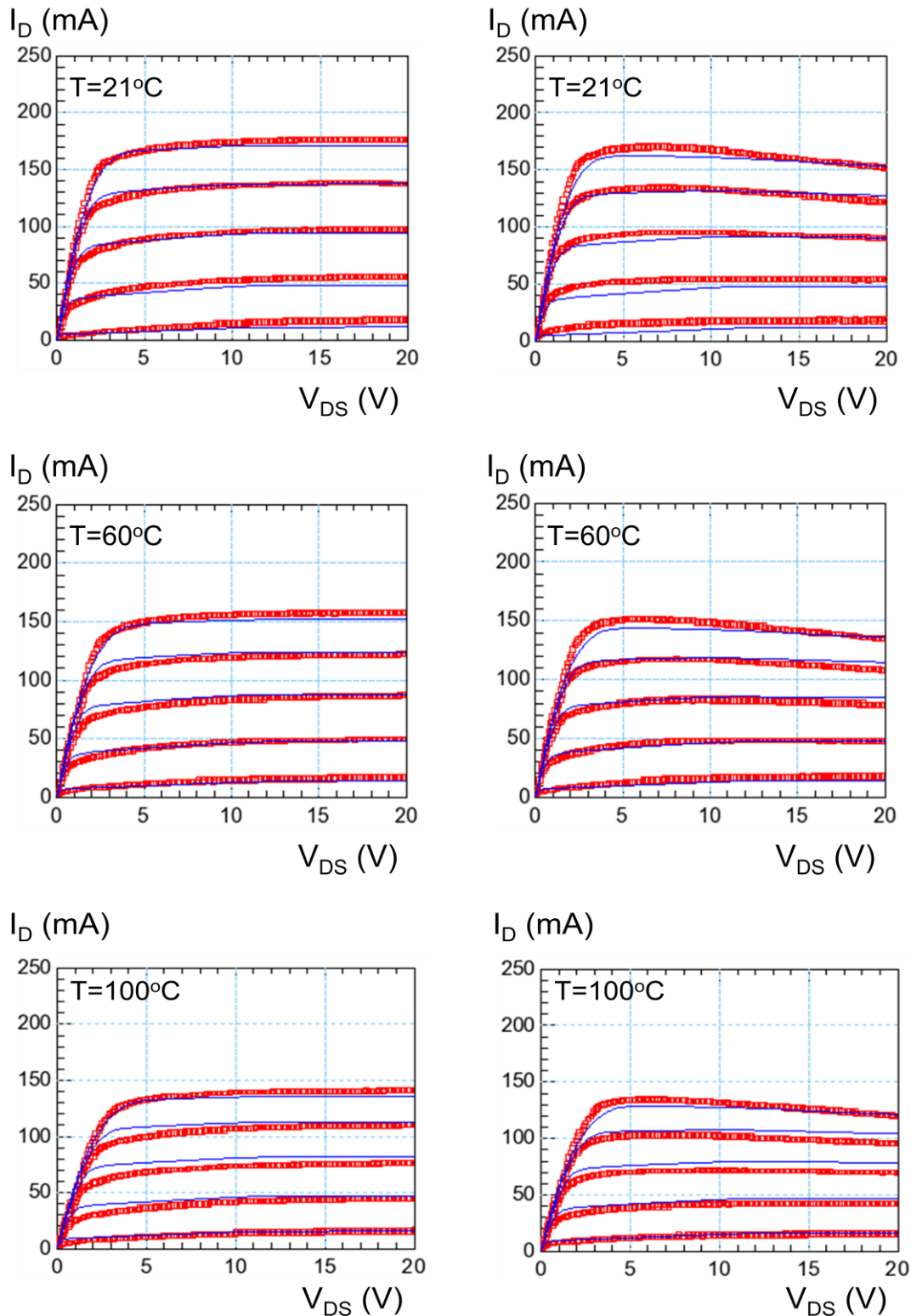


Figure 5 $I_D V_{DS}$ characteristics of a GaN-HEMT device measured at temperatures of $T = 21$, 60 , and 100 °C. The figures in the left column show the pulsed IV characteristics, using a pulse width of 500 ns. The figures in the right column show the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (blue solid lines) are in good agreement for the measured bias conditions and temperature range

Validation on the GaN-HEMT devices was done in the same way. A comparison of measured pulsed and (non-pulsed) IV characteristics to the corresponding electro-thermal GaN-HEMT model developed in Therminator deliverable D2.2.3 is shown in Figure 5. Measurements and model were found to agree.

In summary, a detailed validation of the electro-thermal compact models for power technologies developed in WP2 of Therminator on pulsed and non-pulsed IV-characteristics has been presented (see

Figure 2–Figure 5) demonstrating our measurable objective MO7.1.1 of validation of thermal models for RF-LDMOS and GaN-HEMT.

In Figure 6, the S-parameter measurement technique for directly determining the thermal resistance is validated for other types of device, *i.e.* larger RF-LDMOS transistors as used in Therminator deliverable 2.2.1. Measurements and simulations are in agreement. This comparison demonstrates the accuracy of the physical scaling rules derived in WP2 of Therminator. Thermal characterization of the smallest geometry is sufficient. Benefits of this approach include (i) time-efficient characterization of all geometry variants within a technology, and (ii) no need to measure large devices, which are difficult to characterize.

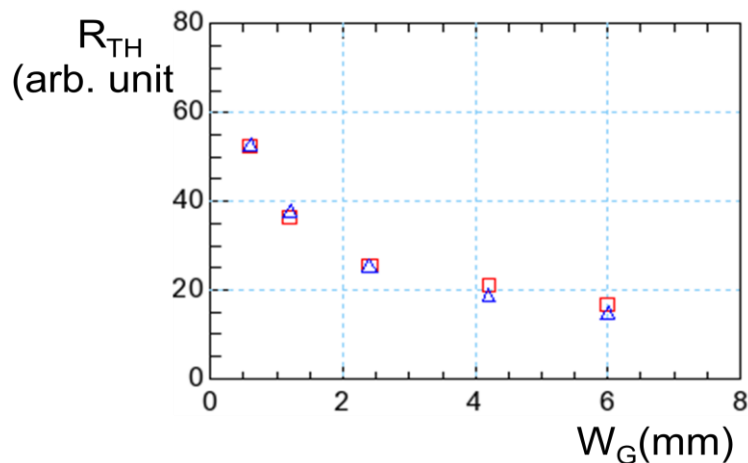


Figure 6 Validation of the S-parameter measurement technique for other type of device, *i.e.* larger RF-LDMOS transistors as used before. The RF-LDMOS transistors used in deliverable D2.2.1 had a maximum total gate width W_G below 2.5 mm. Measurements are shown as red squares, and the electro-thermal compact model results are shown as blue triangles.

The thermal compact model for RF-LDMOS developed in Therminator has been integrated into a commercial design flow, as shown in the snapshot of Figure 7. The model integrated into the commercial simulator has been used to do large-signal simulation, and validation with measurements under application conditions. The results of these simulations and validation activity are reported in Figure 8 and Figure 9. The large signal measurements were done on a load-pull system, with active tuning of the load impedances. This active tuning of the load impedances allows one to accurately measure the transistors for optimum performance, in this case efficiency. In Figure 8, the comparison of large signal measurements and simulations for optimum efficiency in class-AB operation is shown. The comparison of large signal measurements and simulations for optimum efficiency in class-C operation, which is important for Doherty amplifiers, is shown in Figure 9. Under both operation conditions, the electro-thermal model accurately matches the measurements. In conclusion, we have embedded the RF-LDMOS model into our design flow and compared it to measurement data taken under typical application conditions (see Figure 7–Figure 9), demonstrating our

measurable objective MO7.1.3 of integration of the electro-thermal model for RF-LDMOS into design tools and validation on large-signal application data.

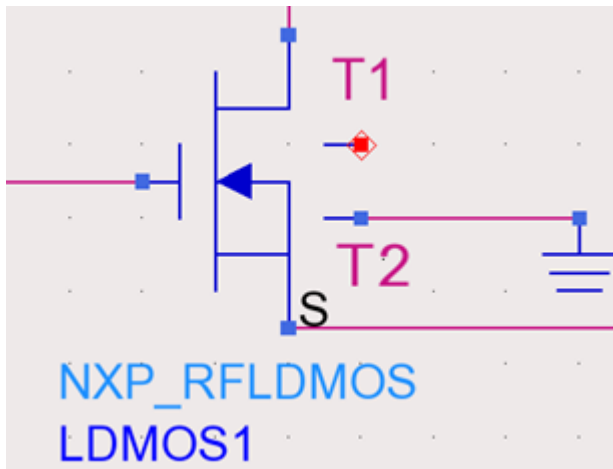


Figure 7 Schematic representation of the electro-thermal RF-LDMOS model in a commercial design tool, *i.e.* the Agilent ADS simulator. The nodes T1 and T2 are the nodes of the thermal compact model derived in Therminator deliverable D2.2.1.

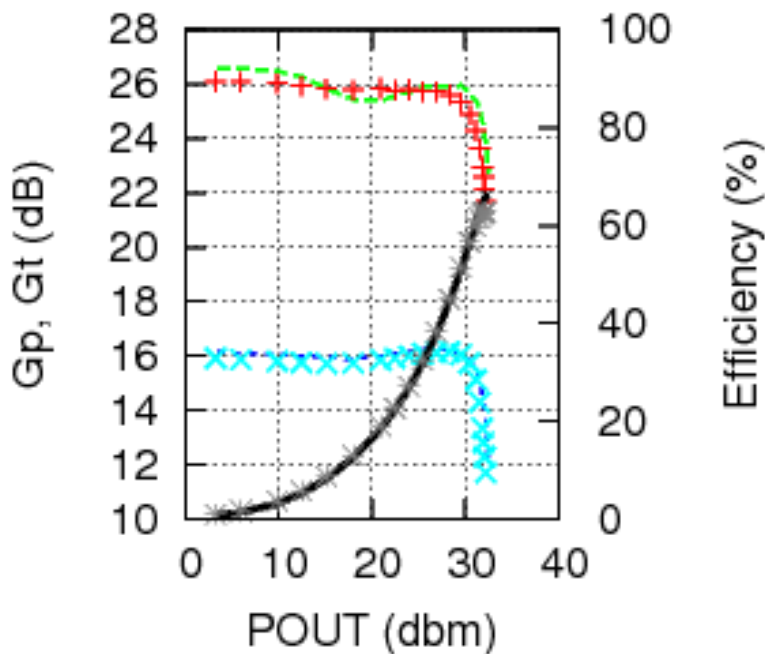


Figure 8 Large-signal validation in class-AB operation of the RF-LDMOS model. The power gain (G_P), transducer gain (G_T), and efficiency are shown as a function of the output power. The red markers and green line correspond to the measured and simulated power gain (G_P), whereas the light blue markers and dark blue line correspond to the measured and simulated transducer gain (G_T), both displayed on the left y-axis. The grey markers and black line correspond to the measured and simulated efficiency, displayed on the right y-axis.

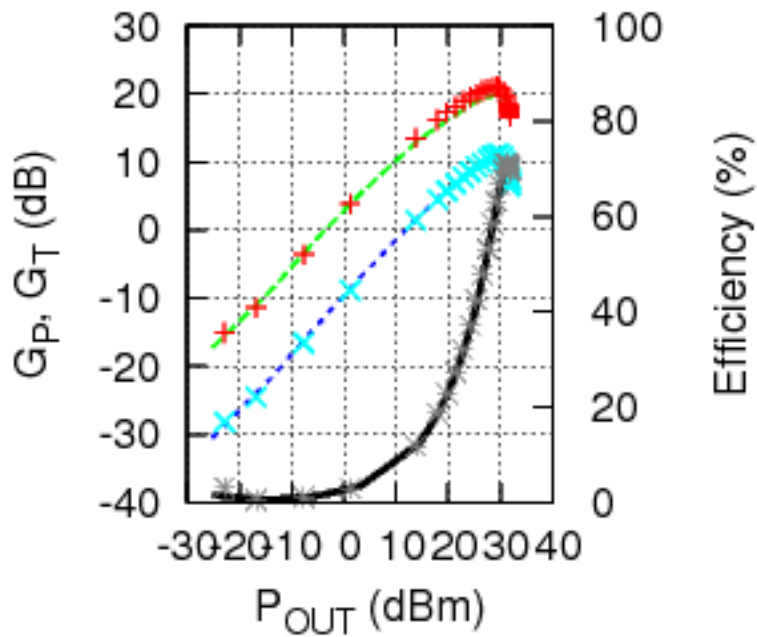


Figure 9 Large-signal validation in class-C operation of the RF-LDMOS model. The power gain (G_P), transducer gain (G_T), and efficiency are shown as a function of the output power. The red markers and green line correspond to the measured and simulated power gain (G_P), whereas the light blue markers and dark blue line correspond to the measured and simulated transducer gain (G_T), both displayed on the left y-axis. The grey markers and black line correspond to the measured and simulated efficiency, displayed on the right y-axis.

2.2.2 Validation of the electro-thermal compact model with numerical calculations

In Therminator deliverable D2.2.1, a compact thermal model was derived for arrayed power transistors. In this section, the physical scaling rules of the thermal resistance of this compact thermal model will be validated with numerical calculations. Since a complete mathematical derivation of the thermal resistance of the compact thermal model was already given in deliverable D2.2.1, we will only highlight the approach followed, and summarize the main approximations.

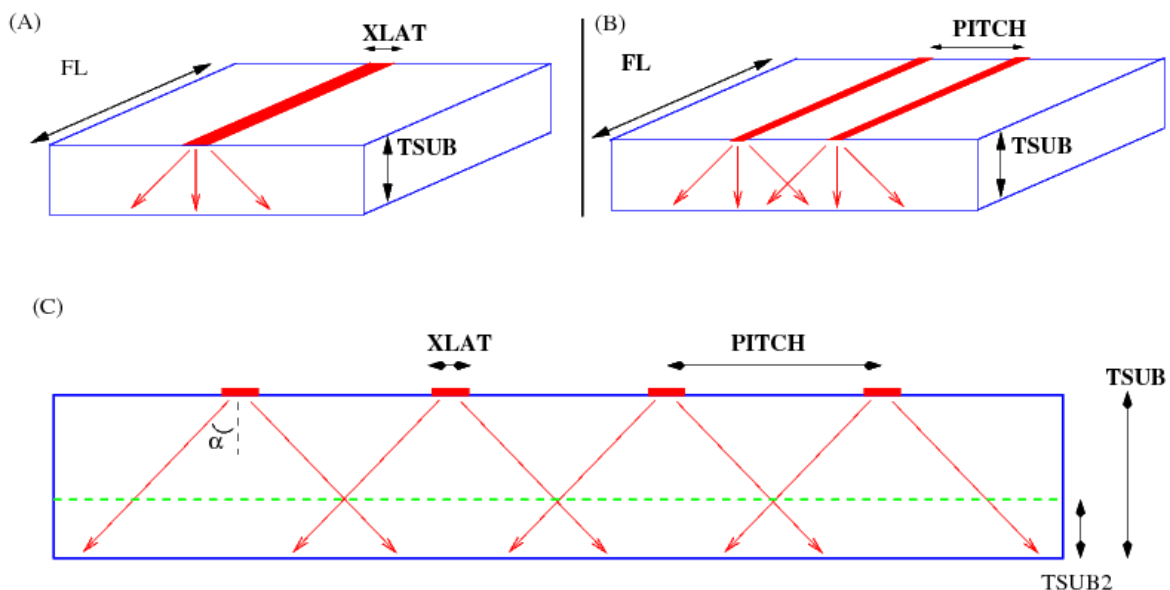


Figure 10 A power device with finger length FL and lateral dimensions XLAT is represented by a heat source at the surface of the substrate shown in figure A. In practice, multiple devices are organized in arrays, and thermal cross-talk or mutual heating will occur, as shown as in figure B. A compact thermal model for transistors, separated by a distance PITCH in an array, was derived in Therminator deliverable D2.2.1 by assuming that the heat flows within an angle α into the substrate. In the upper layer of the substrate, no mutual heating occurs, whereas in the bottom layer the heat conduction is proportional to the total area of the array (see figure C).

In a power device, the heat is generated at the surface of the substrate, where the current is transported. For a single transistor, the heat is generated in a rectangular area. The dimensions of this area are the finger length FL and the lateral dimension of current flow XLAT. The finger length is the width of the device. XLAT corresponds to the distance from the source to the drain. Since the finger length ($\sim 0.1\text{--}1$ mm) is much longer than the lateral dimension ($\sim 2\text{--}5$ μm), thermal effects at the end of the finger were neglected in the compact thermal model. For this reason, the heat source of a single transistor was modelled as a uniform strip, as shown in Figure 10A. In practical devices, multiple transistors are arranged in arrays (see Figure 10B), and thermal cross-talk or mutual heating will occur. In the compact thermal model, it was assumed that the heat flows within an angle α into the substrate, as shown in Figure 10C. The thermal resistance of the arrayed devices was calculated in the compact thermal model by assuming that (i) no mutual heating in the top layer of the substrate occurs, and (ii) the heat conduction is proportional to the area of the total array in the bottom layer of the substrate (see Figure 10C). With the aforementioned approximations, it was demonstrated in deliverable D2.2.1 that it is possible to derive an analytical expression for the thermal resistance depending on all relevant geometry variables for power technologies, *i.e.* finger length, lateral device dimension, pitch, and substrate thickness.

In order to validate the compact thermal model, numerical calculations of the thermal resistance were done using an in-house software tool. These numerical calculations are based on directly solving the heat equation using a Green's function approach. This numerical approach is of course too time-consuming to be integrated within a compact device model of the transistor for fast circuit simulations. However, directly comparing the results of these numerical calculations using the Green's function approach to the derived compact thermal model for different layout variations is possible. The main results of this comparison are collected in Figure 11 to Figure 14. In Figure 11, the thermal resistance of the thermal compact model is compared to the results of the numerical calculations using a Green's function method as a function of finger length.

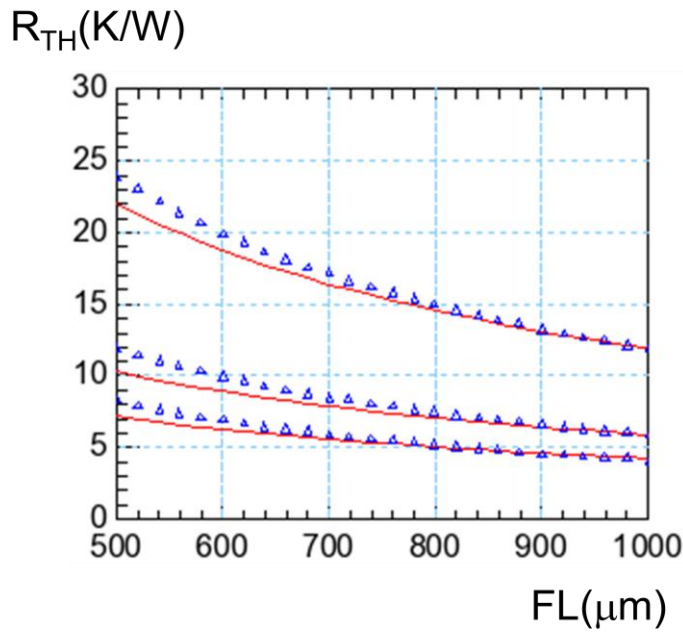


Figure 11 Validation of the thermal compact model (blue markers) with numerical calculations using a Green’s function method (solid red line). The thermal resistance is shown as a function of finger length FL for a single-cell device, 3 devices, and 5 devices in parallel.

A similar type of validation is shown in Figure 12, where both methods are compared for different pitches.

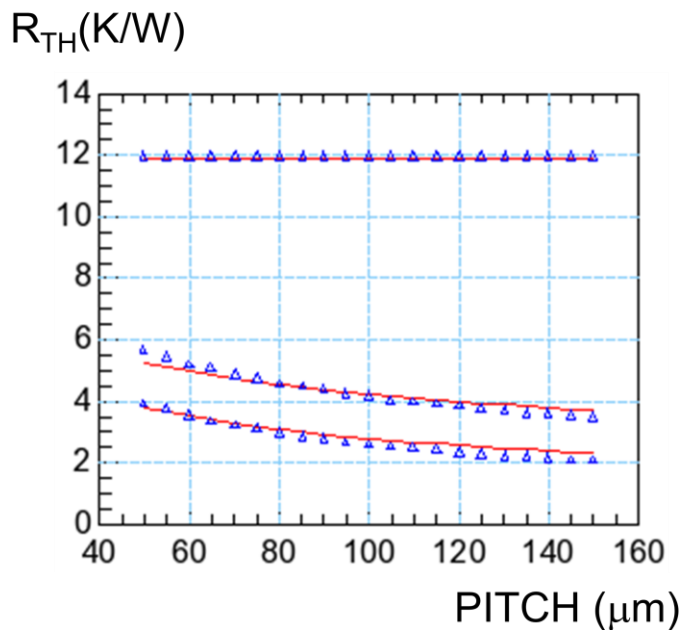


Figure 12 Validation of the thermal compact model (blue markers) with numerical calculations using a Green’s function method (solid red line). The thermal resistance is shown as a function of PITCH, for a single-cell device, 5 devices, and 9 devices in parallel. The PICTH has no meaning in the case of a single-cell device, and the thermal resistance is constant.

Finally, the thermal resistance of the thermal compact model is compared to the numerical results of the Green’s function method as a function of the number devices in parallel, as

shown in Figure 13, and Figure 14. In summary, Figure 11–Figure 14 demonstrate that the approximations made in the thermal compact model are validated by the numerical calculations using the Green’s function method for all the relevant geometry variations in a power technology.

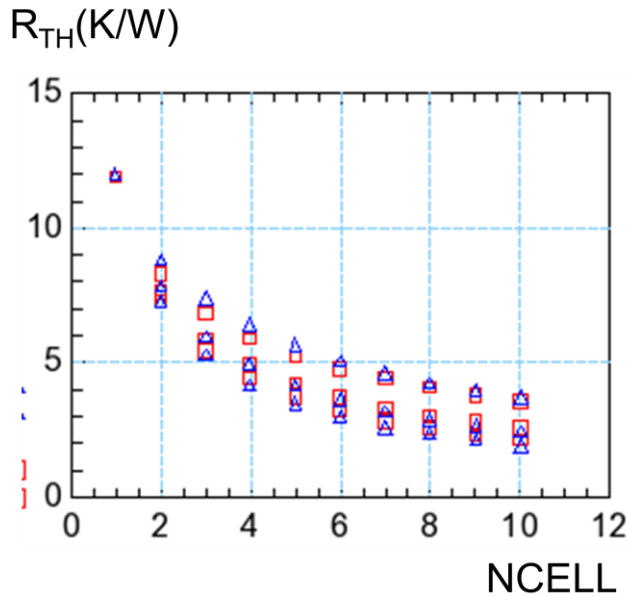


Figure 13 Validation of the thermal compact model (blue markers) with numerical calculations using a Green’s function method (red markers). The thermal resistance is shown as a function of the number of cells for PITCHES of 50, 100, and 150 µm.

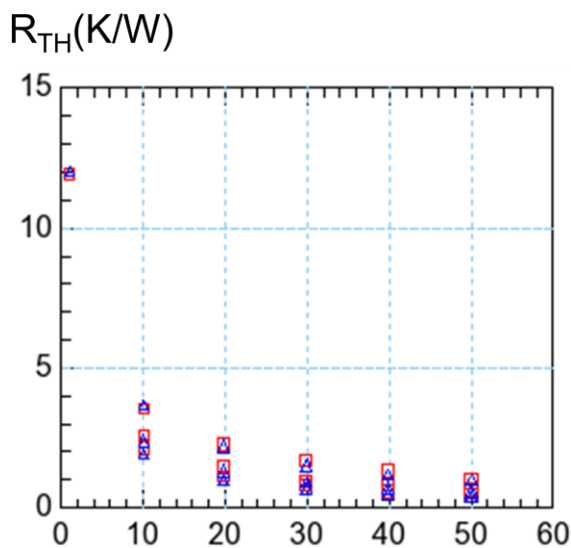


Figure 14 Validation of the thermal compact model (blue markers) with numerical calculations using a Green’s function method (red markers). The thermal resistance is shown as a function of the number of cells for PITCHES of 50, 100, and 150 µm.

2.2.3 Validation on different types of device

In this section, the S-parameter method for determining the thermal resistance is applied to different device types not studied in the previous Therminator deliverables (D2.2.1 and D2.2.3). For the silicon devices, silicon-on-insulator (SOI) LDMOS devices are studied

instead of the RF-LDMOS devices. For GaN devices, Schottky diodes instead of GaN HEMTs are measured and validated with a model.

The basic working principle of the physics-based electro-thermal compact model is shown in Figure 15. The total dissipated power in the device, P_{diss} , is calculated from the compact model describing the electrical characteristics of the device. The thermal network calculates the temperature increase with respect to the ambient temperature using the dissipated power. The calculated temperature increase results in a different parameter set for the compact model of the device, which in turn results in a different amount of dissipated power. The final transistor temperature and dissipated power are known after the compact device model and thermal model have converged in the circuit simulator.

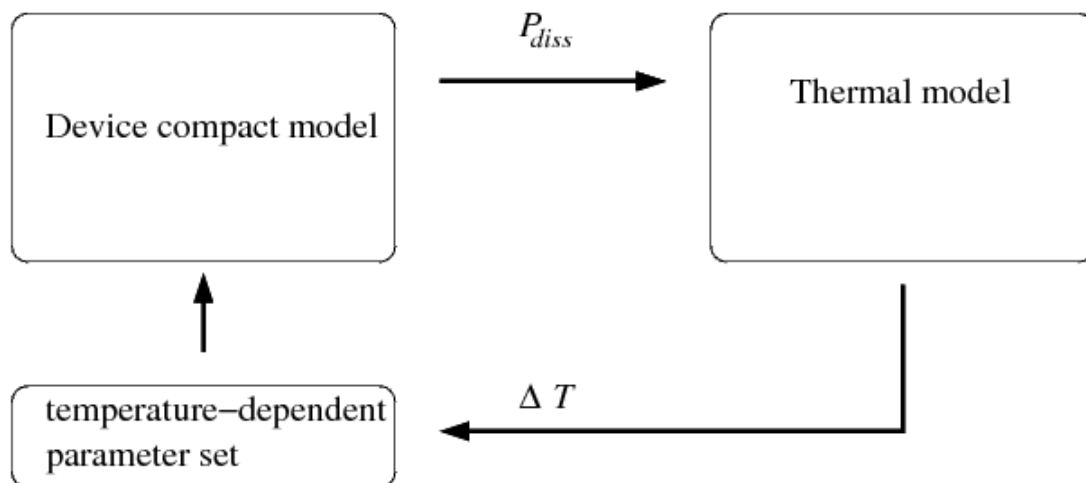


Figure 15 Schematic overview of the working principle of a device compact model in combination with a thermal model. For modelling the GaN Schottky diode, the device compact model of the GaN HEMT, developed in deliverable D2.2.3, will be replaced by a developed GaN Schottky diode model. For modelling the SOI-LDMOS, the thermal model for RF-LDMOS, developed in deliverable D2.2.1, will be adapted for SOI.

To study and compare measurements with models for the different device types, appropriate changes need to be made in existing models developed in WP2 of Therminator. These changes can be in the device compact model and/or in thermal model of Figure 15. In order to study the GaN Schottky diodes, the GaN-HEMT compact device model as developed in D2.2.3 needs to be replaced by a Schottky diode model. The thermal model can be reused, because the Schottky diodes are organized in arrays in the same way as the RF-power devices (see Figure 10). For SOI-LDMOS, the silicon RF-LDMOS model approach can be used as a starting point. In this case, the main modifications are in thermal model where the different substrate, *i.e.* oxide instead of silicon, requires adaptation.

2.2.3.1 GaN Schottky diodes

A schematic cross-section of the GaN Schottky diode is shown in Figure 16. The material layers on top of the substrate are the main GaN layer and an AlGaN layer. A thin layer of electrons, *i.e.* a two-dimensional electron gas (2DEG), is formed at the AlGaN-GaN hetero-junction, *i.e.* the interface between the AlGaN and GaN layers. The anode makes a Schottky contact to the 2DEG layer, whereas the cathode contact of the diode is made by a metal with an Ohmic contact to the 2DEG layer.

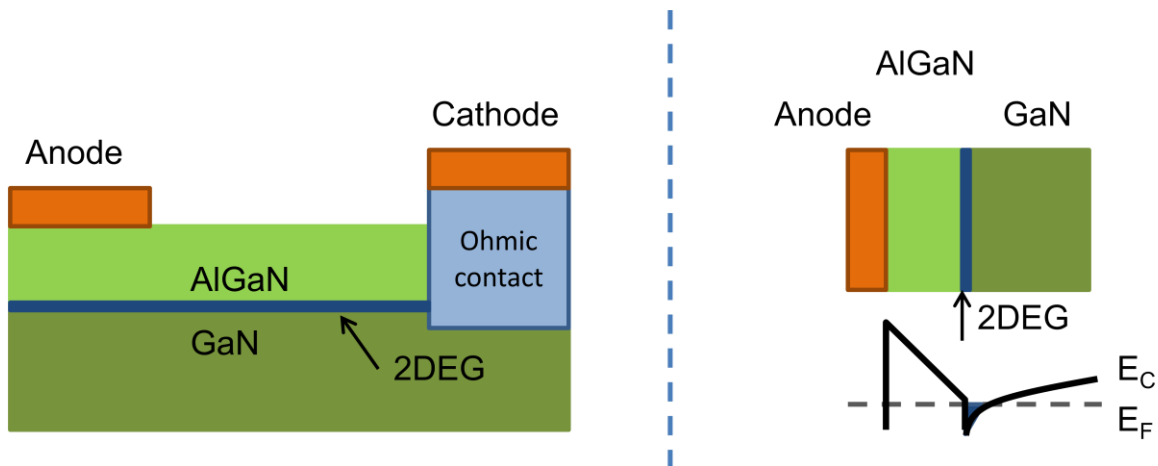


Figure 16 Schematic cross-section of the GaN Schottky diode (left), and schematic band diagram (right), showing the Fermi level (E_F) and the conduction-band minimum (E_C) at equilibrium.

In order to characterize the GaN Schottky diode, the S-parameter characterization technique (as described as part of Therminator deliverable D1.1.1) is used. The S-parameter technique allows one to determine the thermal resistance directly from measurements. The measurement results are compared to the developed electro-thermal compact model for the Schottky diodes. The model parameters have been extracted on the measurements of the smallest device only. The physical scaling rules have been used to compute the thermal resistances for the larger devices with more devices in parallel, different finger length, and variations in device separation (pitch).

The thermal resistance of the Schottky diode as measured with the S-parameter characterization technique is compared to the developed Schottky model in Figure 17. The thermal resistance was extracted under forward operation of the diode. Measurements and

model were found to be in good agreement over the measured temperature range from 20 °C to 90 °C.

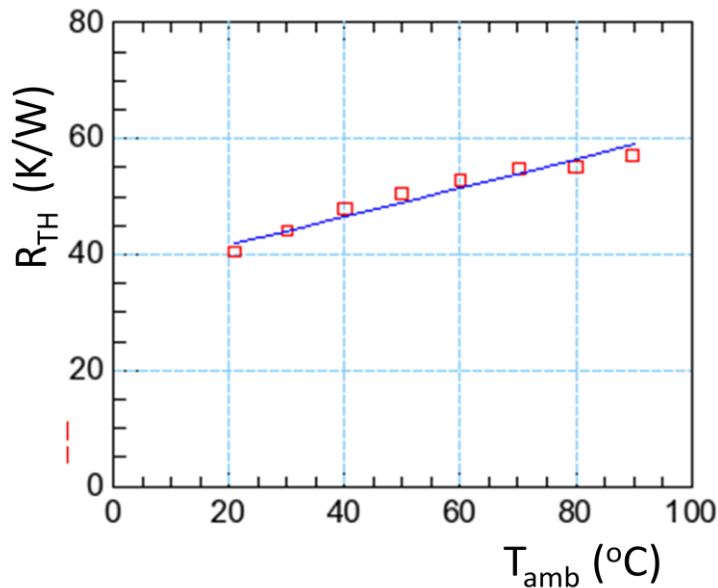


Figure 17 Thermal resistance R_{TH} versus ambient temperature T_{amb} , comparing direct characterization of the thermal resistance using S-parameters (red rectangles) to the Schottky diode model (blue line).

The thermal resistance as a function of finger length **FL** is shown in Figure 18. In the compact thermal model derived for GaN-HEMT in deliverable D2.2.3 of Therminator WP2, and now reused for the GaN Schottky diodes, thermal effects at the edges of the fingers were assumed to be small enough to be neglected. From symmetry it follows that the resulting thermal resistance has to be inversely proportional to the finger length **FL**. The measurements, as shown in Figure 18, demonstrate this dependence.

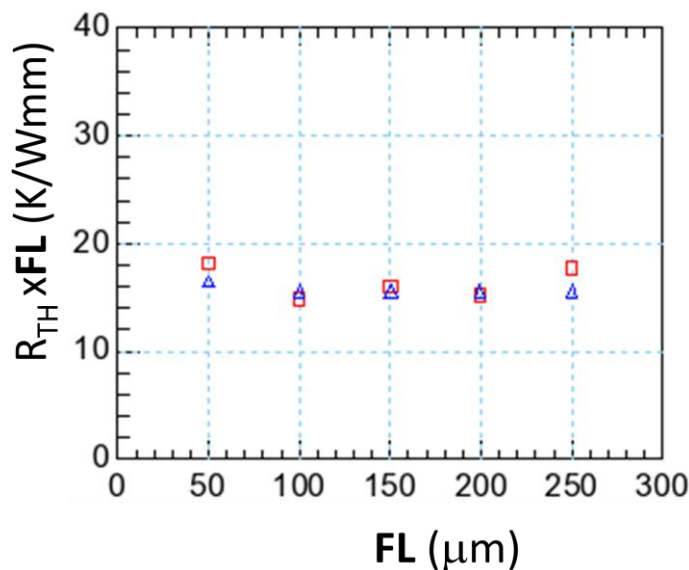


Figure 18 Thermal resistance times finger length ($R_{TH} \times \mathbf{FL}$) versus the finger length (**FL**), comparing direct characterization using S-parameters (red rectangles) to our Schottky diode model (blue triangles). The measurements demonstrate that the thermal resistance of the

Schottky diodes is inversely proportional to the finger length, which demonstrates that the impact of thermal effects at the ends of the fingers is marginal.

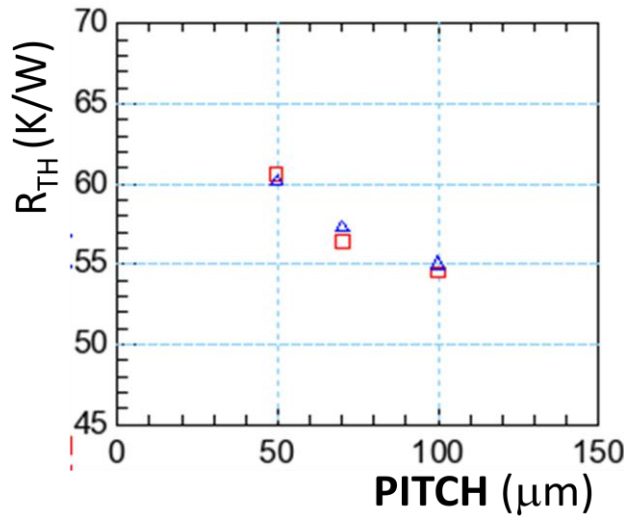


Figure 19 Thermal resistance R_{TH} versus PITCH, comparing measurements obtained with the S-parameter technique (red rectangles) to our Schottky diode model (blue triangles). The thermal resistance decreases for larger pitches due to less mutual heating between devices. Model parameters have been extracted only on a small reference device (not shown). The physical scaling equations have been used to compute the thermal resistances for the larger devices.

In Figure 19, the measured and modelled thermal resistance as a function of pitch is shown. For a larger pitch, the thermal resistance decreases because there is less mutual heating between devices in the array of Schottky diodes. The measured and modelled thermal resistance as a function of the number of Schottky diodes in an array is shown in Figure 20. The characterization with the S-parameter technique gives a thermal resistance decreasing with the number of devices or cells. However, the measured thermal resistance was not found to be inversely dependent on the number of cells, due to mutual heating. The compact thermal model gives an accurate description of the mutual heating of Schottky diodes.

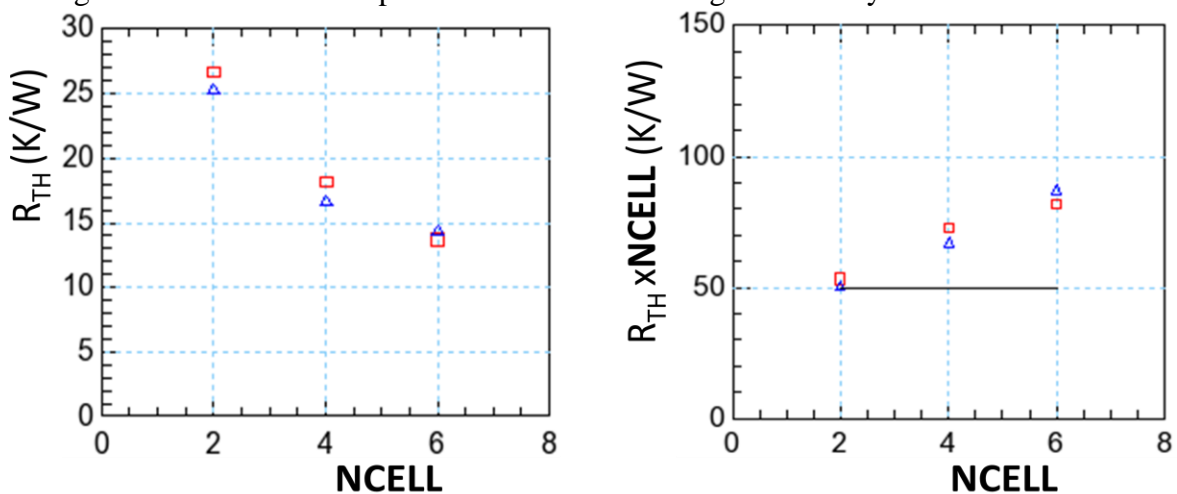


Figure 20 The thermal resistance R_{TH} versus the number of cells NCELL, comparing direct characterization of R_{TH} using S-parameters (red rectangles) to our Schottky diode model (blue triangles), is shown in the figure on the left. The parameters have been extracted directly on a small reference device, and then the

physical scaling equations have been used in order to obtain the thermal parameters for the other devices. In the figure on the right, the same thermal resistance data has been scaled with **NCELL**. In the absence of mutual heating between cells, this scaled thermal resistance should be constant, as shown by the solid black line. However, the scaled thermal resistance obtained from direct characterization (red rectangles) is not constant due to mutual heating. The derived compact thermal model with mutual heating and its physical scaling (blue triangles) is in good agreement with the measurements.

Finally, the developed electro-thermal GaN Schottky diode model is validated on IV measurements. In Figure 21, measurements of the forward diode IV characteristics are compared on a logarithmic scale.

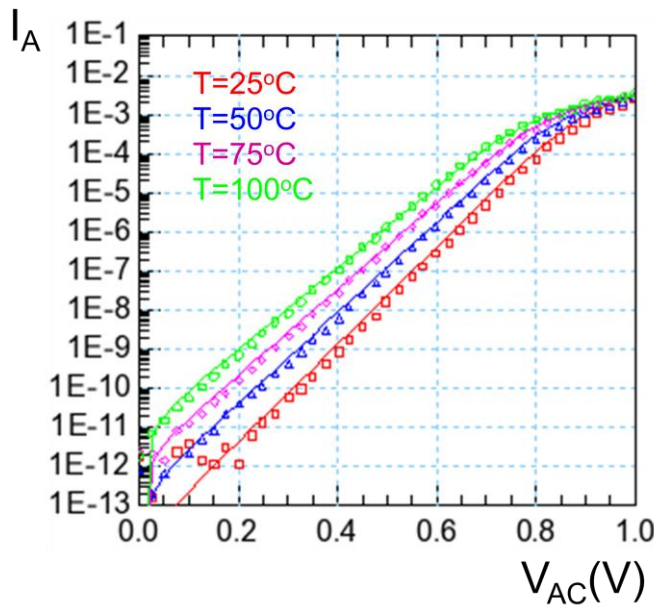


Figure 21 Validation of the developed GaN Schottky diode model on forward diode IV characteristics for temperatures in the range of $T = 25\text{ }^{\circ}\text{C}$ to $T = 100\text{ }^{\circ}\text{C}$. Measurements (markers) are in good agreement with the model (solid lines).

Pulsed and DC IV characteristics as a function of temperature are shown in Figure 22. The pulsed measurements were taken with a pulse width of $0.5\text{ }\mu\text{s}$. By variation of the pulse width, it was confirmed that no self-heating effects are present in the pulsed measurements. The developed GaN Schottky diode model gives a good description of the temperature dependence in the pulsed measurements, and the self-heating in the DC IV characteristics.

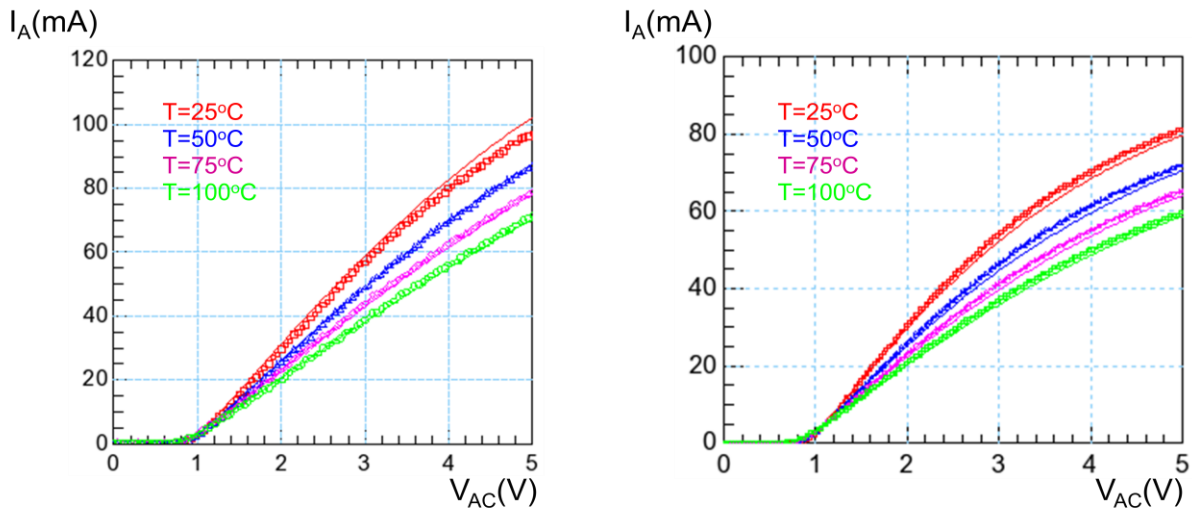


Figure 22 Validation of the developed GaN Schottky diode model on pulsed IV measurements in the figure on the left, and DC IV measurements in the figure on the right. Measurements (markers) are in good agreement with the model for measured temperatures in the range of $T = 25\text{ }^{\circ}\text{C}$ to $T = 100\text{ }^{\circ}\text{C}$.

Figure 23 shows a detail of the forward Schottky diode IV characteristics with a temperature inversion point. The temperature inversion point exists because at low forward voltages V_{AC} the current increases with temperature, as shown in Figure 21, whereas at higher forward voltages V_{AC} the current decreases with temperature. At lower forward voltages, the current increases with temperature because of the diode characteristics ($I \sim \exp(V_{AC}/(k_B \cdot T))$). The decrease of current at higher forward voltages occurs because the series resistance of the 2DEG increases with temperature.

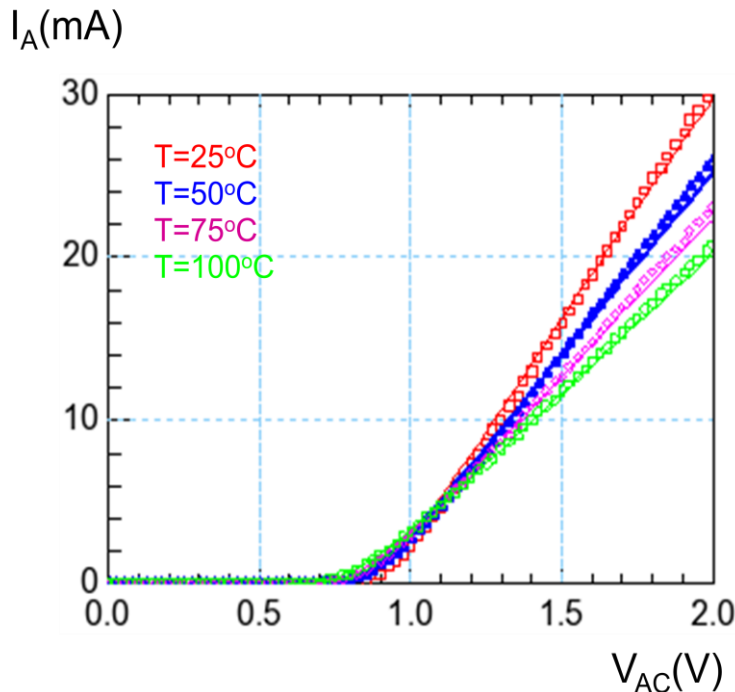


Figure 23 Detail of the forward Schottky diode IV characteristics. The measurements show a temperature inversion point around a forward voltage $V_{AC} = 1.1\text{ V}$. The temperature inversion is the result of diode IV characteristics, which increase with temperature at low forward voltages (see also Figure 21), and decrease with temperature due to an increasing series

resistance. The temperature inversion effect in the measured IV characteristics (markers) is described accurately by our GaN Schottky diode model.

The overall accuracy of the GaN Schottky diode model, as shown in Figure 17–Figure 23, was found to be within 15%.

2.2.3.2 SOI-LDMOS

A schematic cross-section of the SOI-LDMOS transistor is shown in Figure 24. Similar to the RF-LDMOS transistor, which is also shown schematically in Figure 24, the SOI-LDMOS transistor comprises a channel region in combination with a drift region, or drain extension. The purpose of the drift region is to protect the channel region from high voltages. The important difference between the SOI-LDMOS and RF-LDMOS transistors for thermal behaviour is the substrate.

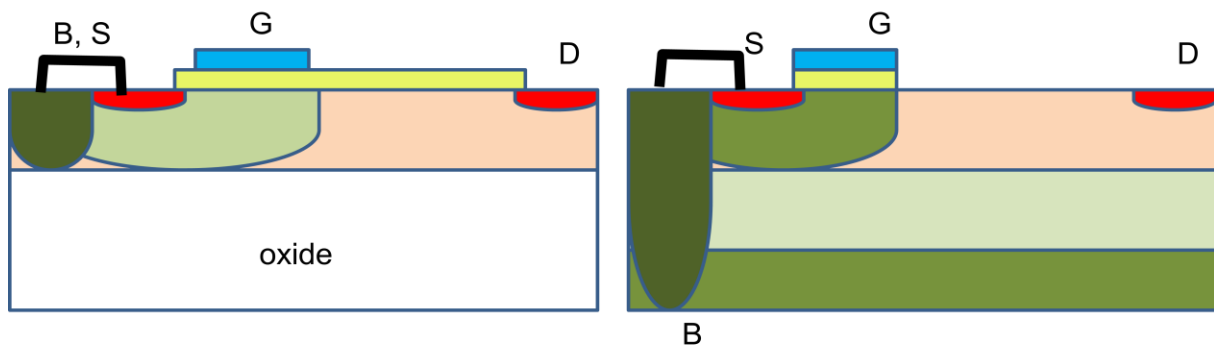


Figure 24 Schematic cross-sections of the SOI-LDMOS transistor (figure on the left) and the RF-LDMOS transistor (figure on the right).

In the case of the SOI-LDMOS transistor, a substrate consisting of an oxide layer is used. The thermal conductivity of the silicon oxide is much smaller than that of silicon. For this reason, the SOI-LDMOS device will exhibit more self-heating. The advantages of the oxide layer in the substrate of the SOI-LDMOS device are electrical isolation and improved vertical breakdown. Comparing the thermal conductivity of the silicon oxide of 1.4 W/(K·m) to the thermal conductivity of silicon of 150 W/(K·m) shows that the thermal conductivity of silicon oxide is much smaller. In the SOI-LDMOS transistor, heat flow to the edges of the device becomes important and needs to be included in the thermal model. For this reason, the thermal model as used for the RF-LDMOS model has been modified. The overall results, in which the electro-thermal SOI-LDMOS model is compared to corresponding measurements, are shown in Figure 25 and Figure 26. Figure 25 shows the measured pulsed and DC $I_D V_{DS}$ characteristics of the SOI-LDMOS device, measured at three temperatures ($T = 21, 60,$ and $100\text{ }^\circ\text{C}$). The pulsed $I_D V_{DS}$ characteristics have been measured with a pulse width of $0.5\text{ }\mu\text{s}$. It was checked experimentally (by varying the pulse width) that, for the used pulse width of $0.5\text{ }\mu\text{s}$, self-heating can be excluded. The reduction in current in the pulsed $I_D V_{DS}$ characteristics as a function of increasing temperature (left column of Figure 25) can be attributed to the temperature dependence of the transistor parameters, *e.g.* the mobility in the channel region and the on-resistance of the drift region. Comparison of the measured to the simulated pulsed $I_D V_{DS}$ characteristics demonstrates that the transistor parameters have the correct temperature dependence. The impact of self-heating in the SOI-LDMOS device becomes clear by comparing the pulsed to DC $I_D V_{DS}$ characteristics at each temperature in Figure 25. Comparison of the measured and simulated DC $I_D V_{DS}$ characteristics in the right column of Figure 25 demonstrates that the model also accurately describes the self-heating in the transistor over the measured temperature range. The corresponding $I_D V_{GS}$ transfer

characteristics are shown in Figure 26. The accuracy of the electro-thermal SOI-LDMOS model, shown in Figure 25 and Figure 26, was found to be within 15%.

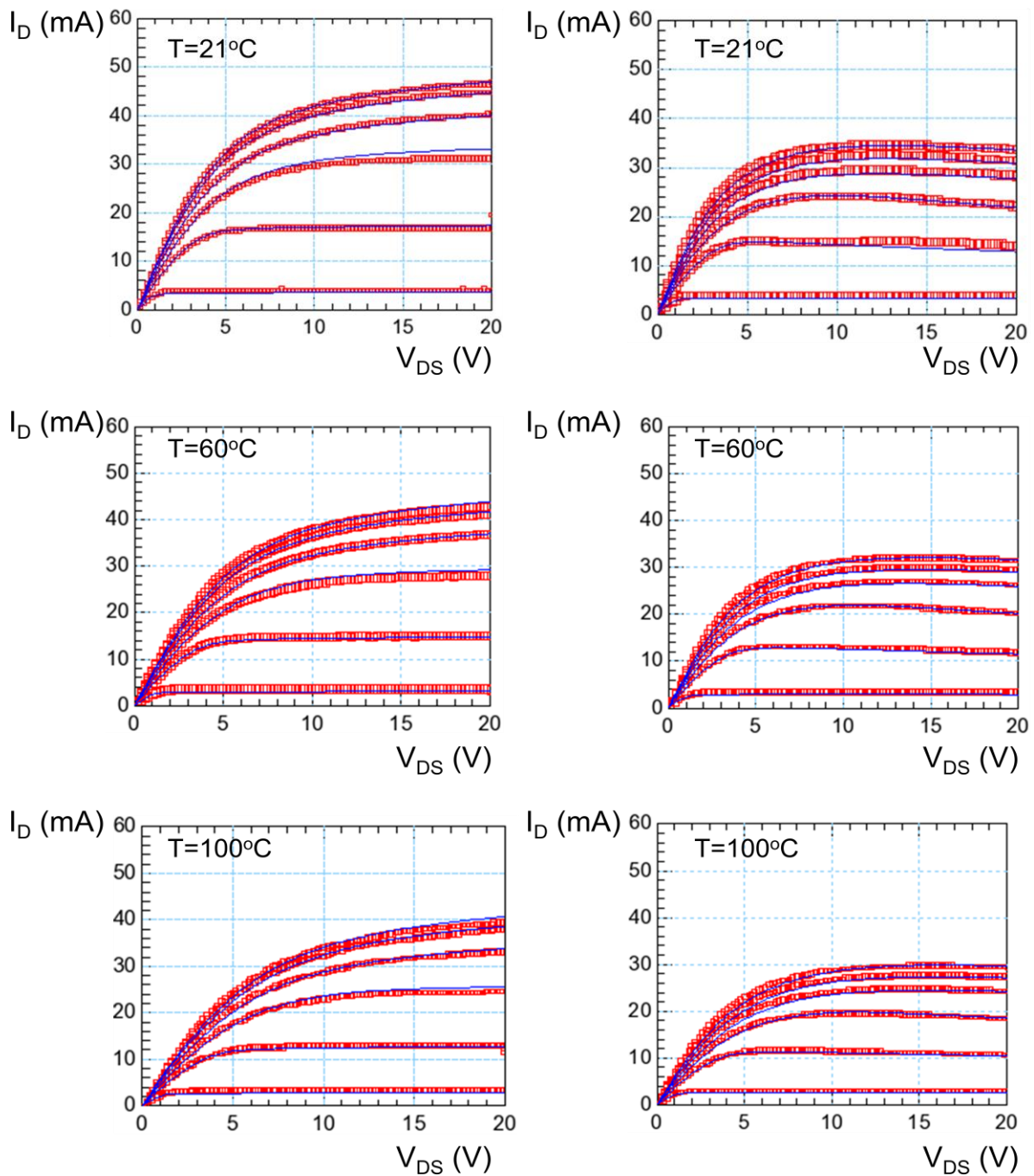


Figure 25 $I_D V_{DS}$ characteristics of the SOI-LDMOS device measured at temperatures of $T = 21, 60,$ and $100\text{ }^\circ\text{C}$. The figures in the left column show the pulsed IV characteristics, using a pulse width of $0.5\text{ }\mu\text{s}$. The figures in the right column show the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (solid blue lines) are in good agreement for the measured bias conditions and temperature range.

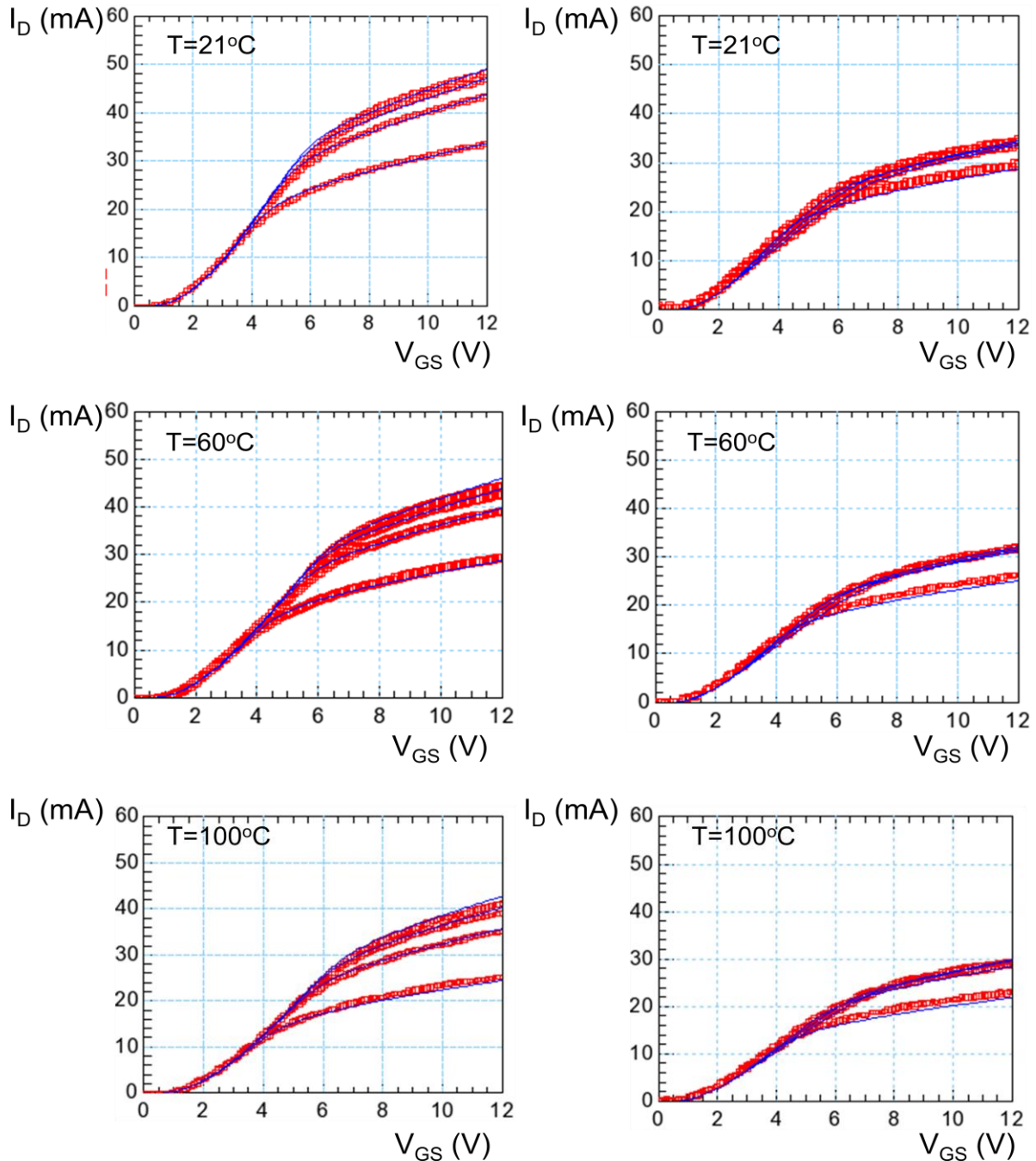


Figure 26 I_D V_{GS} transfer characteristics of the SOI-LDMOS device measured at temperatures of $T = 21, 60,$ and $100\text{ }^\circ\text{C}$. The figures in the left column show the pulsed IV characteristics, using a pulse width of $0.5\ \mu\text{s}$. The figures in the right column show the DC IV characteristics. The scaling of the y-axis has been kept the same in all figures in order to demonstrate the impact of the ambient temperature and self-heating on the device characteristics. The measurements (red markers) and developed model (solid blue lines) are in good agreement for the measured bias conditions and temperature range.

In conclusion, we have shown that (i) the scalable electro-thermal model developed for the GaN-HEMT can be reused for GaN Schottky diodes by using the same scalable thermal model of deliverable D2.2.1 and replacing the device models, and (ii) good modelling results are obtained for SOI-LDMOS by adapting the thermal model for the substrate. These results

demonstrate our measurable objective MO7.1.2 of reuse by adapting electro-thermal models developed on RF power technologies for other types of devices.

2.3 Conclusions

Compact electro-thermal models for silicon RF-LDMOS and GaN-HEMT devices have been developed in WP2 of Therminator (deliverable D2.2.1 and D2.2.3). These models derived in WP2 are physics-based and have a scalable model for the thermal resistance. In this deliverable, these models have been validated using measurements and numerical calculations. The validation against measurement data has demonstrated that the compact models give an accurate description of the pulsed and DC IV characteristics over a wide temperature range for both silicon RF-LDMOS and GaN-HEMT. In addition, the models have been shown to be in good agreement with large-signal application measurements. Next, the thermal compact model has been compared to numerical calculations using a Green's function approach. This comparison has resulted in validation of the approximations made in the derivation of the compact thermal model in WP2, as well as validation of the compact thermal model over a wide range of geometries.

Furthermore, the developed models have been validated on different device types, *i.e.* larger geometries as used in WP2 for RF-LDMOS and other device types. The other device types are SOI-LDMOS and GaN Schottky diodes. The S-parameter method for determining the thermal resistance has been used to characterize the thermal device properties. By making the appropriate changes in the device or thermal models in the models for the RF-power devices developed in WP2, accurate modelling of the SOI-LDMOS and GaN Schottky diodes was demonstrated.

In conclusion, the measurable objective MO7.1.1 of validation of the thermal RF-LDMOS and GaN-HEMT models has been demonstrated in Section 2.2.1 (

Figure 2–Figure 5). The measurable objective MO7.1.2 of reusing and adapting the electro-thermal models developed for RF-devices on other device types has been shown in Section 2.2.3 (Figure 17–Figure 23 and Figure 25–Figure 26), and the integration of the RF-LDMOS model into design tools and validation on large-signal application data (MO7.1.3) was demonstrated in Section 2.2.1 (Figure 7–Figure 9).

3 Verification of TCAD (SNPS-CH, together with IMC, IMEC, ST, NXP-D)

3.1 Introduction

This section reports about the verification of Technology CAD (TCAD) calibrated simulation decks that were developed in WP2 and WP6 by SNPS-CH with and for supporting different partners for studying thermal effects at the very low end of the abstraction hierarchy. The model details are described in the respective WP2 and WP6 deliverable reports.

TCAD simulation includes is the modelling of process steps (such as diffusion and ion implantation), and modelling of the electro-thermal behaviour of the devices based on fundamental physics, such as the doping profiles of the devices.

TCAD enables in-depth analysis of device behaviour, i.e. self-heating, that is relevant to modelling at higher levels of abstraction by running virtual experiments, and allows separation of physical effects that would not be possible with measurements only.

3.2 Verification of TCAD Models and Methodologies

3.2.1 Bulk CMOS 3D TCAD Model

We report about the verification of a 3D TCAD model (Figure 27) for advanced (28/32nm) bulk CMOS technology developed in WP2 and described in detail in D2.1.5. The model was developed with partner IMC technology and measurement / compact model data.

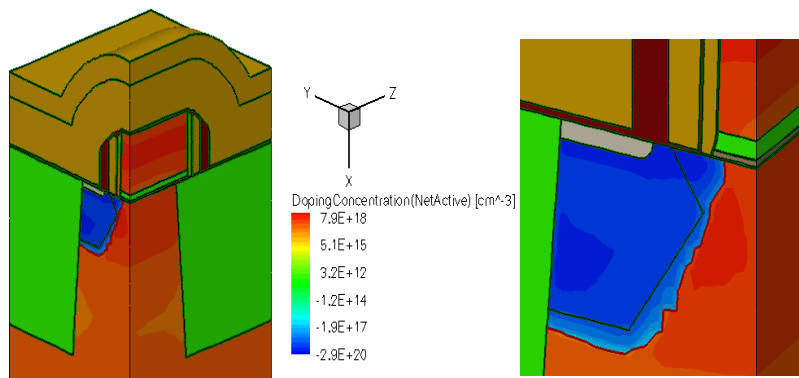


Figure 27: Snapshot showing a 3D pMOS transistor. A zoom on the SiGe pockets of the device is shown in the right picture.

The measurable objective MO7.1.5:

Calibration against available experimental / compact model data within 20% for saturation regime threshold voltages and saturation on-currents, and to obtain the right trends with regard to temperature variation.

was fully achieved for NMOS (10%), whereas for PMOS the accuracy achieved was V_{tsat} within 30%, I_{on} within 35%. However, for both NMOS and PMOS cases the V_{tsat} temperature trend ($\Delta V_{tsat}/\Delta T$) is captured with an accuracy of better than 20%. In order to improve the PMOS absolute accuracy, more detailed process flow and geometry description need to be available. However, because of IMCs data and IP protection requirements neither device geometry information nor process flow description was available for this implementation.

This is shown in Figure 28 and Figure 29 for the saturation on-currents, and in Figure 30 for the saturation regime threshold voltage V_{tsat} .

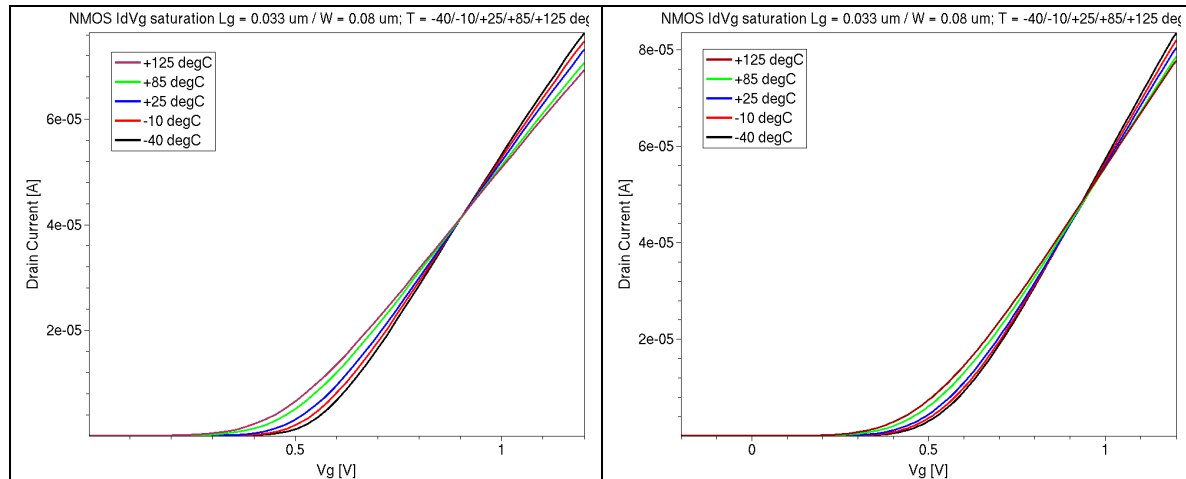


Figure 28: Comparison of the nMOS I_{dVg} in saturation regime of the 3D TCAD model (left) with the data extracted from the compact model provided by IMC (right). The device geometry is $L/W=33nm/80nm$. The saturation on-currents agree within 10% over the temperature range from $-40deg.C$ up to $125deg.C$.

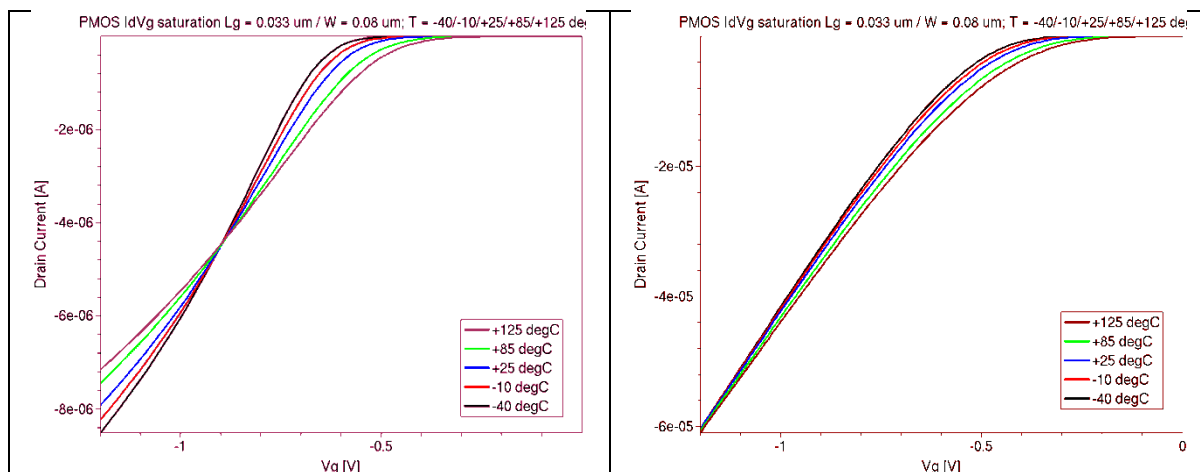


Figure 29: Comparison of the pMOS I_{dVg} in saturation regime of the 3D TCAD model (left) with the data extracted from the compact model provided by IMC (right). The device geometry is $L/W=33nm/80nm$. The saturation on-currents agree only within 35% over the temperature range from $-40deg.C$ up to $125deg.C$. In particular, the crossing point at $V_g = -1.2V$ is not well captured in the TCAD model.

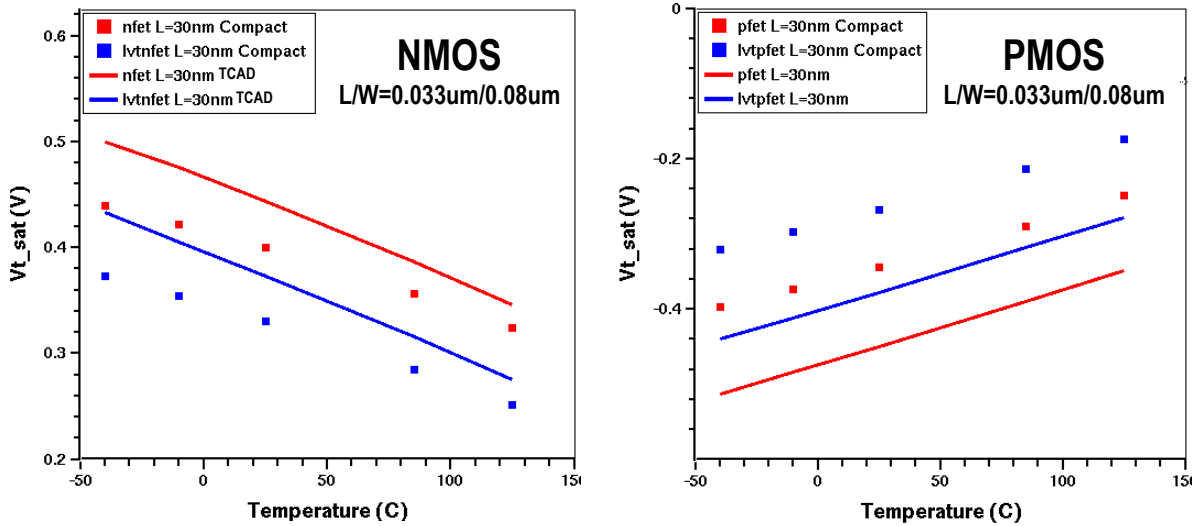


Figure 30: Saturation regime threshold voltage V_{tsat} temperature dependence of 3D TCAD model (solid lines) compared to data extracted from compact model provided by IMC (squares). The trends (dV_{t_sat}/dT) are correctly captured with an accuracy of $<20\%$ for both nMOS and pMOS cases, but in case of pMOS the absolute accuracy target of 20% was not achieved. Comparison for both regular (nfet, pfet) and low voltage (lvnfet, lvtpfet) devices is shown.

3.2.2 GaN HEMT TCAD Model / Compact Model Parameter Extraction

We report about the verification of our calibrated TCAD model (Figure 31) and TCAD-based compact model parameter extraction methodology for discrete GaN HEMTs developed in WP2 and described in detail in D2.2.2, and about the comparison with measurement-based extraction done by IMEC. The GaN HEMT compact model itself (Figure 32) was developed by IMEC.

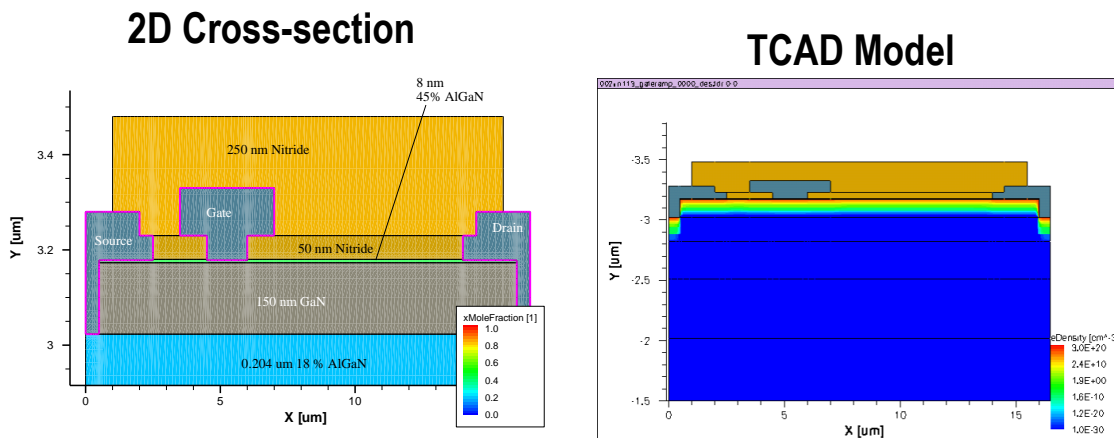


Figure 31: 2D cross section sketch (right) and 2D TCAD model (left) of the GaN HEMT showing the electron density in on-state.

The measurable objective:

Model matches device data (error within 10%) for the maximum drain current in I_dV_d characteristics at different gate bias, and for drain current at max. drain bias, and for R_{out} at drain bias zero.

was achieved (Figure 33).

The compact model parameters extracted by IMEC give a very good agreement to measurement data. For the TCAD based extraction simulations with non-calibrated parameters are done to make the difference to the measured data larger. IMEC’s parameters are taken as initial compact model parameters. After parameter extraction the compact model results based on the extraction of parameters done with TCAD match the TCAD simulation results.

GaN HEMT Compact Model (IMEC)

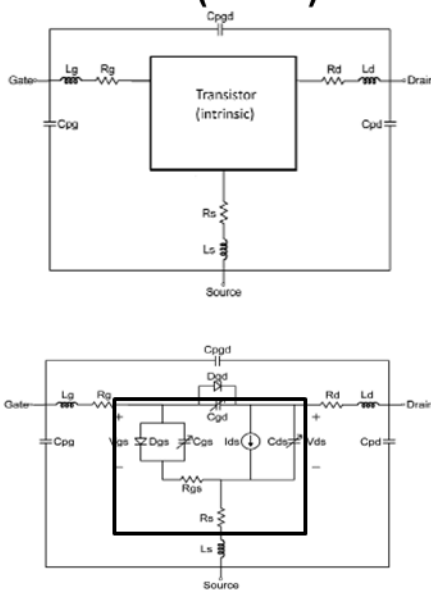


Figure 32: GaN HEMT compact model provided by IMEC. Details are described in D5.1.1b.

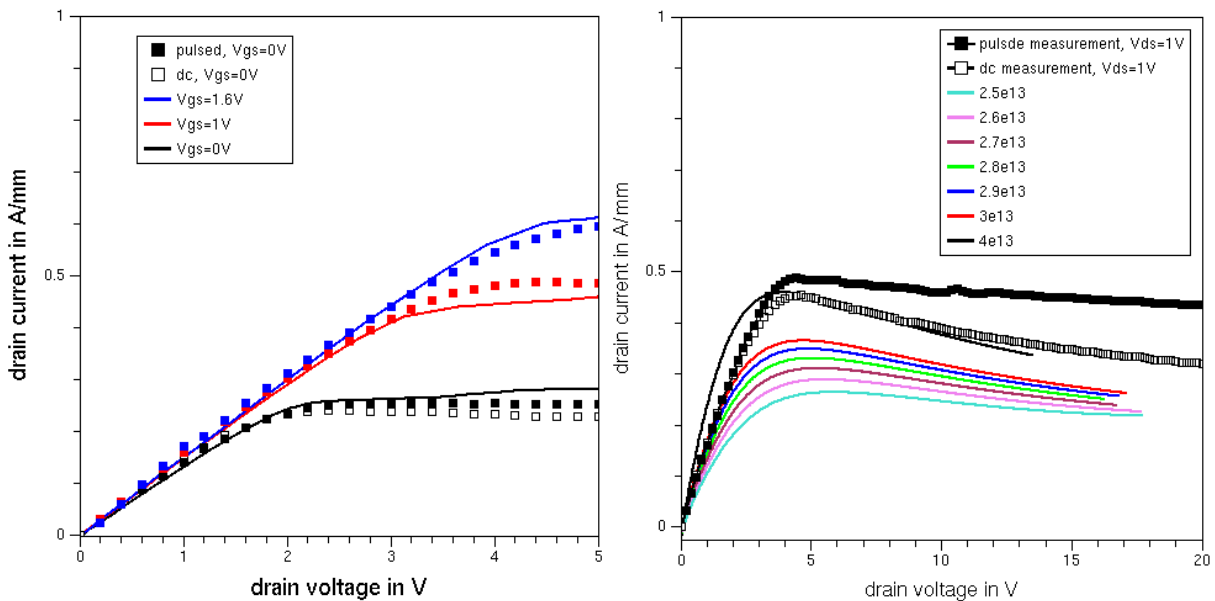


Figure 33: TCAD model IdVd simulation results compared to measurement data provided by IMEC. The figure on the right shows the effect of self-heating (negative differential resistance) for $V_{gs}=1V$, and the effect of different AlGaIn/GaN interface trap densities. Solid lines = TCAD, Symbols = measurement.

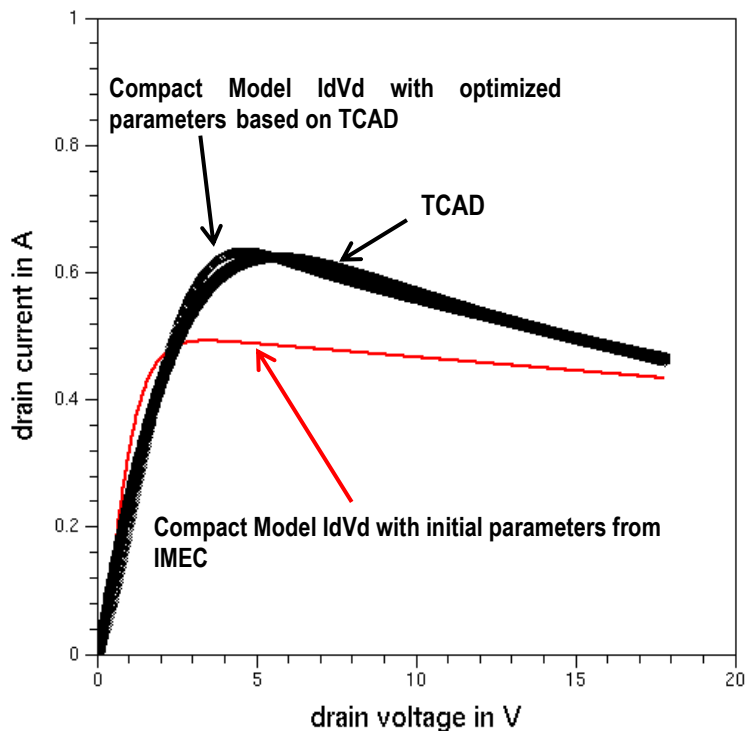


Figure 34: IdVd characteristics comparison. $V_{gs}=1.6V$.

3.2.3 Si power MOSFET unit cell TCAD Model

We report about the discrete power MOSFET TCAD unit cell model verification. The model was developed in WP2 with partner ST and its details are presented in D2.2.2.

The measurable objective MO7.1.4:

Model matches device data (error within 10%) for the maximum drain current in IdVd characteristics at different gate bias, and for drain current at max. drain bias, and for Rout at drain bias zero.

was essentially achieved.

Rout matches the reference data from ST mostly within an error < 10% in IdVd characteristics at different gate bias and temperatures (Figure 35). Only at $V_{gs}=10V$ and at the low temperatures boundary we were not able to meet the objective (<15%). In accordance

with partner ST we preferred to preserve predictability and consistency over the Vgs and temperature range, rather than do a “brute force” fitting to measurements. The maximum drain current (Ids) objective was not applied to the power MOSFET TCAD model. The bias conditions for Ids@Vds=20V would correspond to an operating point well beyond static (and dynamic) safe operating area (SOA) for all Vgs>3V.

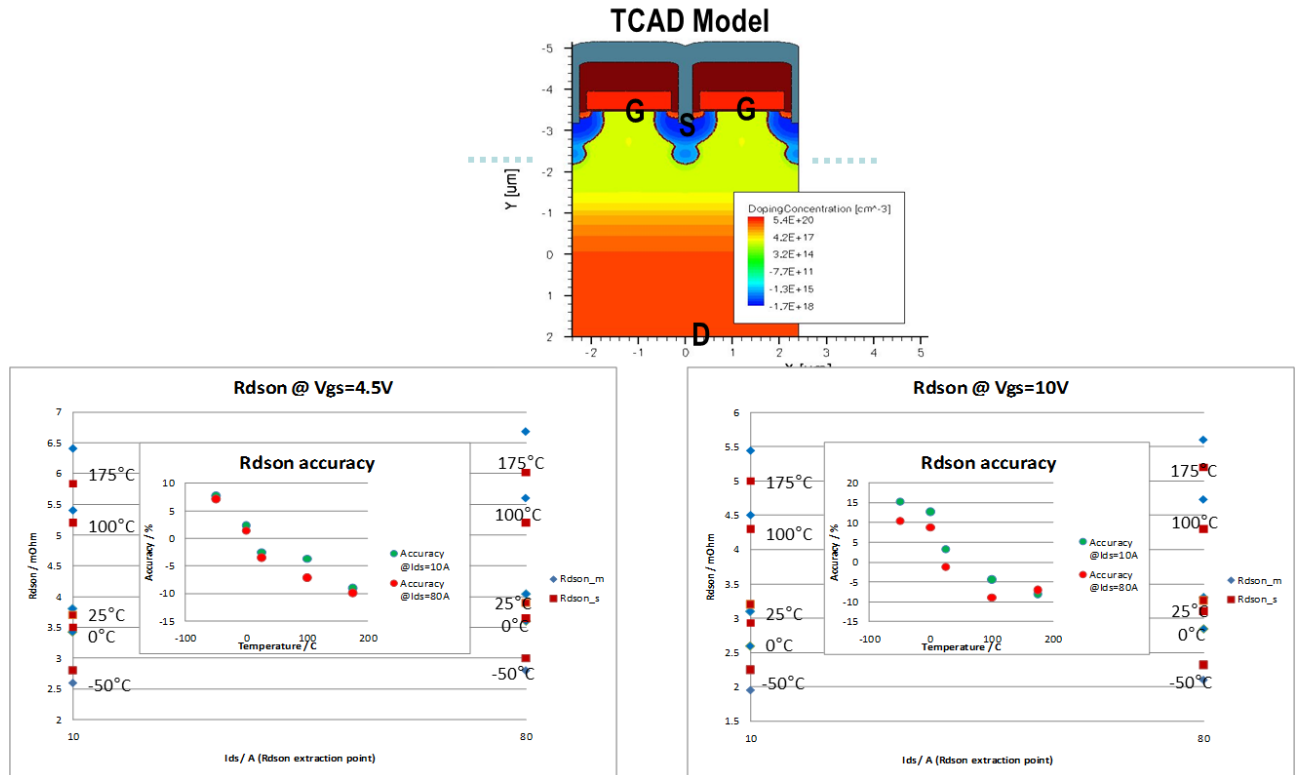


Figure 35 Top: 2D TCAD model of the power MOSFET unit cell.

Bottom: Measured (_m) vs. Simulated (_s) Rdson at two different Ids current values (Ids=10A, 80A) for Vgs=4.5V (left) and Vgs=10V (right), and temperatures -50C, 0C, 25C, 100C, 175C. Rdson (Rout) increases with temperature. The Inset shows the accuracy of TCAD with respect to measurement.

3.2.4 3D TCAD Electro-Thermal Modeling Methodology

We report about the verification of the electro-thermal 3D TCAD Modeling Methodology for discrete devices developed in WP6 with partner NXP-D. The model details are presented in the deliverable report D6.1.1. The verification is performed against NXP test chip (

Figure 36) measurement data. We are focusing on the bipolar structure on the test chip (encircled red). The aim of the test structure is the monitoring of the silicon temperature by using sense diodes (“horizontal”: h1,h2,h3,h4 and “vertical”: v1,v2,v3,v4). The heat source is a transistor. The TCAD model details were set as follows in accordance with NXP information about test chip:

- Silicon substrate = 300um
- STI = 0.4 um
- Tungsten via = 0.4 um
- Copper Line = 0.125 um
- Oxide passivation = 1.725 + 5 um

Thermal conductivity:
 Silicon: $1.0/(0.03+1.56e-3xT+1.65e-6xT^2)$
 (=1.55 W.cm-1.K-1 at T=300K)
 Tungsten: 1.73 W.cm-1.K-1
 Copper: 4.0 W.cm-1.K-1
 Oxide: 0.014 W.cm-1.K-1

Heat Capacity:
 Silicon: 1.63 J.cm-3.K-1
 Tungsten: 2.55 J.cm-3.K-1
 Copper: 3.45 J.cm-3.K-1
 Oxide: 1.67 J.cm-3.K-1

Diodes and transistor are based on layout and doping information provided by NXP. Thermal boundary conditions are defined on top, bottom, and sides of the domain.

The measurable objective:

Model matches device data within 10%

was only partly achieved, as shown in

Figure 37, Figure 38, and Figure 39. Possible reasons for the discrepancy reported in Figure 38 and Figure 39 could be on one hand a different temperature extraction method used in the experiment with respect to TCAD that extracts the temperatures at steady-state (temperature of every diode is extracted by comparing the diode's voltage drop against voltage drop simulated with uniform temperature), and on the other hand parasitic effects not taken into account in TCAD. An evidence for the second hypothesis is shown in Figure 13, where simulation data and measurement results are shown in one picture. The measurement data has been shifted by 6 degrees downward. This value has been chosen so that the measurement where no heating was applied has the same temperature as in the simulations. A non-ideal layout, possibly due to the incorporation of a parasitic resistance far away from the heater and the surrounding probing diodes there might cause such an offset. Once subtracted from the measurement data one can see a good agreement of simulation with measurement at high heating power. At lower heating power the slope of the measured curves becomes lower. It seems that in the real test chip this additional effect starts to dominate. This effect becomes smaller at higher heating powers

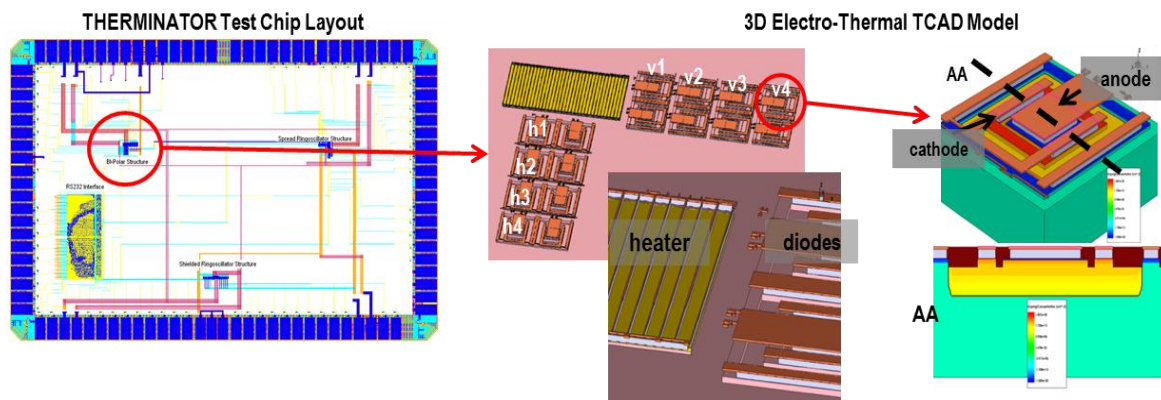


Figure 36: NXP test chip with transistor heater and various sensor elements for temperature sensing purpose (left part). 3D TCAD model of the heater and diode sensor elements (right part).

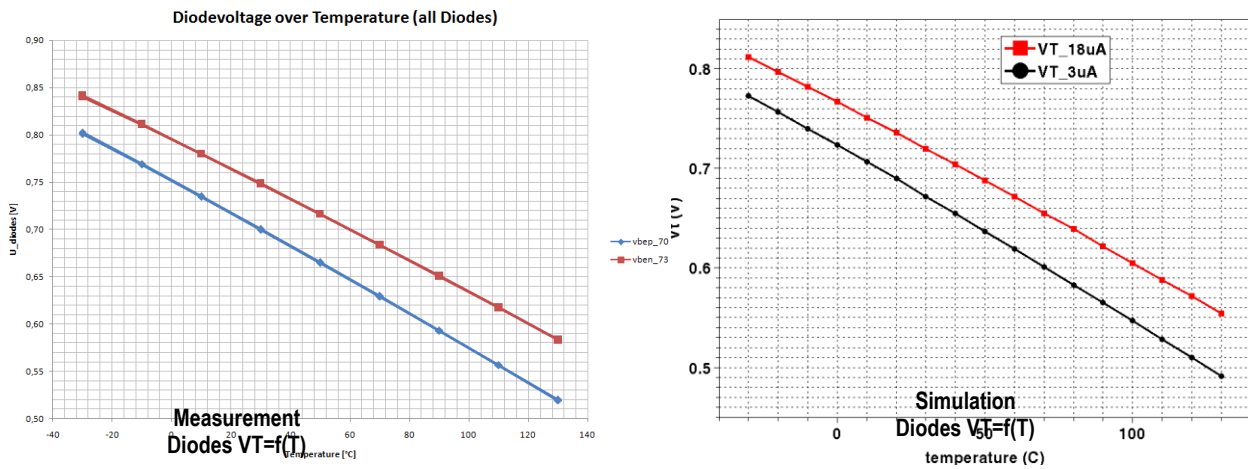


Figure 37: The average diodes voltage as a function of temperature extracted at two different forward current levels (top curve 18uA, bottom curve 3uA). Left: Measurement. Right: TCAD. Accuracy is better than 10%.

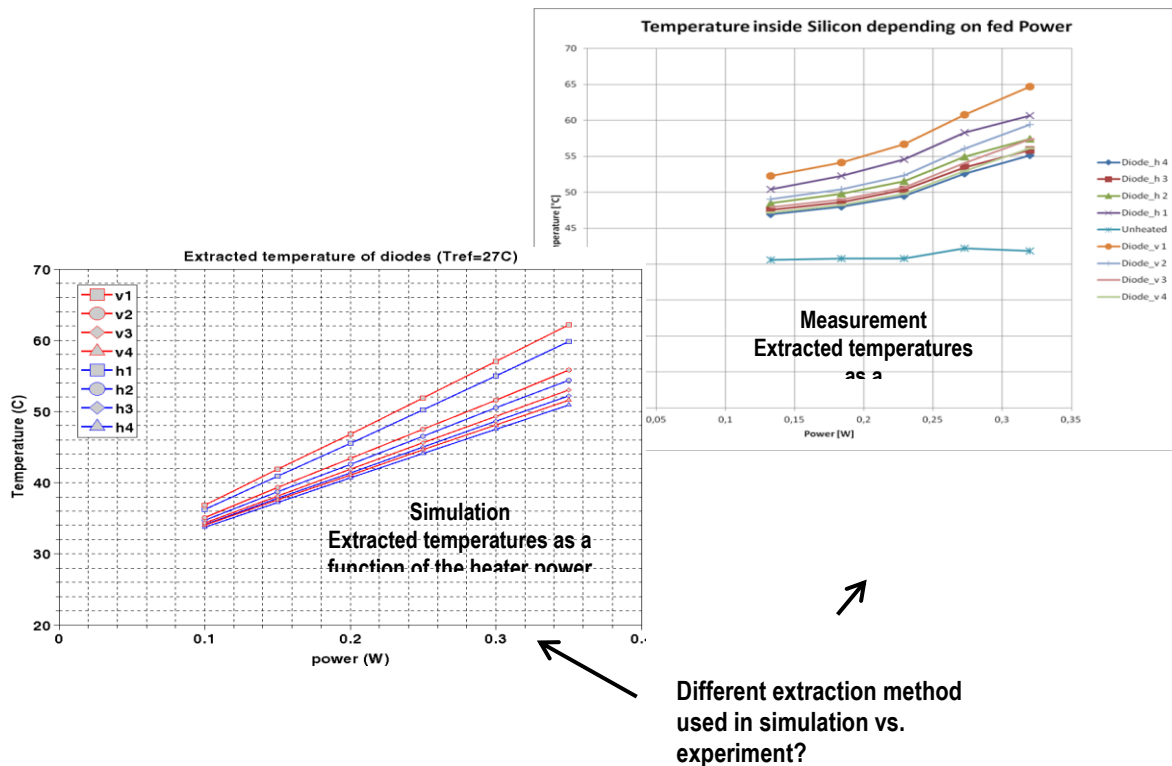


Figure 38: Temperature at different sensor locations (refer to Figure 36) as a function of heater power. Left: TCAD simulation. Right: Measurement performed on test chip. TCAD shows a linear dependency on the power whereas the measurements show a non-linear behaviour that is hard to explain if one considers the linear relationship $V_T=f(T)$ shown in

Figure 37. The discrepancy may be attributed to a different extraction method in TCAD, where extraction at steady-state is performed, vs. experiment. On the other hand, the absolute temperature differences between the various sense diode positions (h1...h4, v1...v4) are correctly reproduced in TCAD.

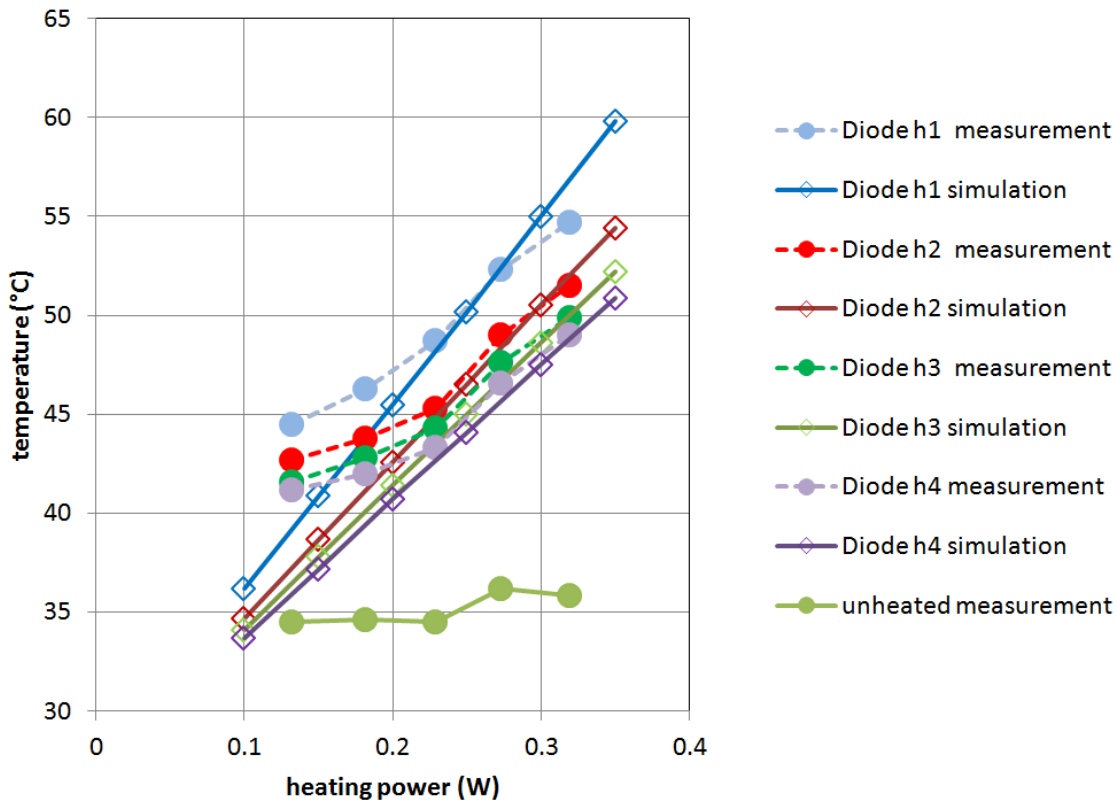


Figure 39: Temperature at different sensor locations (refer to Figure 36) as a function of heater power. The filled circles indicate measurements negatively offset by 6 degrees and the open diamonds are simulation results. One can see that at lower heating powers the measurement data seem to converge to a fixed value. A parasitic effect due to a non-ideal layout could cause this behaviour. At higher heating powers the effect of heater starts to dominate and a good agreement between simulation and measurement can be observed.

3.3 Conclusions

We have reported on the verification of various 2D and 3D electro-thermal TCAD models and modelling methodologies developed in work packages 2 and 6. The defined measurable objectives are essentially met. The cases where the defined objectives were not fully met are described in sections 3.2.1, 3.2.3, and 3.2.4.

4 Modelling and Simulation of discrete components for automotive (ST)

4.1 Introduction

Nowadays electronics play a key role in the automotive sector; several equipments made in the past decades by pure mechanical parts now have been blurred with electronics. Amongst the most critical applications there is the Anti-lock Braking System (ABS) that in recent years, in several countries has become mandatory equipment on all new cars. The main objective of this device is to improve the safety of the vehicle by avoiding car skidding while braking and allows driver to maintain the directional control.

In Figure 40 the scheme of an ABS system with all its main parts is reported.

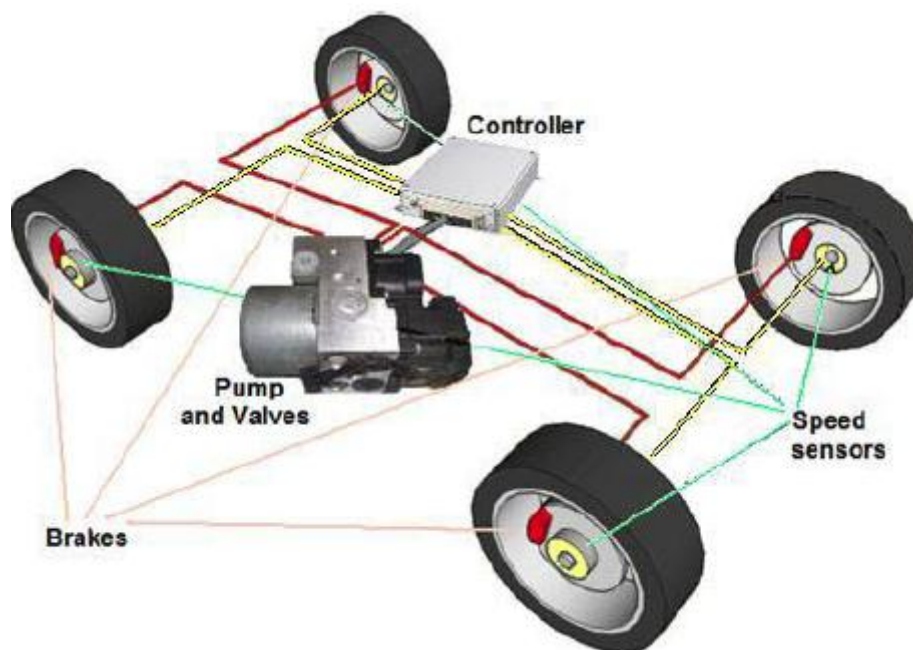


Figure 40 - ABS system basic scheme.

Featured elements are:

- Speed sensors, which allow detecting if any wheel is about to lock up.
- Valves, which allow controlling the fluid pressure in each brake line independently from the strength exerted on the brake pedal.
- Pump, which maintains constant the pressure in the brake system, compensating losses due to valves activation.
- Controller, which acts on the valves on the basis of information provided by speed sensors.

Since the pump represents a critical part of the system which needs to manage significant amounts of energy by adsorbing power peaks up to 1000W, the internal design of its

semiconductor power devices is very critical. The key device is a Power MOSFET expected to perform at least 60 millions of activations during its lifetime.

Once defined the typical working conditions for the device, a fundamental parameter that we will investigate in this context is the temperature variation ΔT inside the silicon junction during a thermal cycle. It has been demonstrated that there is a strong relationship between ΔT and the number of thermal cycle that the device could guarantee in its lifetime [1,2].

Several methods for measuring the thermal variation inside a discrete power device have been described in deliverable 5.1.2 and one of them has been used to retrieve a series of thermal measurements which will be used as reference data for the validation of the thermal simulation framework developed in work package 5. The main objective of this conclusive activity is to prove an error between thermal simulations and thermal measurements below 10% taking as device under investigation the discrete Power MOSFET already described in deliverable 1.1.2.

4.2 Electrical operating conditions

A simplified electrical scheme describing the operating configuration of the Power MOSFET has been reported in Figure 41.

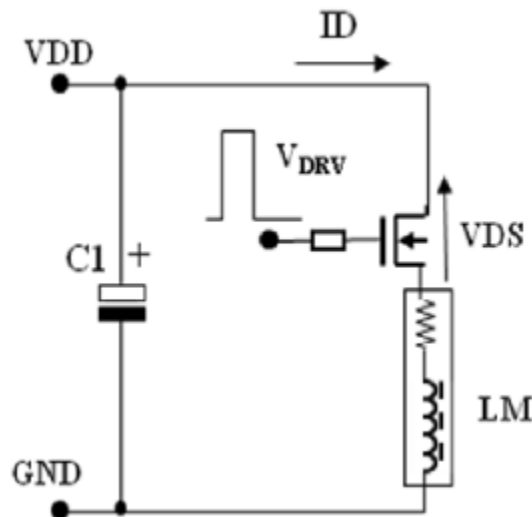


Figure 41– ABS break pump test circuit

Typical electrical waveforms retrieved during a thermal cycle have been shown in Figure 42. As can be deduced from the waveforms reported in the picture, the power MOSFET device that is switching in linear operating condition must dissipate a significant amount of energy. This phenomenon will imply a considerable thermal impact that should be carefully taken into account by designers. V_{gs} profile well shows the behaviour described.

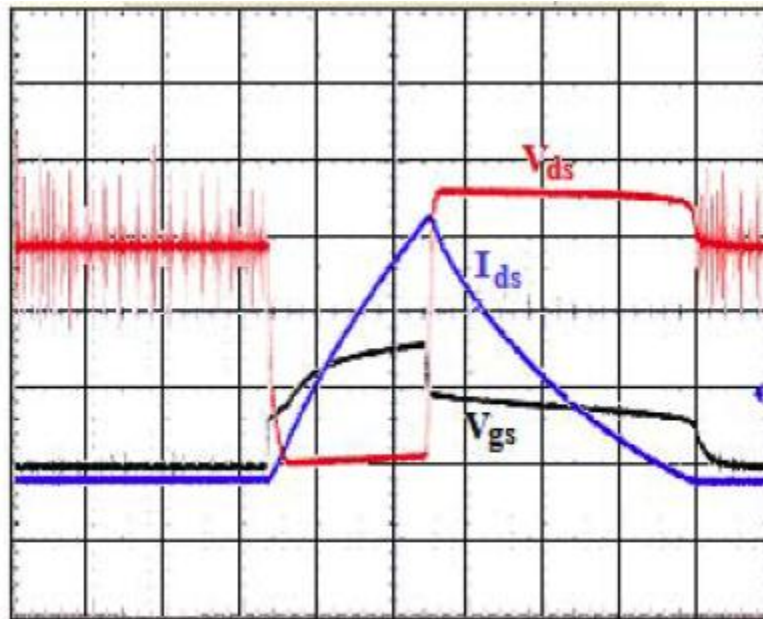


Figure 42 – Voltages and currents measurements during an inductive discharge. V_{gs} (5V/div), V_{ds} (5V/div), and I_{ds} (20A/div), time (400 us/div) during a cycle (down).

4.3 Layout modelling and mapping

The measurement equipment used for retrieving temperature information has already described in deliverable 5.1.2 and is able to acquire thermal maps with a time resolution of 5 μ s, more than enough for the test case under investigation.

An acquisition of the temperature in a cycle under operating conditions described in the previous chapter has been reported in Figure 43 where a current peak of about 82A and a ΔT peak of 53 °C have been recorded.

Starting from the layout data of the device under test described in D1.1.2, by providing the CAD layout to the Matrix Extractor Module (Figure 44) we produced a numerical matrix representing the physical layout composed by three bond wires stitched on the top source metal layer. The matrix, which content has been reported in the Figure 45, is composed by a series of indexes each one related to a physical part of the device (see WP5).

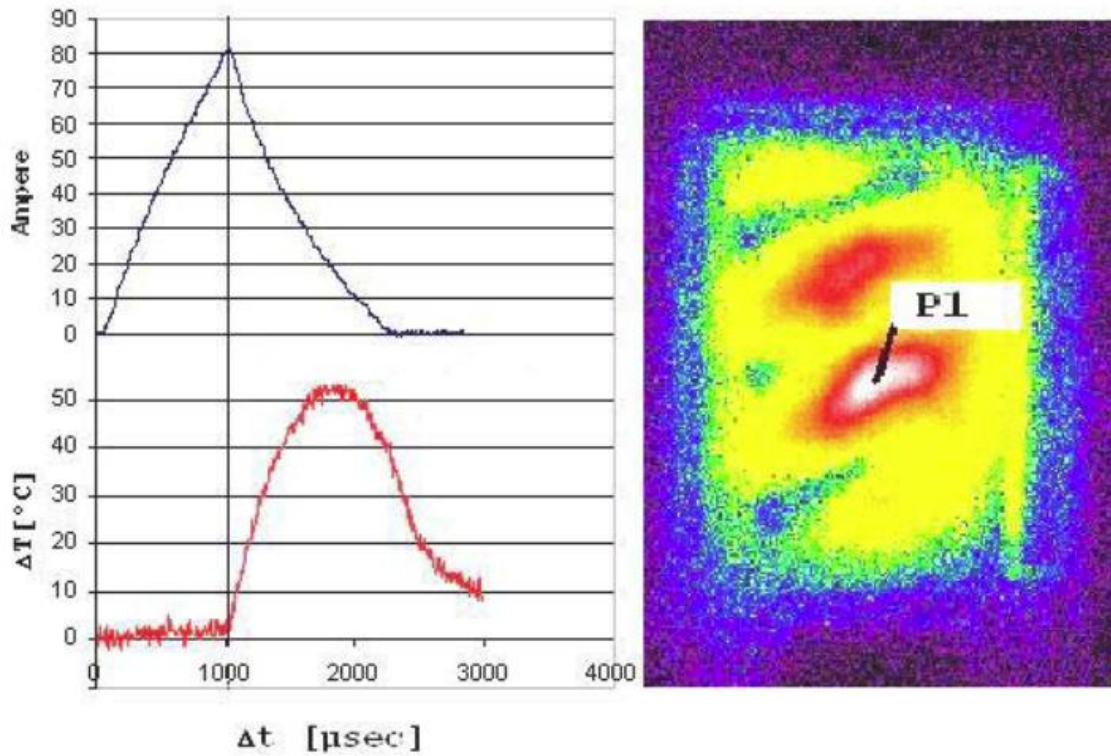


Figure 43- Drain current (up), temperature peak in P1 (down) and thermal map (right) during a thermal cycle.

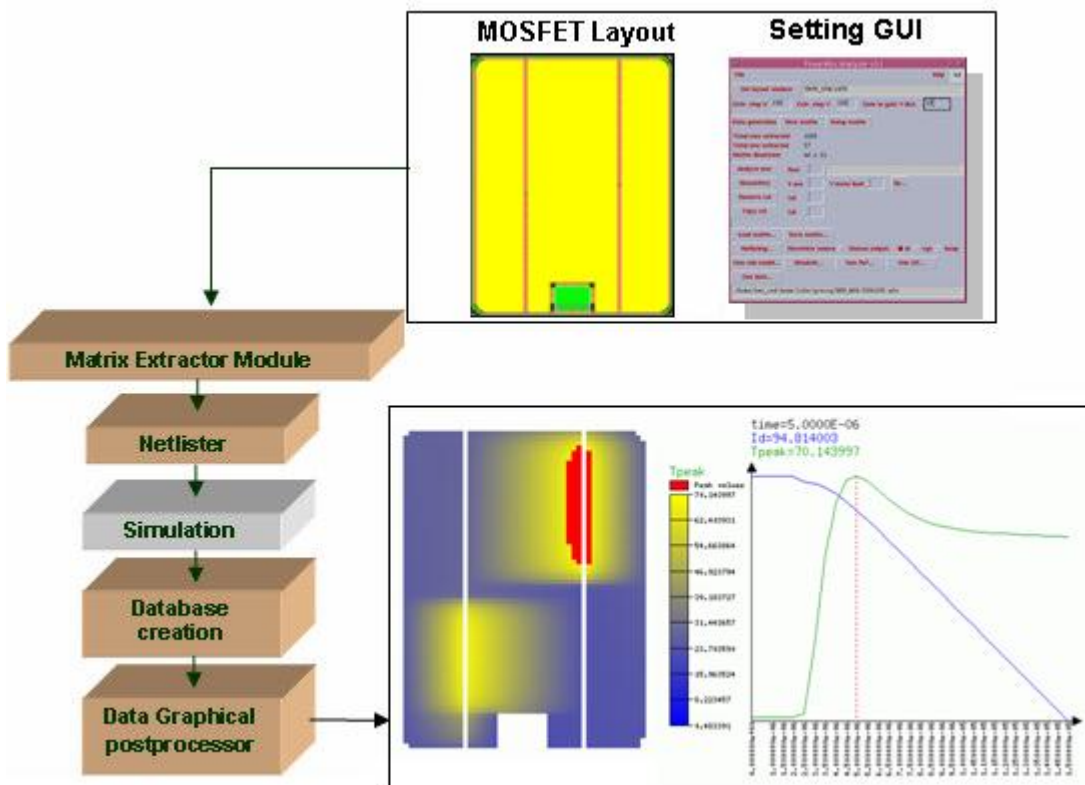


Figure 44 - Thermal-aware simulation framework flow

that the adopted thermal impedance allows accounting for the longitudinal heat conduction and for the dissipated power in the adjacent cells. Furthermore, it is worth noting that in D5.1.3, we have observed that the longitudinal increase of temperature due to a single cell runs out at a distance of about 250µm.

At this point, the full netlist is generated starting from the matrix of Figure 45 through the Netlister module of the Framework. Figure 47 shows the thermal simulation of the DUT under the same work conditions used to perform the measurement reported in Figure 43 where the current flowing in the coil (Figure 41) reach a maximum value of 82A. Temperature behavior retrieved by the simulation, with a peak of about 53 °C, is quite similar to the one measured with the thermal camera by having a ΔT of about 56°C with a relative error of 5%. Also thermal map shows current hot spots areas that recall the ones reported by the thermal camera that are in proximity of bondwires footprints. It is interesting to highlight that in the reported case, the bondwires have been modeled by using a thermal model so that it is possible to see how their thermal capacitance mitigates temperature intensity right below their footprints; in this case they are acting as miniaturized heat sinkers. Due to this predictable behavior, the thermal hotspots are then expected and visible between the three wires contacts (see Figure 43 and Figure 47).

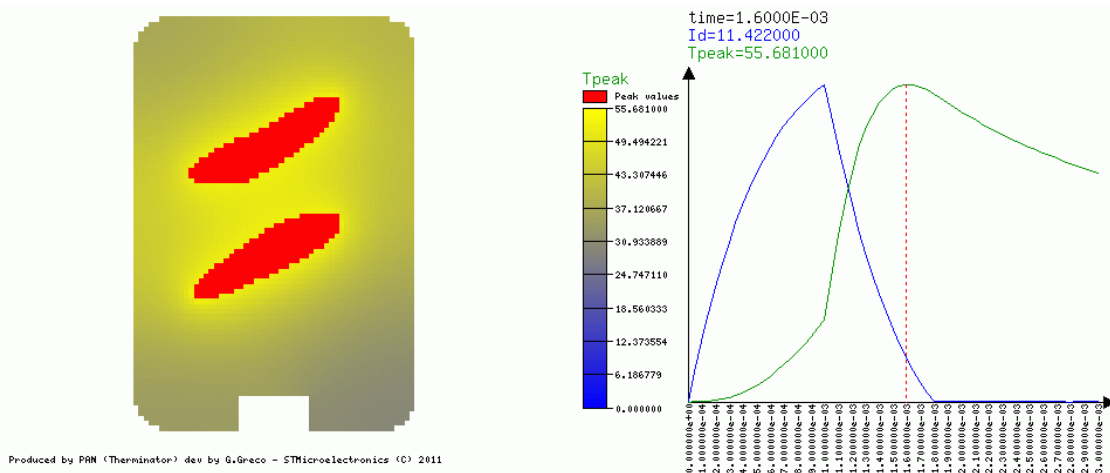


Figure 47 Drain current (blue), temperature peak in (green) and thermal map (left) during a thermal cycle of DUT.

4.5 Conclusions

A simulation activity having as objective the validation of the Thermal Aware Design Framework developed in WP5 has been successfully completed. A cross-simulation between electrical and thermal data of the discrete power devices been completed by taking as device under test a power MOSFET used as switch in an ABS control pump system. The main objective was to replicate the thermal transient measured by advanced thermal measurement equipment during a switching condition.

The criticality of the investigated automotive application demands specific design criteria for the state-solid switches that, thanks to the developed simulation platform, will allow designers to produce devices with a complete predictable thermal behavior under different operating conditions.

The comparison between measurement performed by thermal camera and the simulation performed through the Framework has shown a good agreement in terms of accuracy; an error of 5% is in line with what expected and below the target value stated in the WP7 measurable objective MO7.1.4 equal to 10%.

5 Contactless identification ICs (NXP-D, together with FHG)

5.1 Introduction

NXP-D has done the validation by designing and evaluation of a test chip in silicon. The design comprises several structures to force and measure thermal effects, see Figure 48. The silicon measurements were done on basis of the specification described in deliverable D4.1.3. It is the first time that the CMOS 40nm process with respect to the thermal behaviour is verified. The deliverable D4.2.1 gives an overview about the specified parameters with respect to thermal influence on self heating of analogue circuitries. This is measured and is evaluated on silicon.

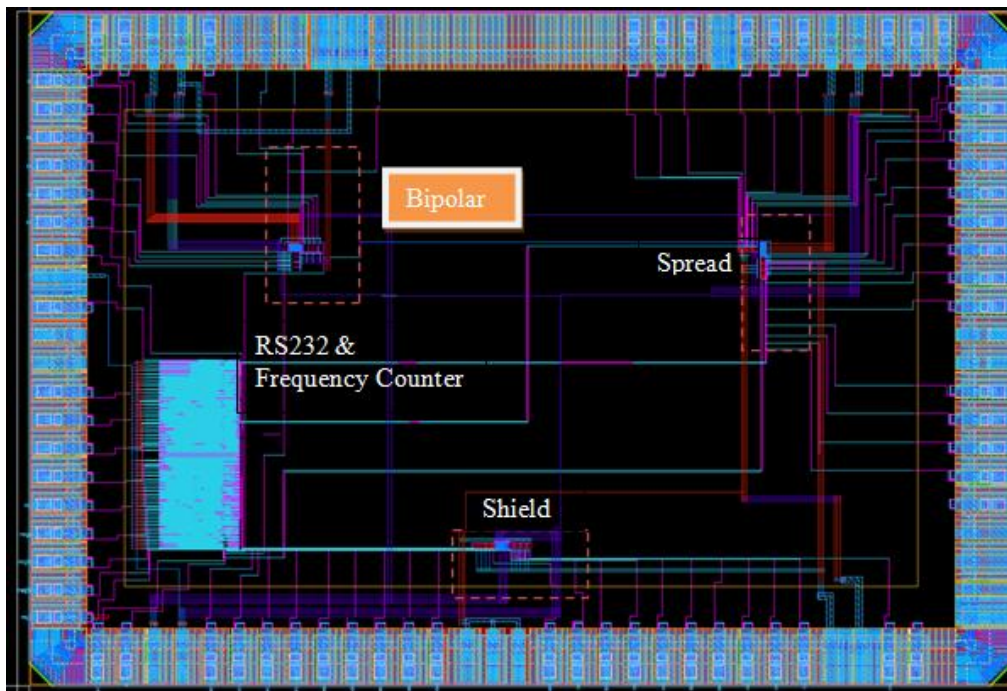


Figure 48: Testchip Layout

FHG-EAS developed the behavioural thermal models. The work was focussed mainly on a detailed thermal simulation of NXPs test chip. It included improvement of the FHG simulation tool Helios towards very early analysis, identification and avoidance of critical thermal behaviour such as hotspots or unfavourable alignment of isotherms. As an example see Figure 49.

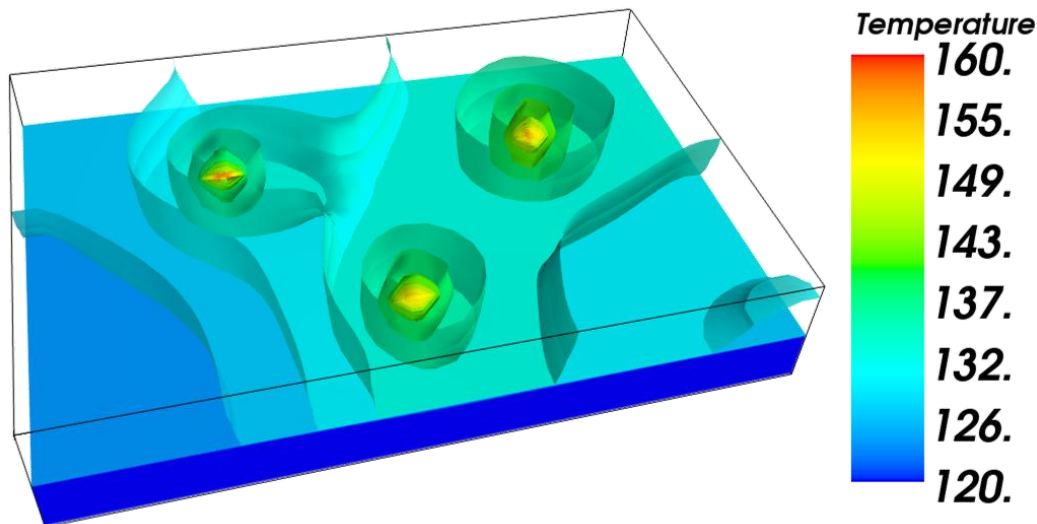


Figure 49: 3D representation of temperature distribution via plot of isothermal faces

5.2 Technical results

The measurements especially of the bipolar test structure is showing that from theory and first simulations on new developed tools from Fraunhofer the Therminator test chip provides the expected effects. The self heating effect can be seen as a local event at power transistor settings up to 0.25W. Overall the measurements of the Therminator test chip are giving a good basis for the next step on top measurements of package influence in work package 6.

FHG has evaluated thermal simulations based on NXP's test chip. The development of the FHG-EAS thermal simulation tool Helios and its integration into the Cadence Design Environment were done. Using some sensible values, FHG have carried out qualitative simulations and compared them to the results of the measurements by NXP.

As expected, the simulation results do not precisely fit the measurements. Temperatures of about 100K less than in the measurement were observed. This, however, might be most likely due to the approximate modelling. On the other hand, the type of data is different. Measurements are bound to the sensing structures and give point-wise temperatures only. The simulations return temperature distributions. We claim that some experimental investigations into the position of the isothermal lines will show a more significant correlation between the simulation and the measurement. From the design automation point of view, such information may be more valuable than the absolute temperature which may be strongly affected by external conditions. Therefore we suggest some thermal imaging measurements for better comparison.

We have additionally conducted some simulations to show the qualitative effect of a heat shielding structure. Contrary to the measurement, we could show a slight decrease in temperature due to the shielding structure. The measurement, however, displayed strongly increasing temperatures. This effect may have its cause in either an electrical or thermal issue. From the thermal analysis point of view, this is most likely due to some electrical misbehaviour.

The reference measurements of a single diode are shown in Figure 50. In this case a constant current is supplied to the diode, the thermal condition is given by elevated, but controlled environment temperature and the voltage drop between emitter and collector respectively the anode and cathode is measured.

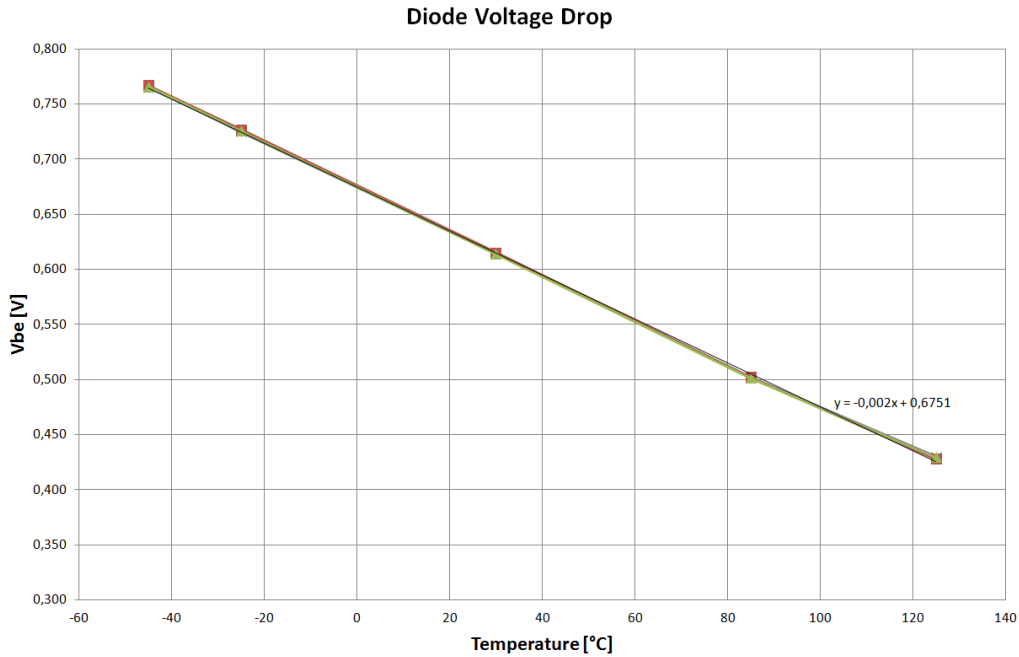


Figure 50 Temperature Dependency of the Diode Voltage V_{BE}

As expected the voltage across the diode is linear with respect to temperature.

The repetition of the same measurement approach but with two different supply currents of the diode results in two different curves like shown in Figure 51.

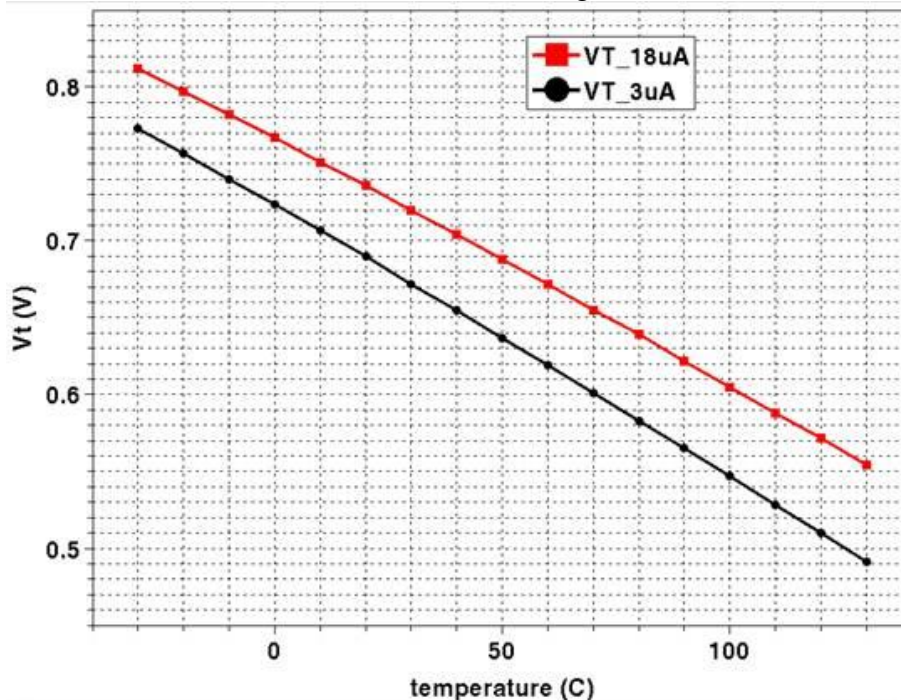


Figure 51 Temperature Dependency of the two Diode Voltages V_{BE} supplied with two different Currents

The difference ΔV_{BE} of the previous measurement is shown in the Figure 52.

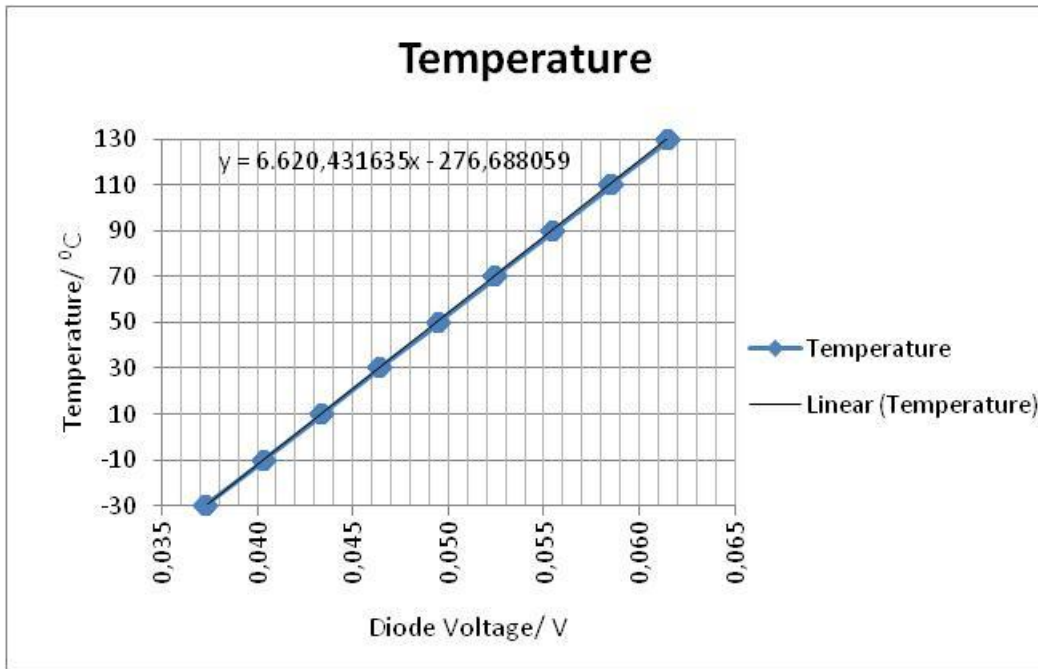


Figure 52 Measurement Result of ΔV_{BE} over Temperature

As a result the ΔV_{BE} behaviour is verified to show a linearity according to the formula
 $T = 6620.4 * x - 276.7 [^{\circ}C]$

The small offset of 3K (276K instead of the expected 273K) is related to a voltage shift of the ground level of the diodes. This effect can be seen if one puts both curves – simulated and measured in one diagram:

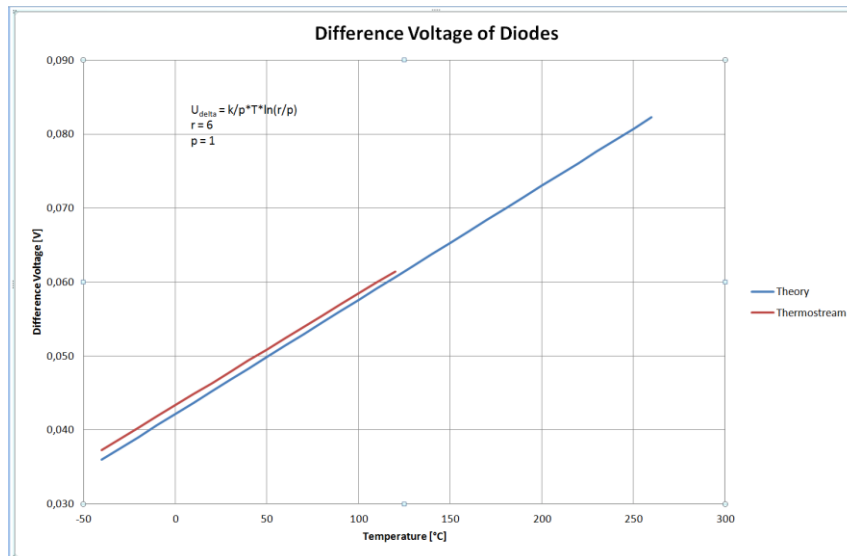


Figure 53 Measured bipolar Trend Curve in Comparison to theoretical calculated Curve

The measured values (red curve) differ from the theoretical calculation (blue curve) by a constant offset. The calculated temperature gradient of the diode is 6,62K/mV.

This curve is completely independent of any process influence. The measurements of several different diode pairs on different devices are showing the same behaviour with the same equation.

5.3 Conclusions

The match of measurement and modelling could be verified by evaluating a range of test structures in the NXP test chip in comparison with the simulation results from the tool developed by Fraunhofer. Major deviations measurement versus modelling could be explained by the measurement- and circuit setup.

6 PSP-based advanced CMOS modelling (IMC)

6.1 Introduction

This deliverable D7.1.1 from work package 7 (WP7) describes the validation and standardization of thermal models with main focus on validation which means the model-hardware-correlation (MHC) itself. As described earlier in deliverable D1.3.1 the project is based on very different practical test cases [3], which span from Power-MOSFET to analog and digital circuits. The model-hardware-correlation described in this deliverable belongs to test case 3 which is the datapath macrocell (digital circuit).

6.1.1 Testcase 3: Datapath Macrocell (digital circuit)

Power consumption is a key system parameter and can vary by several orders of magnitude: From approx. 100W for high-end desktop systems down to 10W for next generation of mobile ultrabooks and further down to smartphones with approx. 1 W in high performance mode and <100 μ W in standby mode. Future digital baseband processors and application processors represent major components for mobile applications and should deliver current desktop computing performance at current smartphone power consumption. This means that system design in terms of power and performance optimization for such applications is highly challenging since high performance modes with high data rates as well as standby modes with very limited circuit activity have to be optimized simultaneously.

Due to the different use-cases and operation modes we see a strong demand for accurate models over a wide temperature range.

Test-case 3 is divided in 4 abstract design levels as follows:

Level	Analysis	Device under test (DUT)
4	static	Single MOSFETs
3	dynamic	Unified Logic Gates
2	dynamic	Ring Oscillator
1	dynamic	Critical Paths

This describes a set of digital CMOS test constructs reflecting the behaviour of digital IP blocks. Derived from critical path information, the different sub-cases provide information about digital circuit behaviour on different abstraction levels.

This deliverable will cover mainly levels 4 to 2, initial results have been partially reported in WP1 and WP2 already (e.g. deliverable D1.1.1 [4] and D2.1.2 [5]). Furthermore test case level 1 will be described in more detail in deliverable D7.2.1 “Demonstration of thermal-aware design techniques” [6].

6.1.2 40nm versus 28nm technology

Besides the link to the actual test-case we also briefly summarize the technological differences of the 40nm and 28nm technologies on a generic level. Due to the diversity of partners and applications and the modular nature of process flows we face many possible technology flavours. Therefore we reference towards the international semiconductor roadmap (ITRS) if applicable.

This sub-chapter will cover the investigation of the conventional planar bulk MOSFET using advanced performance booster for different technology nodes. In general we see the following trend in table 1.1. The Front-End-Of-Line (FEOL) processes show several revolutionary material innovations especially for the current 32nm/28nm nodes whereas the Back-End-Of-Line (BEOL) is more evolutionary by optimising the Cu interconnects and the values of the low-k dielectrics.

Booster \ Tech. Node	65nm	45nm/40nm	32nm/28nm
Gate Lithography	193nm OPC / PSM	193nm OPC / PSM	High NA / Immersion
Gate Electrode	Dual N+/P+ Poly-Si	Dual N+/P+ Poly-Si	Metal Gate
Gate Dielectric	Nitrided Oxide	Nitrided Oxide	High-k
Stress Engineering	DSL / SMT	DSL / SMT / eSiGe	DSL / eSiGe
Silicide	NiSi	NiSi	NiSiPt

Table 1.1 – Technology booster versus technology node, 65, 45/40, 32/28nm

Initially it was expected that the temperature dependence of novel materials (e.g. silicides, metal gates, high-k dielectrics) on the overall thermal behaviour would play a more dominant role. But as we can see in the following sections from the temperature dependence of the effective drain current and the threshold voltage, different design parameters like device geometry and surrounding (e.g. distance/position of device elements) and the variations of the absolute values of the threshold voltage based on random doping fluctuations or material properties (e.g. workfunction) are more dominant for the overall device performance.

6.1.3 SOI-FinFETs and self-heating

At the beginning of the project the partner Infineon (IFX) focused on Multi-Gate SOI-FinFETs. Those results were reported in deliverable D1.1.1. The originally planned comparison between bulk FinFETs and SOI-FinFETs was changed into a comparison of two SOI-FinFETs designs with different fin thicknesses because a bulk FinFET design with similar performance as the SOI-FinFET was not available in hardware. The minimum channel length assessed was 40nm because shorter devices suffer from stronger short channel effects and do not contribute more device insight regarding thermal effects due to other parameter fluctuations.

During the project the partner Infineon was replaced by Intel Mobile Communications (IMC) and the topic self-heating in SOI-FinFETs was stopped because of a lack of available FinFET hardware from Infineon for further modelling activities.

6.1.4 Temperature Inversion trend

IMC focused on advanced planar silicon bulk CMOS Logic MOSFETs instead. The specific interest here is to provide the measurement data which clearly shows the novel temperature inversion effect as trend over a series of technology nodes. This means that the classical view for technologies >65nm in which hotter circuits run slower is now stopped because 40nm technologies show very little temperature dependence. And the trend might even be inverted for 28nm technologies where hotter circuits show faster switching in dependence of the design.

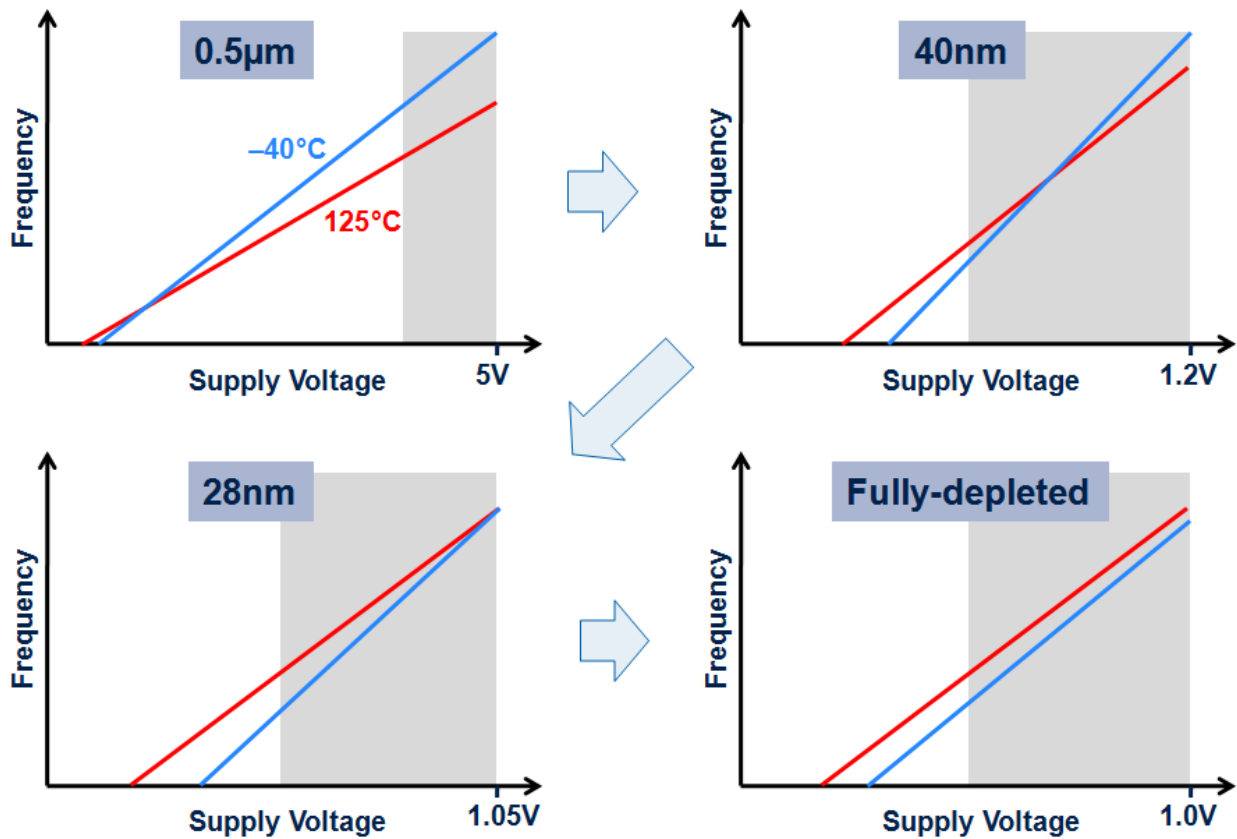


Figure 54 Temperature Impact and Temperature Inversion point.

Figure 54 shows in an abstract but clear way how the temperature inversion effect is emerging over time or novel technology nodes. Four cases are given: First the classical technologies from 0.5µm till 65nm (upper left), then the current 45/40nm technology (upper right), next the novel 32/28nm technology (lower left) and finally the emerging fully-depleted channel technologies for 22/20nm and beyond (lower right). The usual operating range is marked as grey area till the nominal supply voltage.

In older technologies the circuit performance is increased and the circuit is functional with higher frequencies if the system is cooled down (blue curve). But already in these technologies there was an intersection point or voltage range in which hotter circuits (red curve) could run faster at very low supply voltages outside the usual operation range. Over time this intersection point moved up into the middle of the operation range because the supply voltage was reduced with every new technology node. For the 28nm technology we have reached now the situation in which hotter circuits can run with a higher frequency. The continuation of this trend is expected to hold true with further scaling for future technologies. This chapter is an introduction into the topic of the temperature inversion effect which will be investigated in more detail in chapter 6.3.

6.1.5 Therminator project objectives

Therminator project objective #1: New modeling and simulation capabilities to support accurate circuit thermal analysis and simulation

WP7 measurable objective #1:

Error between measurements and simulation within **20%** [IMC] (MO7.1.6→ see e.g. fig. 2.3 and 3.12, chapter 2 & 3)

Therminator project objective #2. Innovative thermal-aware design techniques, methodologies and prototype tools for controlling, compensating and managing thermally-induced effects on parameters such as timing, (dynamic and leakage) power, reliability and yield

WP7 measurable objective #2:

Determine the temperature inversion intersection point of two temperatures corresponding supply voltage within **20%** for relevant parameters as performance and Ion (MO7.1.7→ see chapter 2 & 3).

Therminator project objective #3. Demonstration of the accuracy and ease of integration within existing design flows of the new models by validation against measured data obtained on ad-hoc silicon structures

WP7 measurable objective #3:

Validate the high-k metal gate 28nm CMOS models developed in WP2, with cross-technology reference to 40 nm. Error between measurements and simulation within **20%** [IMC] (MO7.1.8→ see e.g. fig. 3.12, chapter 3)

Therminator project objective #4. Demonstration of the applicability and effectiveness of the new design solutions through manufacturing of test-chips featuring leading-edge silicon technology, as available from some of the project partners

WP7 measurable objective #4:

Demonstration of model hardware correlation based on 40nm and 28nm testchips, i.e. one or more testchips per technology. (MO7.1.9→ testchips as vehicles to achieve results demonstrated)

Therminator project objective #5. Demonstration of the usability and effectiveness of the new design methodologies and tools by their application to industry-strength design cases made available by some of the project partners

WP7 measurable objective #5:

The circuit-referenced PSP-methodology is **100%** compatible to the IMC design flow. (MO7.1.10→ see conclusion section 6.4)

6.2 40nm Model-Hardware-Correlation (MHC) results

6.2.1 Device level model to hardware correlation including devices for analog usage

The DC model to silicon correlation is shown in Figure 55 as a function of physical gate-length for p-FETs of regular VT device flavour (RVT). Lines show the simulation values of the IMC- 40nm model, which is a BSIM 4.5 model, symbols are the measured values of a device chosen by multi-golden device selection with the temperature as parameter, compared here for the range from -40°C to 110°C with intermediate steps at 25°C and at 85°C. Figure 56 shows the corresponding plots for n-RVT devices. The x-axis in all of the 4 sub-plots covers a wide range of device gate length starting with a subnominal device of ~35nm to a maximum device length of 9µm. All design relevant gate lengths are covered by dedicated test structures, the nominal gate length of 40nm is used for digital and library cells, a 50nm

gate length is used for a leakage reduced standard cell library. Even longer transistor gates are typically used for mixed-signal and analog purposes as well as for power switches.

Figure 55 Figure 54a shows the model hardware correlation (MHC) for V_{tlin} (threshold voltage in linear regime) which is measured by a constant current criterion of $10nA * W_{phys}/L_{phys}$, the drain voltage is 50mV. V_{tsat} is measured with the same criterion, but with a drain voltage of $V_{DD}=1.1V$ and is more dependent on short channel control than V_{tlin} . From Figure 55, it is clearly visible that the dependency of threshold voltage over length is significantly different for linear and saturated operating condition. Despite this fact the temperature dependency is very similar for both V_{tlin} and V_{tsat} and even over the entire gate length range covered by the test structures. The change of V_T with temperature is larger than the variation over length from digital to the long channel device emphasizing the importance of a good temperature modelling.

The lower plots of Figure 55 and Figure 56 show the corresponding I_{dlin}/W and I_{dsat}/W values over length and temperature. Compared to the V_t plots the currents show in general a much smaller temperature dependence than length dependence. Close to the digital length the T-dependence comes to very small values for I_{dlin} and nearly seems to vanish for I_{dsat} .

The reason behind is the compensation effect of V_T , which decreases with T resulting in a higher gate overdrive and mobility of electrons and holes which decreases at higher temperature.

The challenge of temperature modelling in a 40nm technology can be seen as to accurately describe a small resulting overall I_{on} -change from two contrarily and strongly T-dependent effects.

This compensation of two competing effects is illustrated by Figure 57 which shows the measured performance of a ring oscillator circuit vs. V_{DD} for $T = -40^\circ C$ and $T=125^\circ C$. The lines are linear fits to measurements and visualize the competing effects of V_t -shift, which is simplified here as the interception of the linear fits with the x-axis and is lower for the high T operation of the ring oscillator and the slope, which is smaller for high T due to reduced mobility. At a V_{DD} of 1.1V the circuit performance is exactly the same for both temperatures, this T-value is called the temperature inversion point and is for RVT devices of a 40nm technology close to the typically used V_{DD} -values. Below that point the performance is higher for high T as the gate overdrive ($V_{DD}-V_t$) dominates the performance.

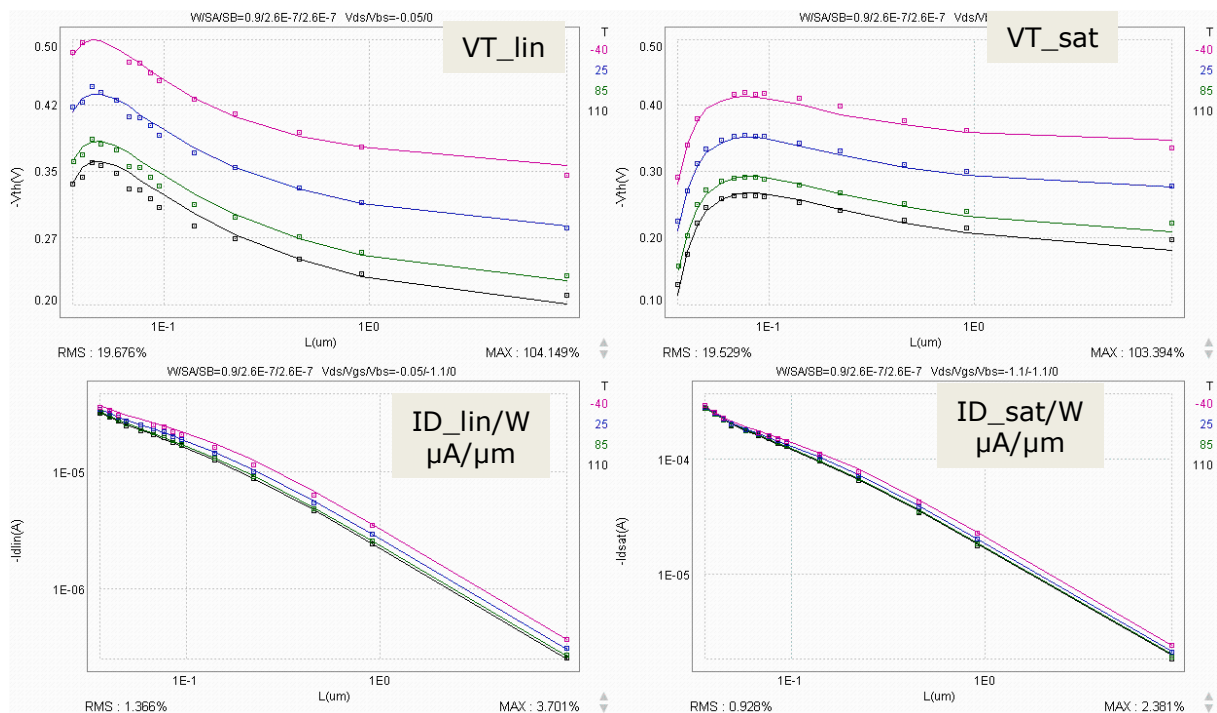


Figure 55 Electrical key parameters of p-RVT devices as a function of physical gate length with temperature as parameter. Lines are simulation, symbols denote measured values

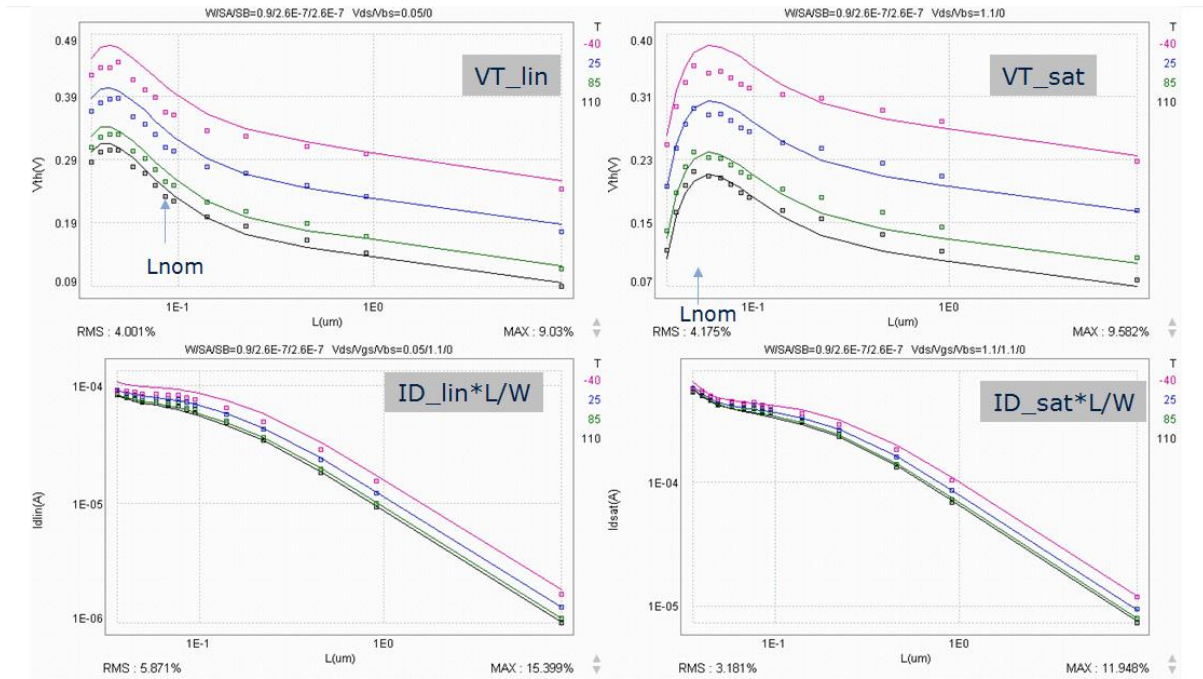


Figure 56 Electrical key parameters of n-RVT devices as a function of physical gate length with temperature as parameter. Lines are simulation, symbols denote measured values

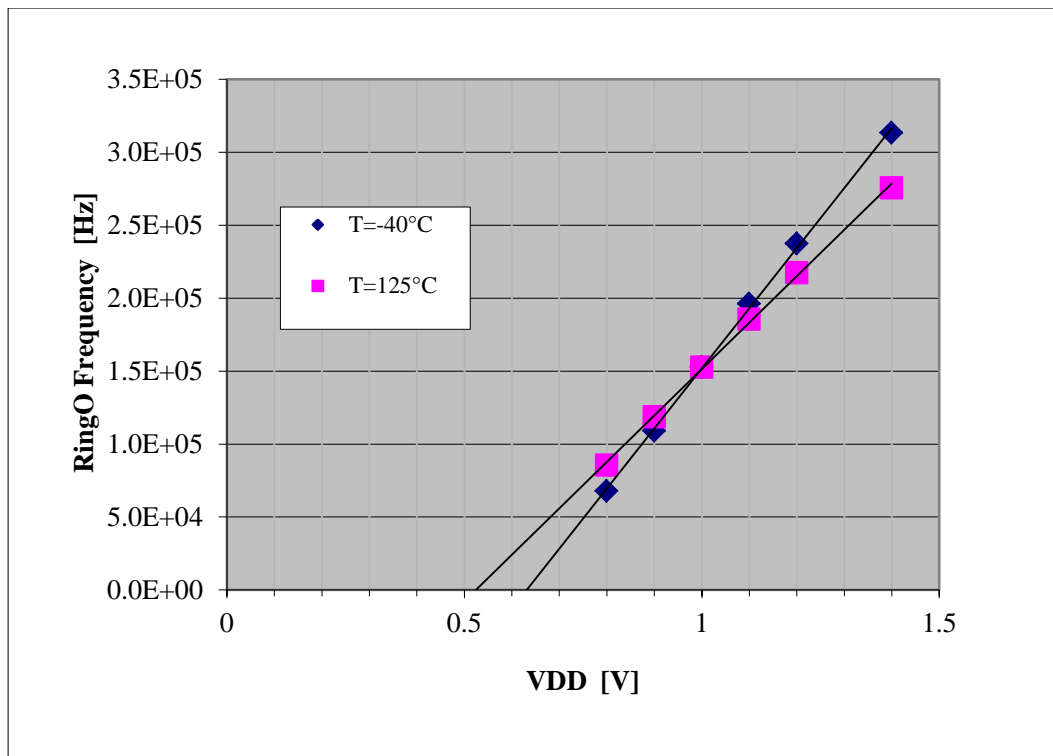


Figure 57 Measured circuit performance (ring oscillator) vs. VDD for T = -40°C (dark blue symbols) and T=125°C (purple symbols). The lines are linear fits to measurements and illustrate the competing effects of V_t -shift (interception of fits with x-axis, lower for high T) and slope, smaller for high T

Above the temperature inversion point the higher mobility of the low T operation has the bigger impact.

While Figure 55 and Figure 56 show that the modelling quality for all of the DC key parameter is decent over the whole length range, Figure 58 – Figure 60 allow a closer look on the consistency of model and measurement data. These plots show the V_{Tsat} and I_{on} vs. T-behavior for 3 design relevant gate lengths representing digital, mixed signal and analog devices. Thereby, the model is the same as used for Figure 55 and Figure 56, but hardware is from a different 40nm technology source which was aligned with respect to fulfil IMC’s product requirements.

For the digital length in Figure 58 the V_T decrease over the measured T-range from -40°C to 110°C is about 160mV for both, n- and p-RVT, the I_{on} decrease with T is only 4% for p-RVT and about 10% for n-RVT. Figure 59 represents an intermediate gate length typically used for analog circuits, here the V_T change with T is quite similar to the digital length but I_{on} is much more reduced with about 14% for both, n- and p-RVT. For long channel devices (Figure 60) the V_T decrease is still very similar to the digital and analog length, but I_{on} is reduced drastically over T with ~20% for p-RVT and as much as 40% for the n-RVT long channel device. Despite this qualitative change of I_{on} vs. T for the different devices the IMC model as developed for silicon of source 1 is capable of well describing also the Si of a 2nd source.

DC T-Behavior RVT, L_{nom}

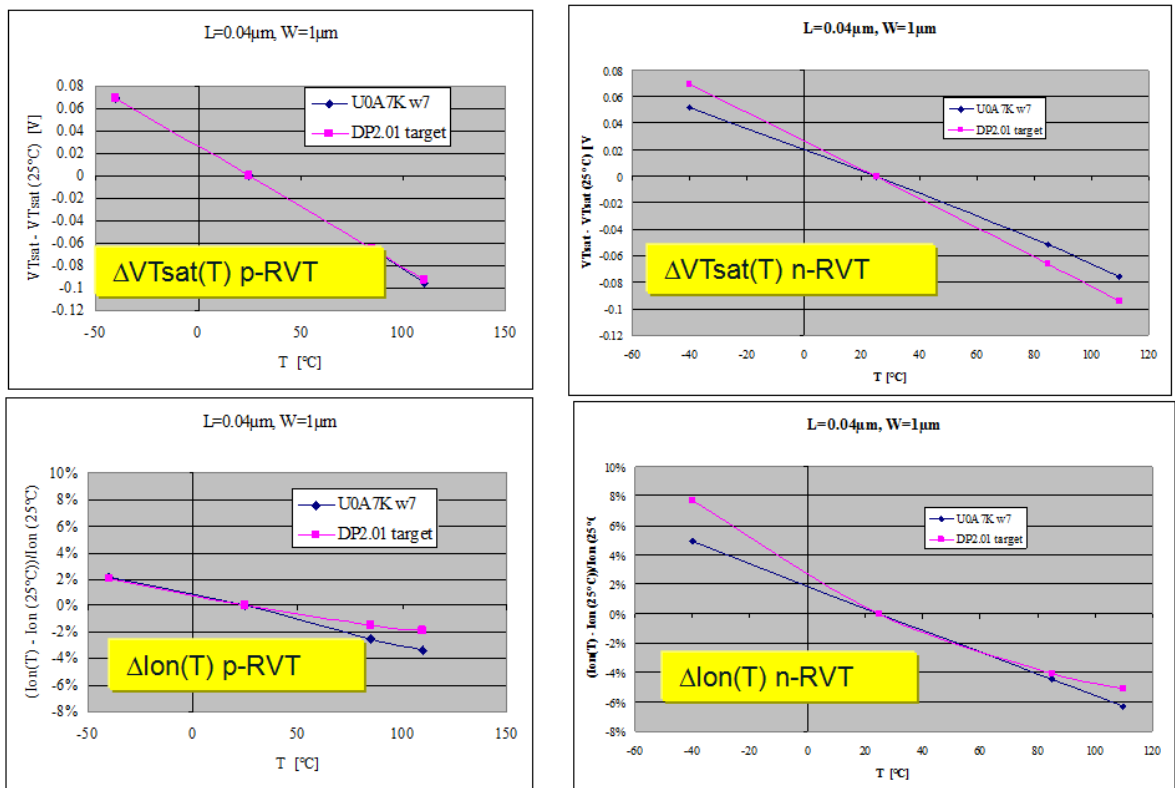


Figure 58 - Electrical key parameters of p-RVT (left side) and n-RVT (right side) for T-dependent change of V_{Tsat} and I_{on} for RVT devices of nominal length, normalized to room temperature. Targets (shown in purple) are model values, measurement values are shown in blue

DC T-Behavior RVT, Analog Length

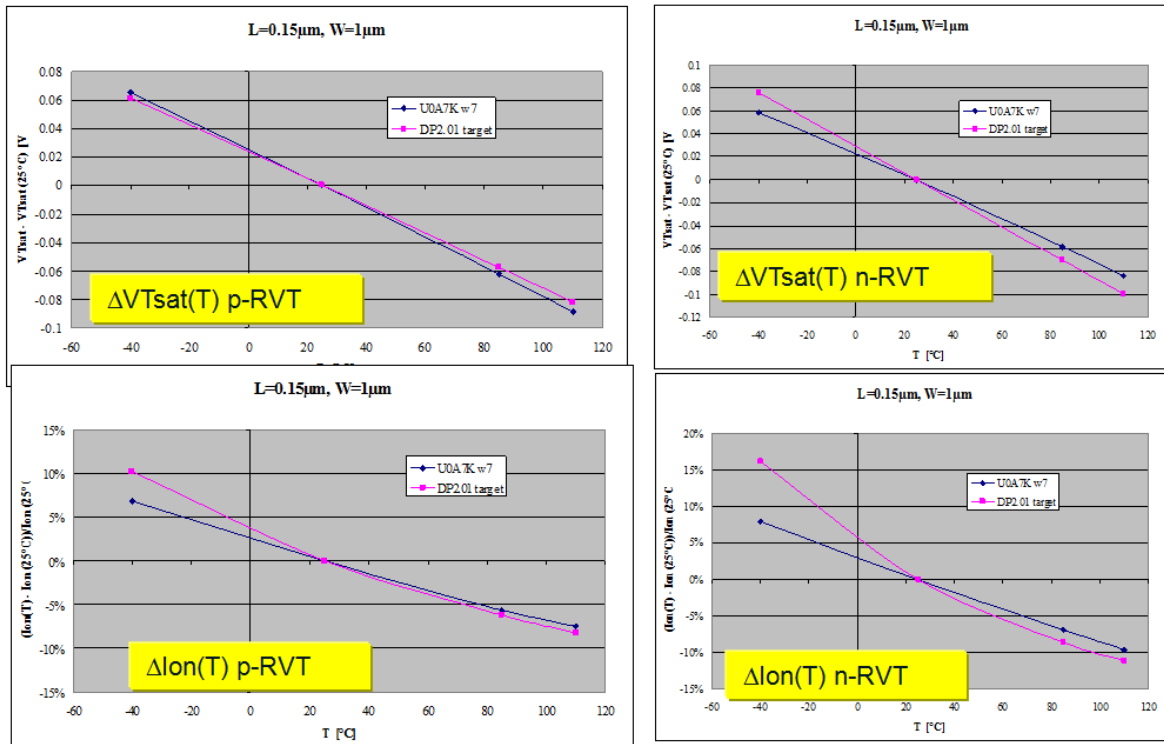


Figure 59 Electrical key parameters of p-RVT (left side) and n-RVT (right side) for T-dependent change of V_{Tsat} and I_{on} for RVT devices of intermediate length as typically used for analog circuits, normalized to room temperature. Targets (shown in purple) are model values, measurement values are shown in blue

DC T-Behavior RVT, Longchannel

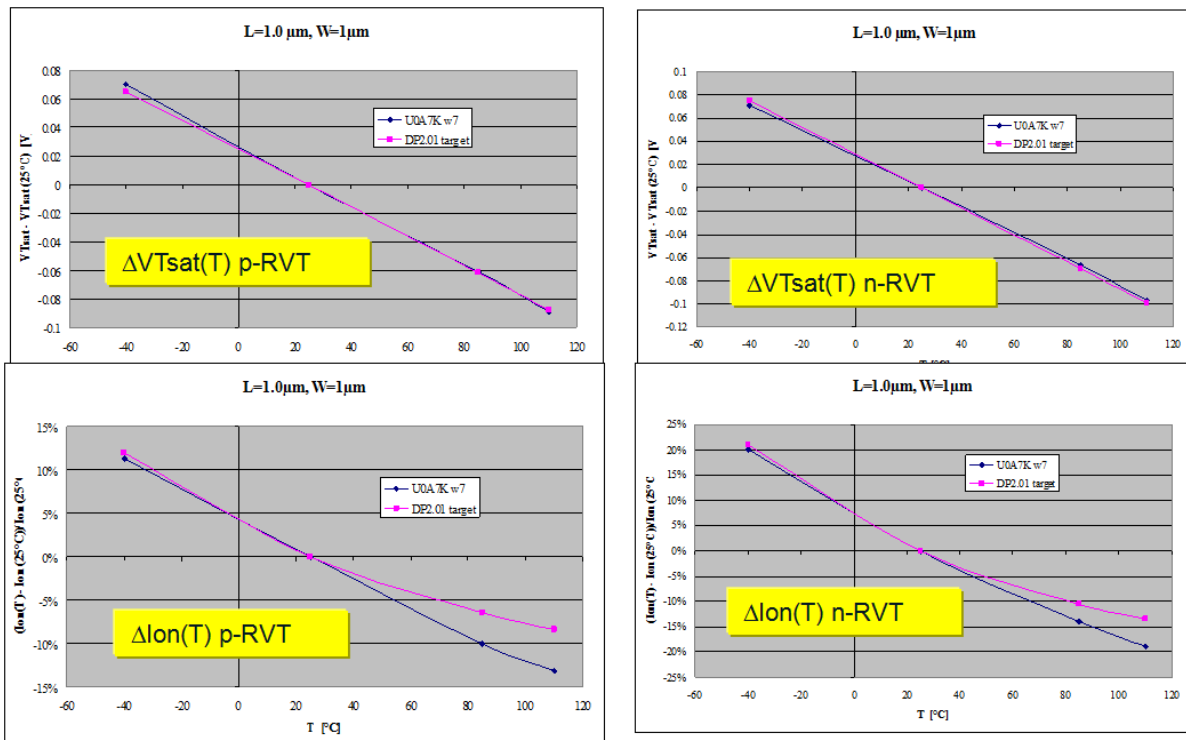


Figure 60 Electrical key parameters of p-RVT (left side) and n-RVT (right side) for T-dependent change of V_{Tsats} and I_{on} for RVT long channel devices, normalized to room temperature. Targets (shown in purple) are model values, measurement values are shown in blue

6.2.2 Self-heating

Self heating is no concern for performance modelling as in 40nm technology the typically used VDD values are very close to the temperature inversion point, see Figure 61 for RVT and high VT (HVT) devices. Self-heating in general is largest at the highest VDD as used in the technology node and the given application. From Figure 61 it can be concluded that at a VDD of 1.2V the performance shift of an RVT inverter library cell is only ~0.05%/K and is even smaller for HVT devices. If the magnitude of the self heating effect is assumed to be 20K which is something like a worst case this would result in a performance degradation of less than 2%. This is negligible compared to other inaccuracies in the 40nm temperature modelling. Therefore, self-heating effects were not further evaluated in 40nm bulk technology as used by IMC.

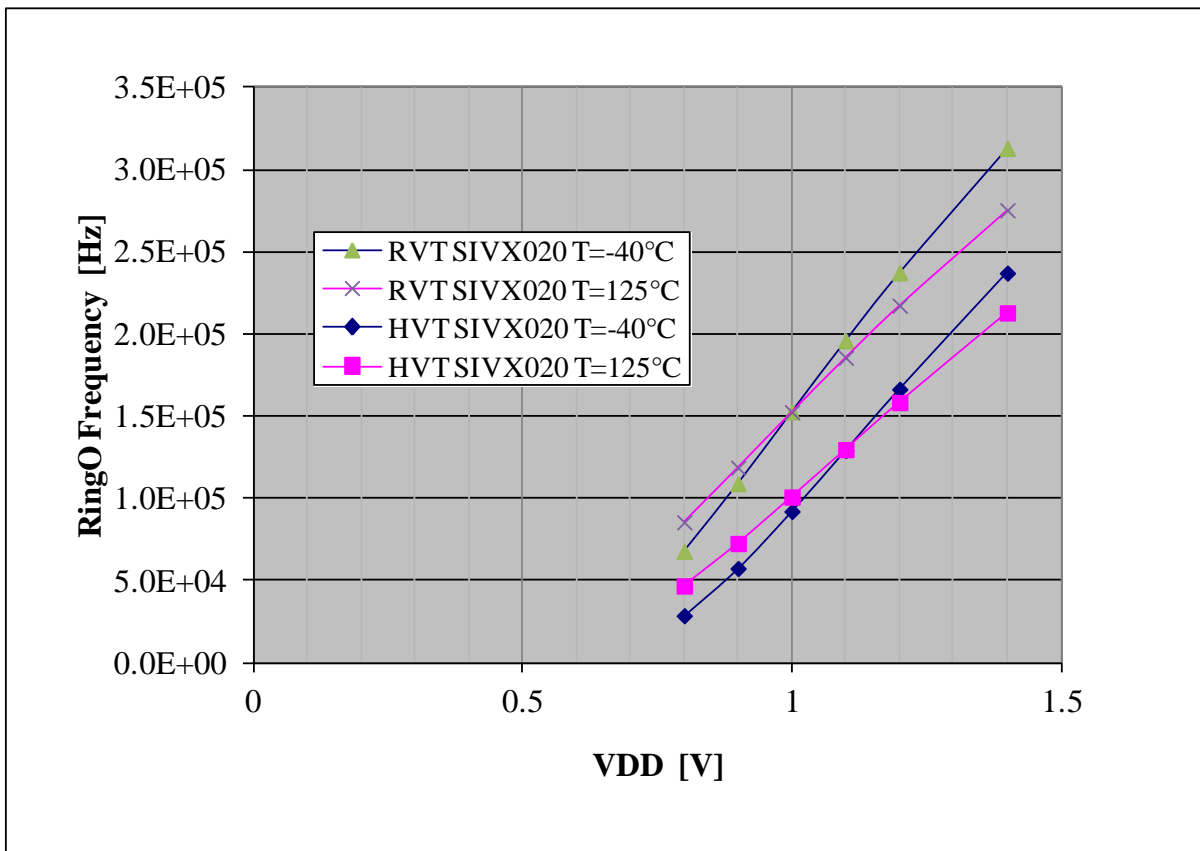


Figure 61 - Temperature inversion point for RVT and HVT hardware of ring oscillator built up from inverter library cells. The inversion point is at VDD=1.0V for RVT and 1.1V for HVT

6.2.3 Circuit level Model to Hardware Correlation for digital and library standard cell applications - performance

The most critical topic for digital applications is the good matching of model and silicon for dynamical operation as described by the delay of standard logic cells covering the full operation range of input slopes, output capacitances and over the full VDD range as used in a product. Typical test structures for model hardware correlation for digital applications are ring

oscillators built up from standard library cells of product relevant logic functions. The key parameter of such a ring oscillator is the oscillation frequency which is reciprocal to the delay of the respective library cell.

Inverter cells have the most basic functionality of all library cells and in most cases they also have a relatively simple layout and therefore are only affected by a subset of the layout dependencies present in complex technologies using massive stress engineering like the 40nm technology used by IMC.

Figure 62 shows the performance or frequency ratio of an inverter ring oscillator between 125°C and room temperature for 3 different VDD. Big symbols indicate the model and small symbols the measurement data on die level. For a nominal voltage of VDD=1.1V it can be seen again that the change with temperature is extremely small, measured and modelled values for this library cell are close to 0.98 meaning that the high temperature (25°C) performance is 2% smaller than when operating the circuit at 25°C. For ultralow VDD of 0.8V the high T performance is about 12% higher than for room temperature, the overdrive operation at VDD=1.26V is about 5% slower at high T. From the scattering of the die-fine measurement data it can be seen that also the performance variability of the individual dies causes some spread in the performance ratio between high and room temperature and the model values fit into the measured distributions very well for the entire VDD range as typically used by mobile products in 40nm technology.

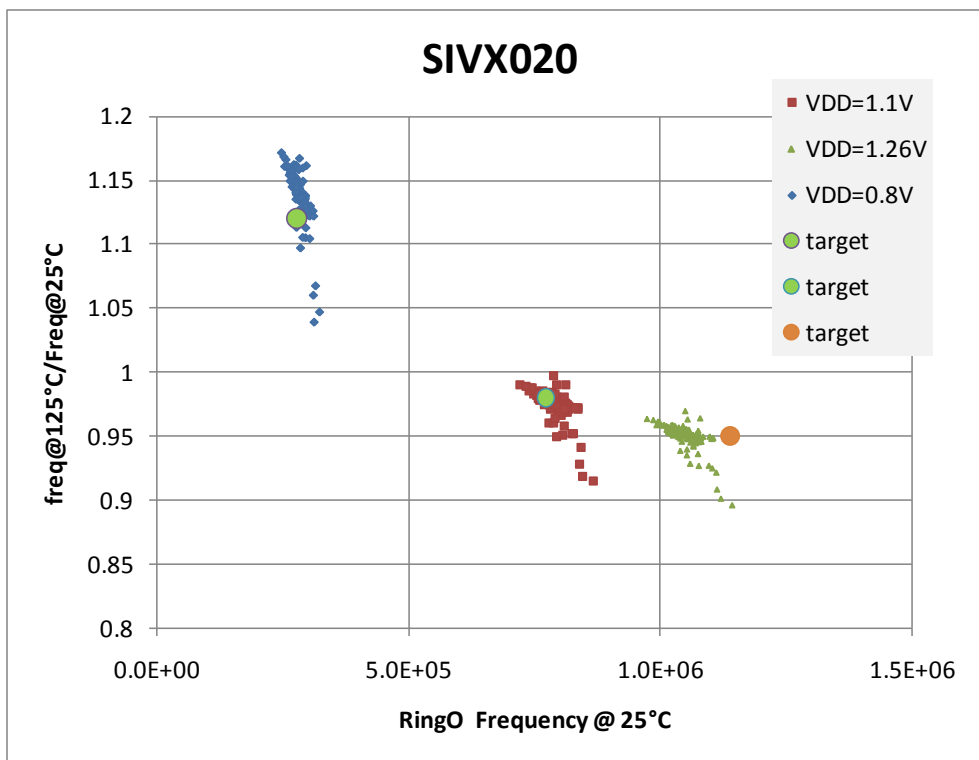


Figure 62 - Performance (frequency) ratio between T=125°C and room temperature for a ring oscillator structure built up from library standard cell (Inverter) as a function of VDD. Small symbols show die-fine measurement data, large circles denote the model values

Looking more into the details of temperature modelling, Figure 63 shows the performance ratio on a very fine resolution on both the temperature and VDD with measurement and

model values at temperatures of -40°C, -10°C, 25°C, 55°C, 85°C, 125°C and VDD from as low as 0.8V to a very high overdrive voltage of 1.4V in steps of only 0.1V. A 2-input NAND has been chosen for this detailed comparison because it highly uses standard cells and it is already a more complex library cell using transistors in series operation.

Figure 64 shows the deviations between model and measurement for all of the operating conditions and data as shown in Figure 63. It can be easily seen that for most of the operating conditions the model hardware correlation is in a narrow band of +/-2%. The biggest discrepancies occur at low temperature which is mostly related to the shortcomings of the BSIM 4.5 model. This will be improved in future technologies by using PSP as the compact model for device modelling and circuit simulation, see chapter 6.3.

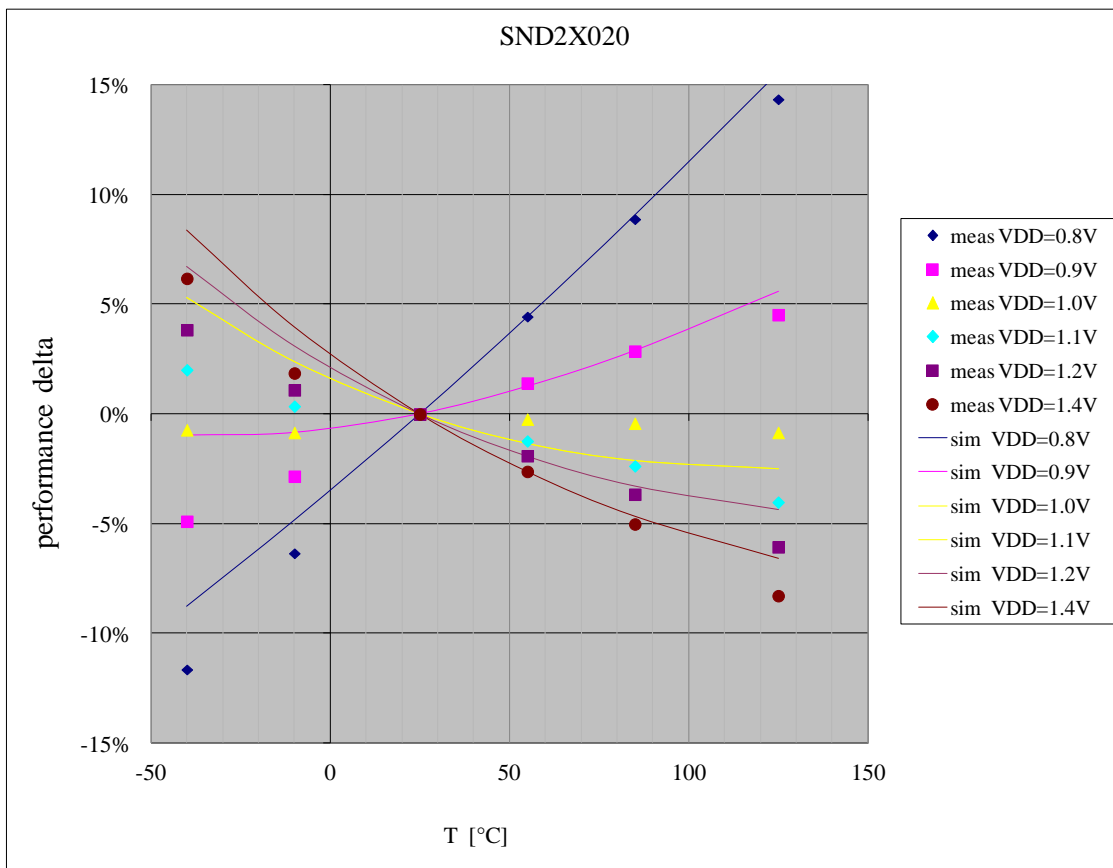


Figure 63 - Temperature and VDD dependent comparison of model and Si measurement for a ring oscillator built up from 2-input NAND library cells (RVT). Normalized to performance at room temperature. Lines show model values, symbols indicate measurements

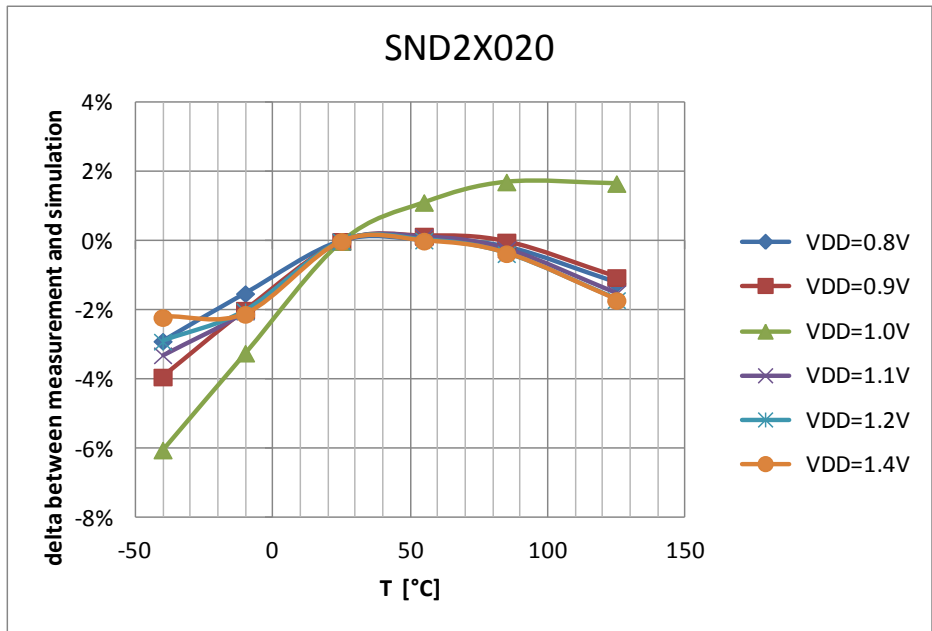


Figure 64 Delta between measurement and model values as a function of temperature and voltage for the 2-input NAND ring oscillator from Figure 63

We looked to a larger set of library cells which include more functionality on the one hand, and are affected more heavily by different layout dependencies on the other hand. Figure 65 shows a plot of performance ratios for high to room temperature. Additionally, the model hardware correlation is included for the leakage reduced standard cell library based on an increased gate-length of 50nm. The maximum delta between modelled and measured performance ratio is about 2% and the typical deviation is below 0.5% which is much smaller than the dependency of the ratio from the cell functionality and the VDD.

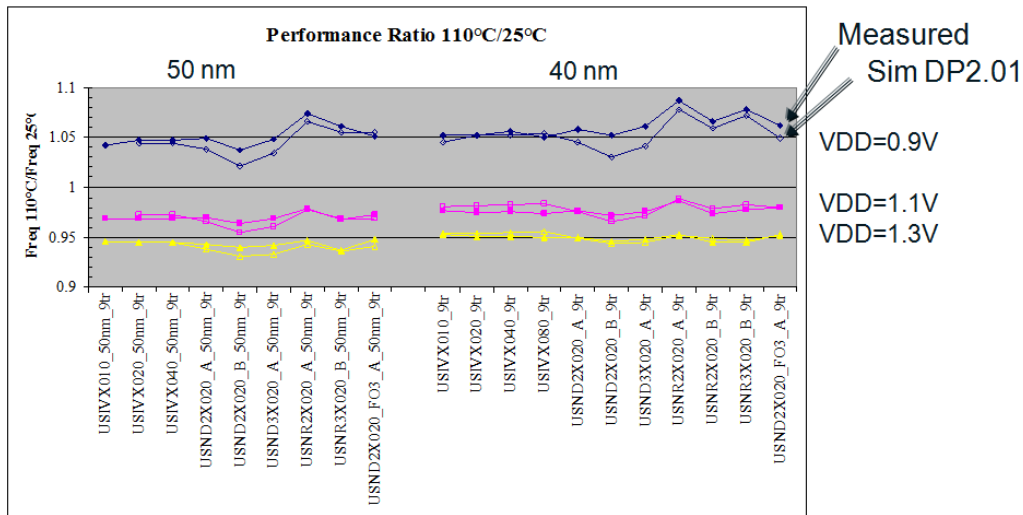


Figure 65 Performance (frequency) ratio between $T=110^{\circ}\text{C}$ and room temperature for ring oscillators built up from different library standard cells as a function of VDD. Right side of plot shows values for digital library with nominal length (40nm), left side shows results for leakage reduced library with 50nm gate length. Open symbols indicate modelled values, solid symbols indicate measured results

6.2.4 T-dependent Model Hardware Correlation for a large number of library cells

Figure 66 to Figure 71 show the dynamic model hardware correlation for a larger set of library cells with the y-axis showing the deviations between measured and simulated values for the delay per library stage. The set of cells is a representative one since it represents all relevant standard cell groups used in products including complex cells which might be heavily impacted by layout dependencies. Cell names and details can't be disclosed here. Measurements were done on a product tester allowing the measurement of many library cells under different operating conditions and for a large sample size.

The first 3 plots (Figure 66 to Figure 68) show data for nominal voltage VDD=1.1V and at temperatures of -30°C, 29°C and 125°C. The changes of deviations with temperature for the mean values for all cells are very similar to the previous results. Additionally, it comes out here that even for the much more complex cells included in these plots the temperature model fits to the measured cells on a cell-fine level with a similar accuracy.

Even at ultralow VDD-condition of 0.8V, which is extremely sensitive to VT-modelling as shown in Figure 69 to Figure 71 the accuracy of temperature modelling is not much reduced compared to a nominal VDD of 1.1V.

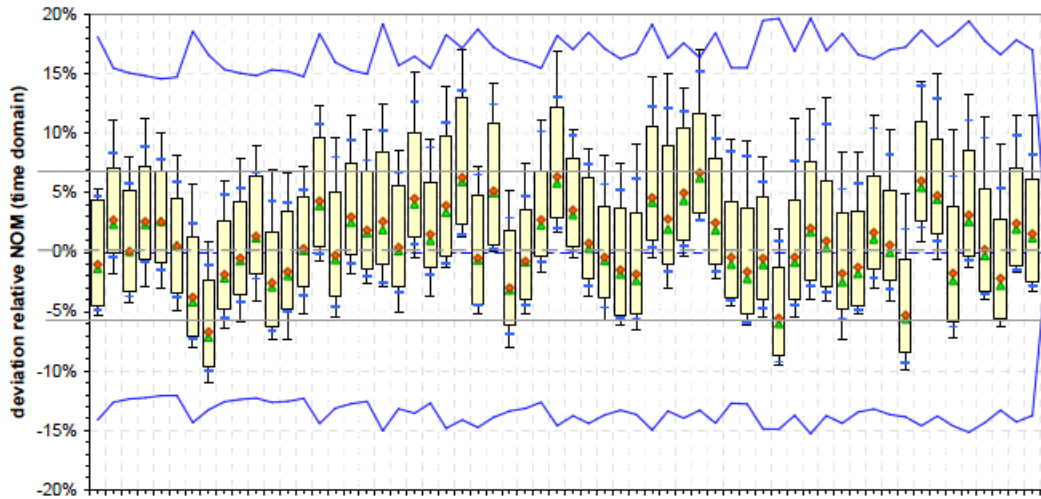


Figure 66 T= - 30°C, VDD=1.1V, mean deviation over all measured cell: +0.5%

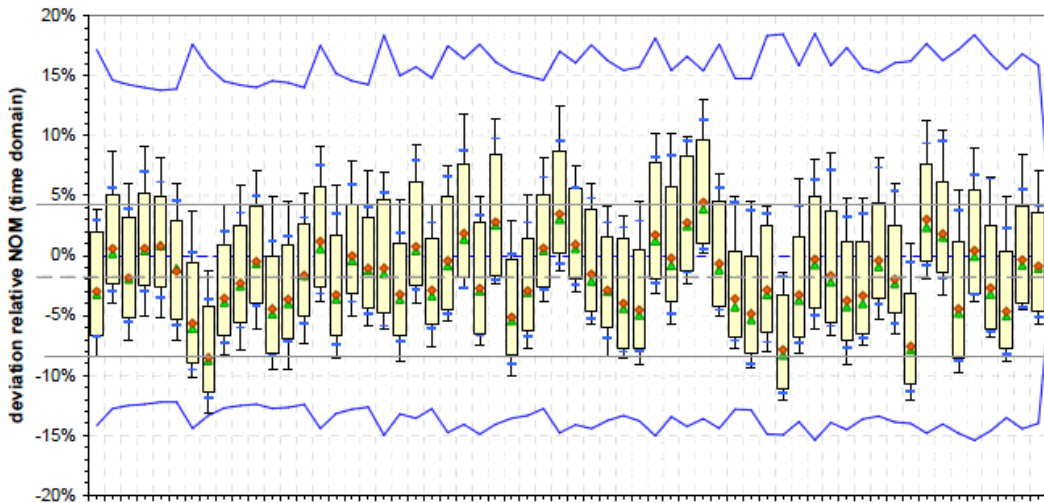


Figure 67 T=29°C, VDD=1.1V, mean deviation over all measured cell: -2%

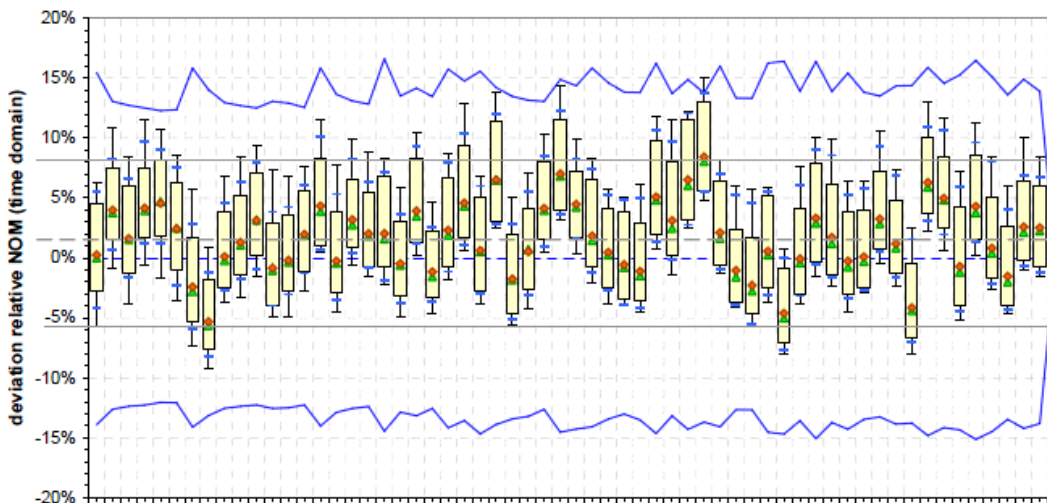


Figure 68 T=125°C, VDD=1.1V, mean deviation over all measured cell: +2%

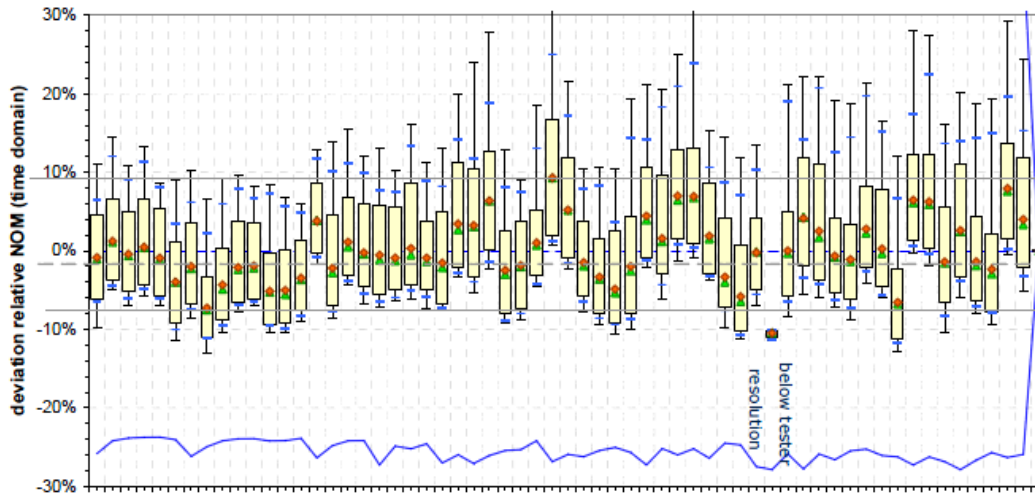


Figure 69 T= -30°C, VDD=0.8V, mean deviation over all measured cell: -2%

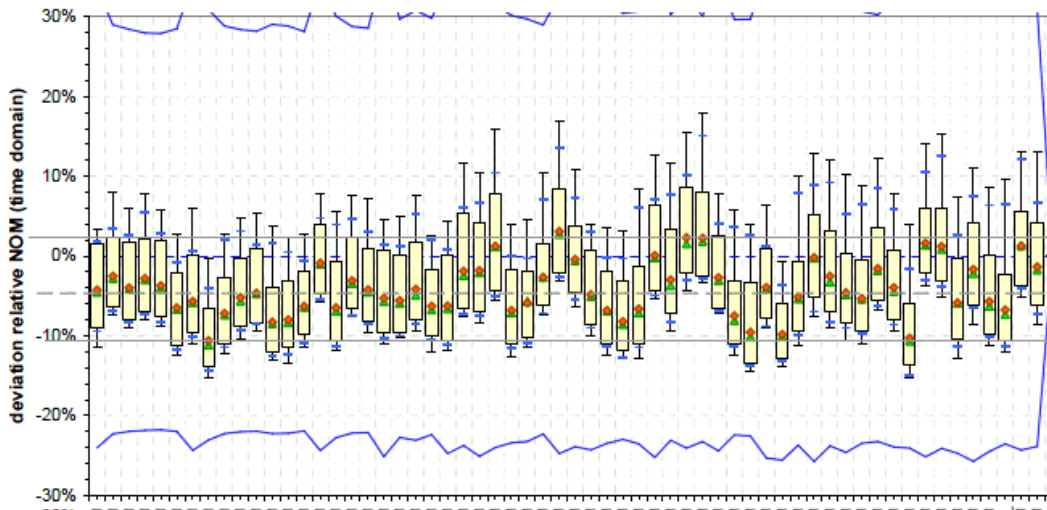


Figure 70 T= 29°C, VDD=0.8V, mean deviation over all measured cell: -4%

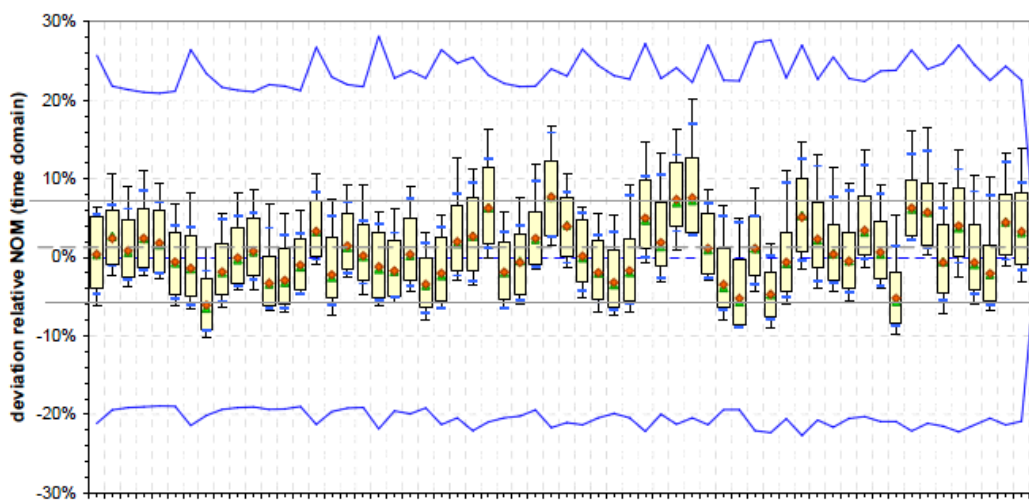


Figure 71 T= 125°C, VDD=0.8V, mean deviation over all measured cell: +2%

6.2.5 Circuit level Model to Hardware Correlation for digital and library standard cell applications – leakage

Appropriate modelling of product leakage comes more and more into focus for mobile products. While a typical device model aims to describe the typical or worst case behaviour of a given transistor with all its contributions over VDD and temperature a leakage model for circuit applications has to take some additional aspects into account. Especially all variability effects -for example device mismatch- lead to a distribution of single transistor leakage values on circuit level even if the global manufacturing process is perfectly on target. As all of the typical leakage contributions of a transistor are log-normal distributed the average leakage of an ensemble of transistors is larger than the median of the same ensemble. Thus a circuit containing many library cells has a different leakage to performance ratio than the typical library cell itself. Dedicated IMC leakage models were developed for the proper description of circuit or product level leakage.

Figure 72 shows the correlation between performance and leakage for ring oscillator circuits over VDD and temperature for the leakage models compared to die-fine circuit measurements. As the measured wafer was not well centered the measurement values are not exactly hitting the targets but the correlations trends suggest a good fit between leakage models and performance centered silicon.

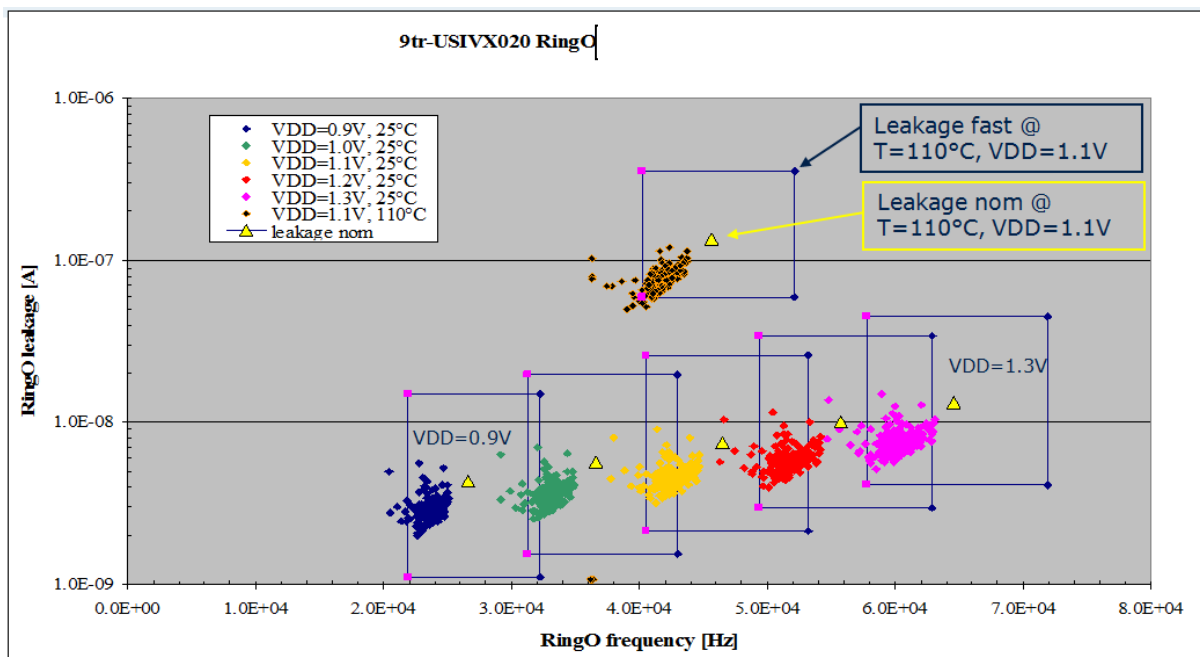


Figure 72 - Circuit leakage of ring oscillators built up from a library standard cell (Inverter) vs. Performance for different VDD and temperature. Small symbols show die-fine measurement data, yellow triangles denote model values (Si was not well centered to target)

6.3 28nm Model-Hardware-Correlation (MHC) results

Most advanced 28nm technology nodes feature high-k gate dielectrics instead of silicon dioxide and a metal-dominated gate stack instead of the polysilicon gate stack previously employed (HKMG). Both of these changes can have an impact on temperature behavior. The high-k dielectric can result in a different surface (fixed charge) scattering, which shifts the balance between the different channel scattering mechanisms, which in total determine the overall mobility. In contrast to a poly-Si gate, a metal gate does not develop a carrier depletion zone when biasing the device in the on-state. Thus there will be no change of extension with temperature due to the higher availability of free charge carriers. The V_t shift with temperature is stronger than in a depletion-zone-containing gate stack.

Temperature behavior on device level was assessed and models were fitted to hardware data. For the early 28nm hardware, BSIM models were extracted, while later with more mature hardware models were based on PSP in order to benefit from the advantages of using local models in temperature behavior extraction. In older technologies (45/40nm and 90nm), the model basis was exclusively BSIM.

6.3.1 Test structures

Dedicated test structures were designed and put onto the 28nm test vehicle in order to assess device behavior on a low (i.e. pure device) level. Test structures included single-device structures (Figure 73), capacitance structures (Figure 74) and ring oscillator structures (Figure 75), with the most likely environment, i.e. adjacent structures resembling typical layout in fully fledged circuits.

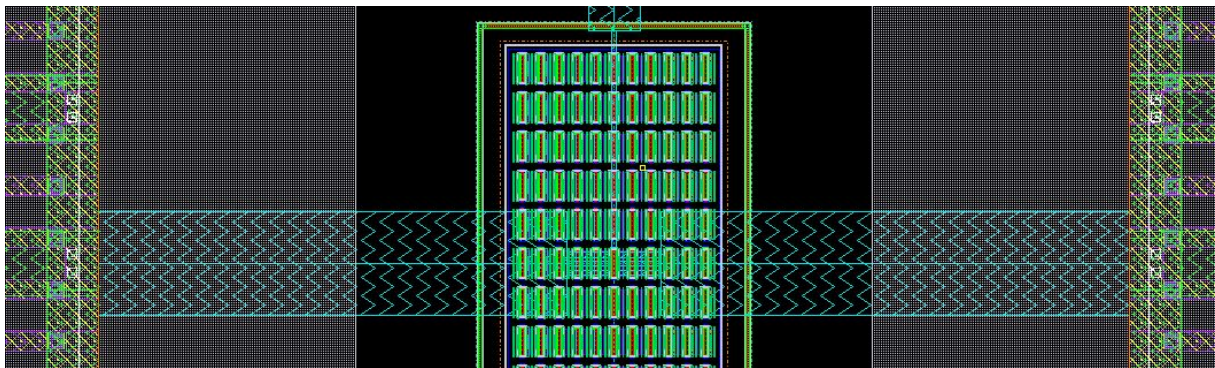


Figure 73 Single device (low V_t NFET) test structure with environment consisting of pitched devices of same geometry and polarity. The wide metal wiring reduces parasitic voltage drops and thus give unbiased access to the device characteristics.

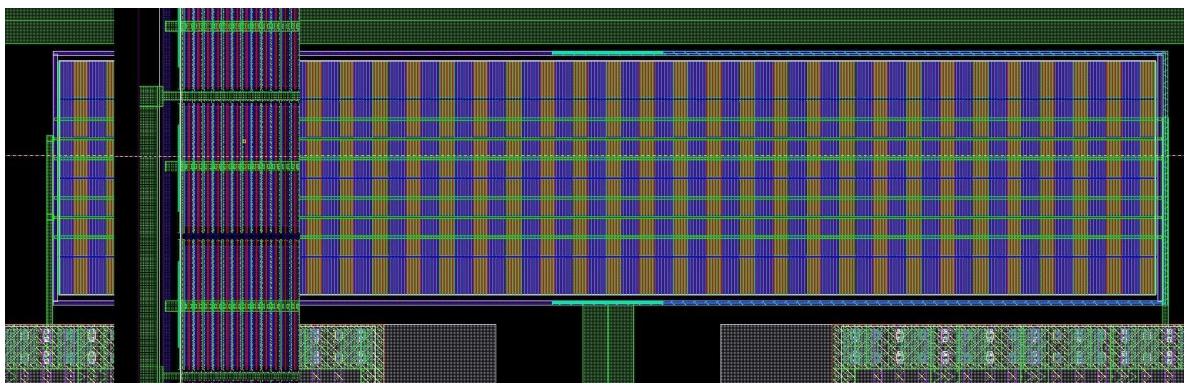


Figure 74 28nm capacitance test structure of devices at nominal length and at high multiplicity to achieve a total capacitance of a few pF, suitable for accurate CV measurements.

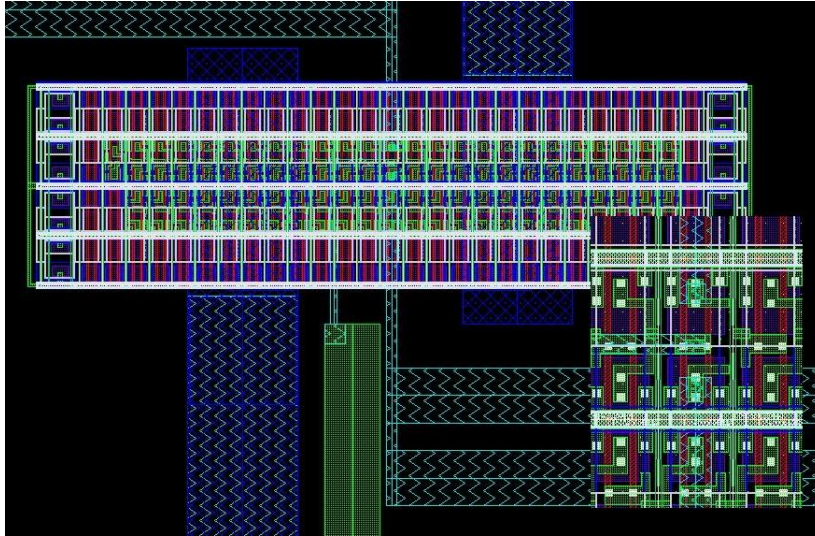


Figure 75 - Fully functional ring oscillator test structure as found on the 28nm test vehicle. The ring oscillator consists of 49 inverter stages with one dedicated oscillation-enabling stage.

6.3.2 Findings

For both, low V_t n-FET (LVTNFET) and low V_t p-FET (LVTPFET) in 28nm HKMG technology, the models are in good agreement with hardware temperature behaviour (Figure 76, Figure 77). For both device types and both nominal and long gate lengths, there is a pronounced temperature dependence of V_{tlin} and V_{tsat} : Over the full temperature range of -40 to 125 °C, the V_t decreases by about 160mV for the LVTNFET and about 170 to 210mV for the LVTPFET. The most crucial parameter of these devices is I_{dsat} (drain current in “on” state), which is impacted by two effects: The V_t reduction at higher temperatures causes an increase of I_{dsat} as the effective gate voltage (applied gate voltage minus threshold voltage) increases. On the other hand the mobility decreases with increasing temperature due to the increased phonon scattering experienced by the charge carriers in the channel. For electrons, the scattering dependence on temperature is slightly stronger than for defect electrons (holes). Design specifications require the designer to assure the full functionality of the respective circuits over the whole temperature range. One of the most crucial aspects in digital designs is the switching speed, typically expressed as ring oscillator frequency, or delay per stage. The designer has to verify that the circuits reach at least the required minimum speed at all temperatures. Thus, a strong temperature dependence of the involved devices renders the designer’s job more difficult and can make circuit balancing more challenging. While the specified metrics can be very comprehensive, the most relevant metric is the speed, which depends on both VDD and temperature. Due to the temperature effects changing their balancing with temperature their total effect can reverse when changing VDD, so there is a VDD point in between without temperature dependence. This point is referred to as “temperature inversion point” and will tell the designer at which VDD they can expect to see no or only negligible temperature dependence of circuit speed.

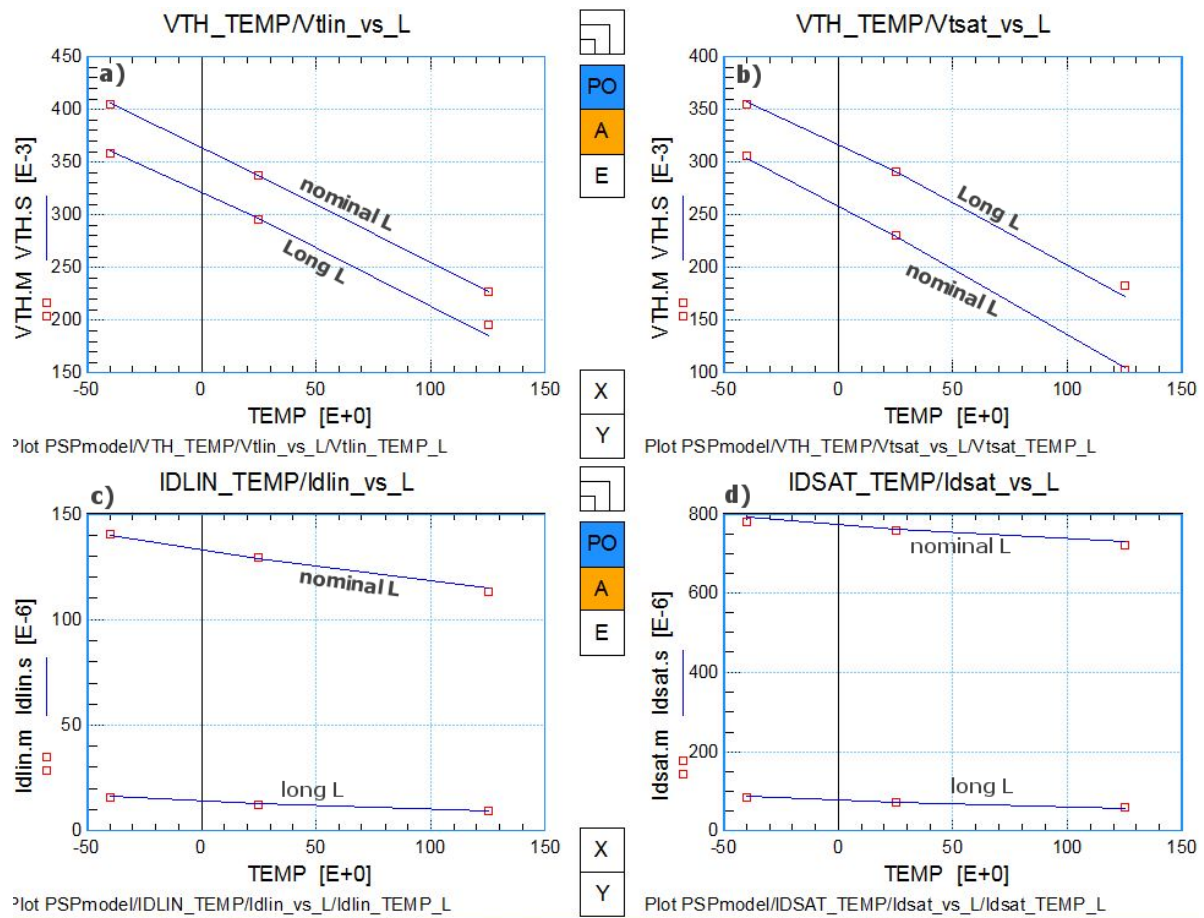


Figure 76 - Temperature behaviour of key device parameters for 28nm HKMG LVTNFET device. a) Vtlin, b) Vtsat, c) Idlin, d) Idsat. Model behaviour (blue lines) is in good agreement with measurement data (red squares). Due to the dominating effect of Vt over mobility temperature behaviour, Idsat decreases with increasing temperature.

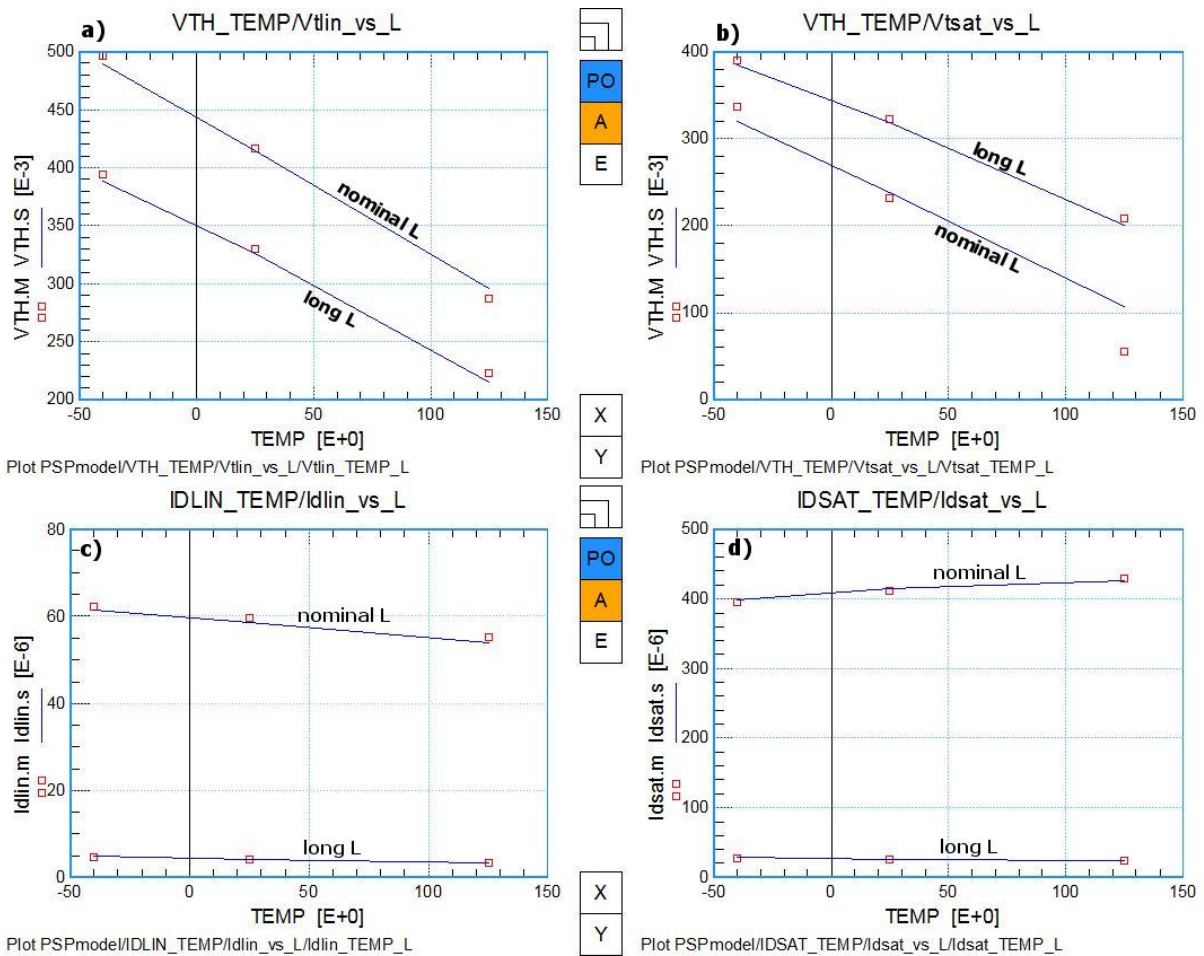


Figure 77 - Temperature behaviour of key device parameters for 28nm HKMG LVTPFET device. a) V_{tlin} , b) V_{tsat} , c) I_{dlin} , d) I_{dsat} . Model behaviour (blue lines) is in good agreement with measurement data (red squares). Due to the strong hole mobility temperature dependence, which exhibits a strong increase with T, the effect of V_t drop is overcompensated and I_{dsat} increases with temperature for short device lengths.

The cross-technology comparison shows that at previous technologies, one would see e.g. in 90nm technology a temperature inversion point of about 0.85V (Figure 78), which is below the nominal VDD of typically 1.0V. Both at high and low temperature, the model accurately predicts hardware behaviour (delta less than 2%). The blue line (-30 °C) shows that for $VDD > 0.85$, the ring oscillator is running faster (less delay) than at room temperature. At high temperatures the ring oscillator is running slower. The effects is more pronounced at higher VDDs, reaching a total delta of about 10% slower at 125 °C and 5 % faster at -30 °C. For low VDD, there is less effect as the devices are being operated closer to their respective threshold voltages, thus rendering the V_t vs. T behaviour the dominating one. The temperature inversion point (VDD for which there is no temperature dependence seen) for ring oscillators with nominal gate length is found for very low VDD at around 0.85V.

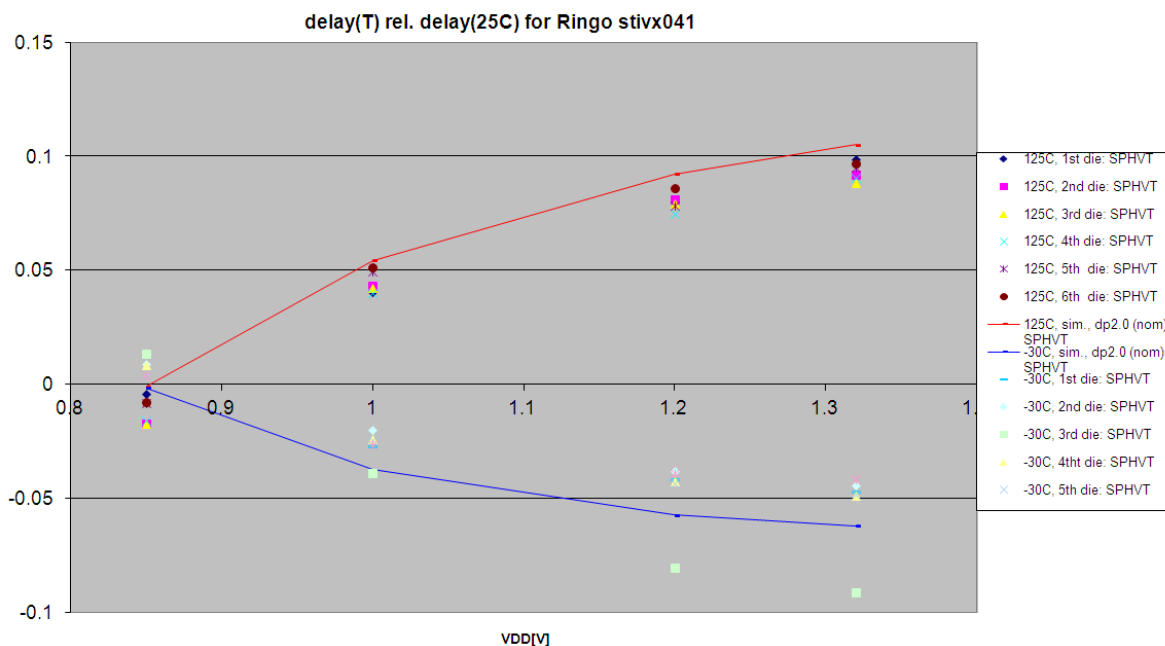


Figure 78 Delay of 90nm technology ring oscillators plotted as relative delay differences with respect to room temperature delay. Hardware data as symbols, model results as lines.

In 40nm technology, the temperature inversion point is found at about 1.0V for regular-Vt devices and 1.1V for high-Vt devices (Figure 79) while the nominal VDD is 1.1V. This behaviour is expected as the devices in both regular-Vt and high-Vt ring oscillators need about the same effective gate voltage overdrive (gate voltage minus Vt) to compensate the mobility effect.

At low VDD, the frequency increases with temperature, as the temperature behaviour of Vt dominates the device performance over the mobility behaviour. With increasing VDD, the mobility effect (reduction of mobility with increasing temperature) is getting stronger and dominates at high VDD.

Thus, 40nm designs have the benefit of having a very benign temperature effect at the most typical circuit supply voltages, which helps in building reliable designs (being functional over the whole temperature range). In 28nm technology, one will find the temperature inversion point at about 1.1V (fig 3.11) while the nominal VDD is 1.0V, so a standard design using nominal VDD will see a slight increase of speed with temperature - opposite to earlier technologies as 90nm mentioned above where a decrease of speed with temperature is observed.

Thus, an accurate reflection of temperature behaviour has more impact on 28nm designs than for the previous generation of 40nm designs.

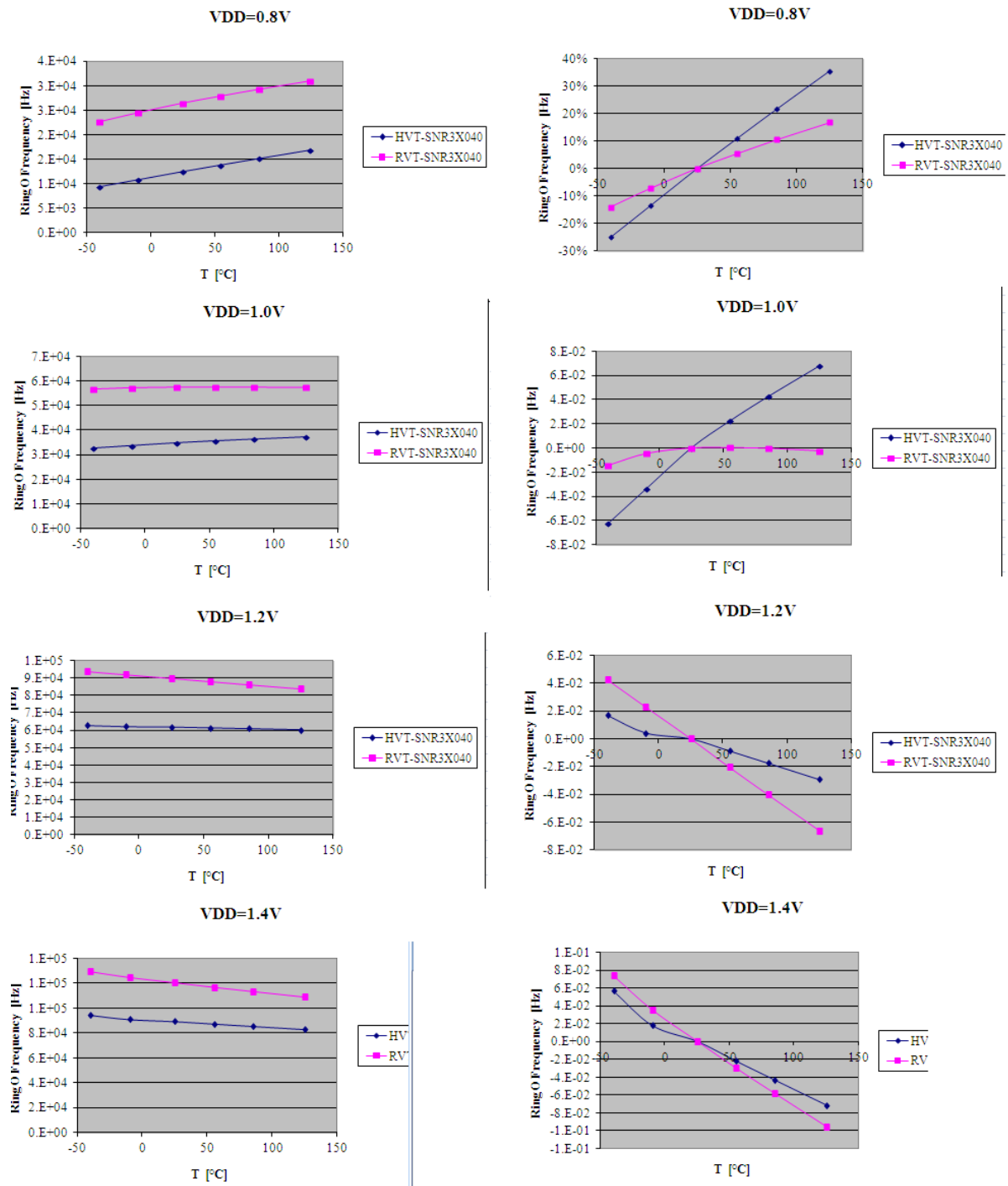


Figure 79 Ring oscillator frequency vs temperature for different VDDs in 40nm technology. High-Vt devices in blue, regular Vt devices in pink. Left column: absolute frequency vs T, right column: relative frequency difference with respect to room temperature frequency. Top to bottom: Increasing VDD of 0.8V, 1.0V, 1.2V and 1.4V.

Figure 80 shows in 28nm technology the ring oscillator frequency as function of temperature for different VDDs. Measurement data are compared with BSIM models on the one hand, and

with PSP models on the other hand. The PSP models, which have been extracted with taking advantage of PSP’s local model support, give a better fit to hardware than the BSIM models in the most relevant temperature range up to 85 °C. Overall, the difference between hardware and PSP models is less than 5%.

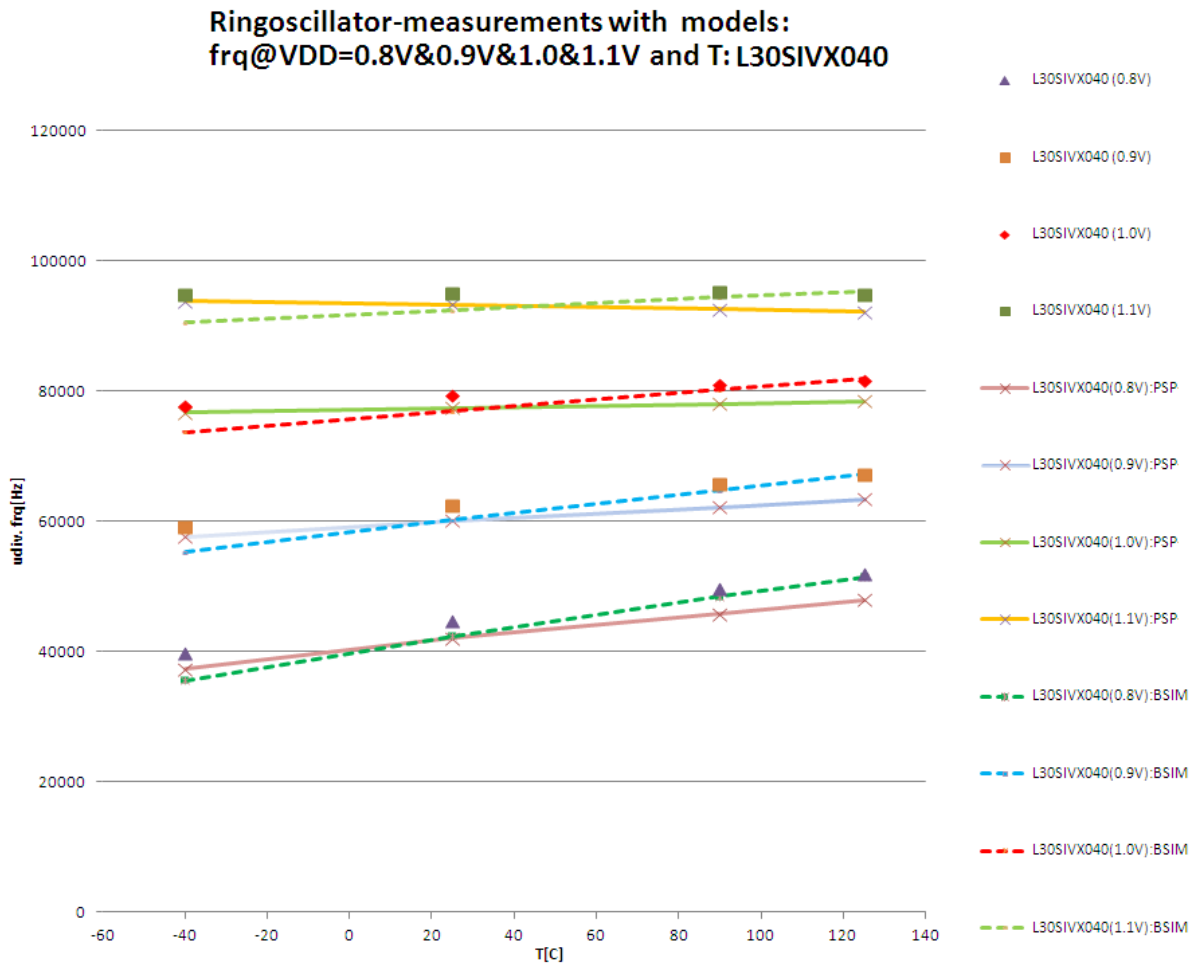


Figure 80 28nm ring oscillator frequency [a.u.] vs. temperature for different VDDs. Symbols: measurement data, dashed lines: BSIM models, solid lines: PSP models.

Figure 81 shows the same comparison measured data vs. the two model approaches for the leakage currents of ring oscillator versus temperature for different VDDs. The increase of leakage with temperature is substantial, over the full temperature range of -40 to 125 °C, an increase of three orders of magnitude is observed. The trend is accurately reflected in the models, while the slight delta between measurement and models is a consequence of the hardware not being fully on target.

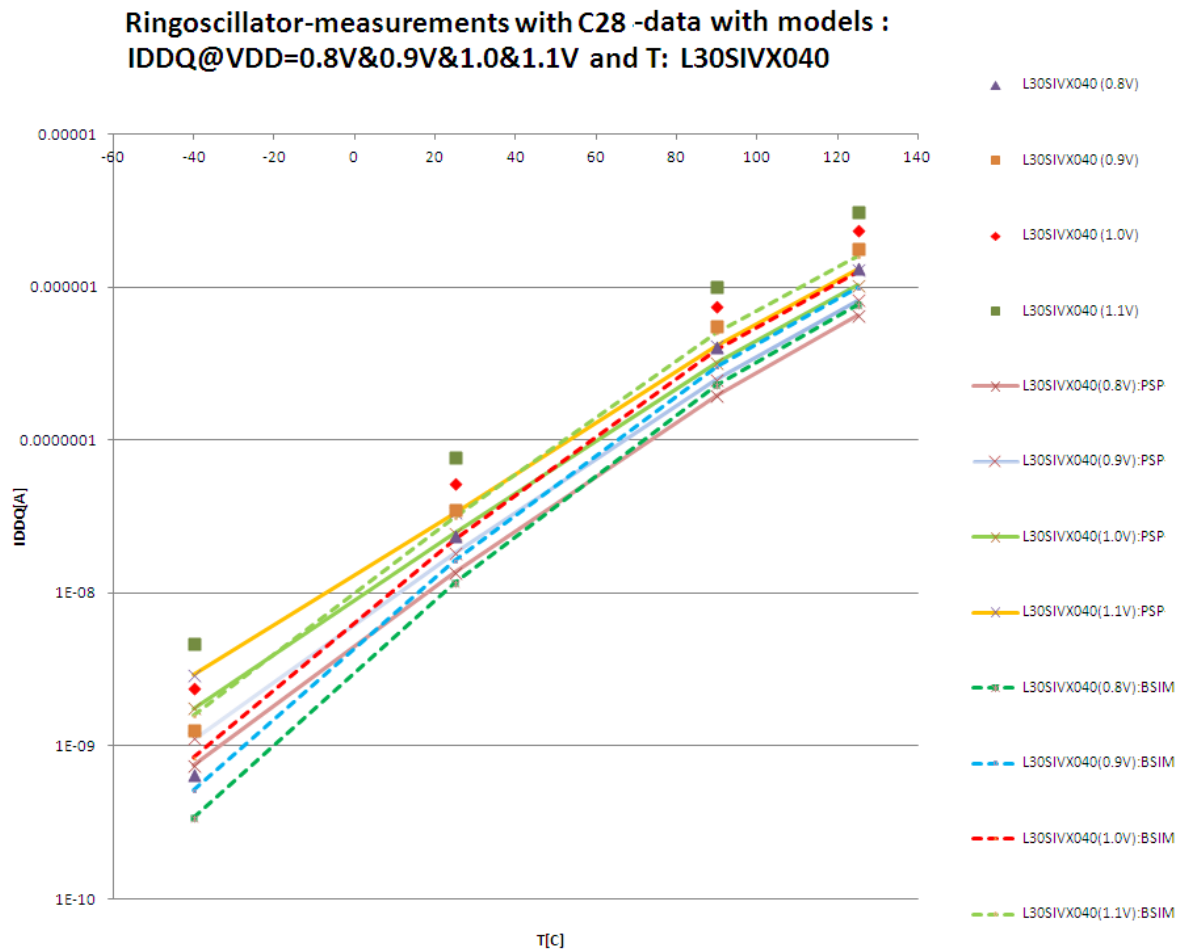


Figure 81 - Leakage current of ring oscillator versus temperature for different VDDs. Symbols: measurement data, dashed lines: BSIM models, solid lines: PSP models.

In Figure 82 the ring oscillator speed (delay/stage) is compared for two different ring oscillator architectures (left and right panel) as function of VDD for four different temperatures. The PSP models give a better fit to measurement data than the BSIM models, with the difference between data and PSP models below 3 % (right panel). At low VDD, the temperature impact is strong, with a difference of about 15 % in delay. With higher VDD, the impact is reduced and reaches the point of no temperature impact (temperature inversion point) at a VDD of 1.1V.

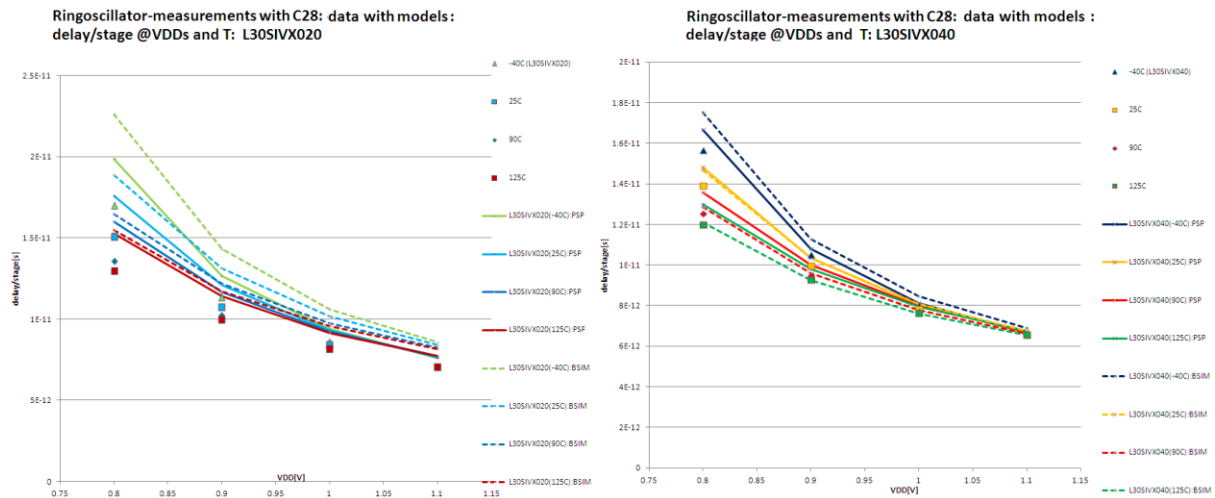


Figure 82 - Ring oscillator speed (delay/stage) for two different ring oscillator architectures (left and right panel) vs VDD for four different temperatures.

In Figure 83 the measured 28nm ring oscillator frequency is plotted as function of Vdd for different temperatures. As mentioned earlier already the temperature inversion point (VDD at which no temperature dependence is observed) is found at 1.1V, i.e., above the nominal VDD of 1.0 V. Regular designs, which employ nominal VDD, will see that higher temperatures lead to faster circuits.

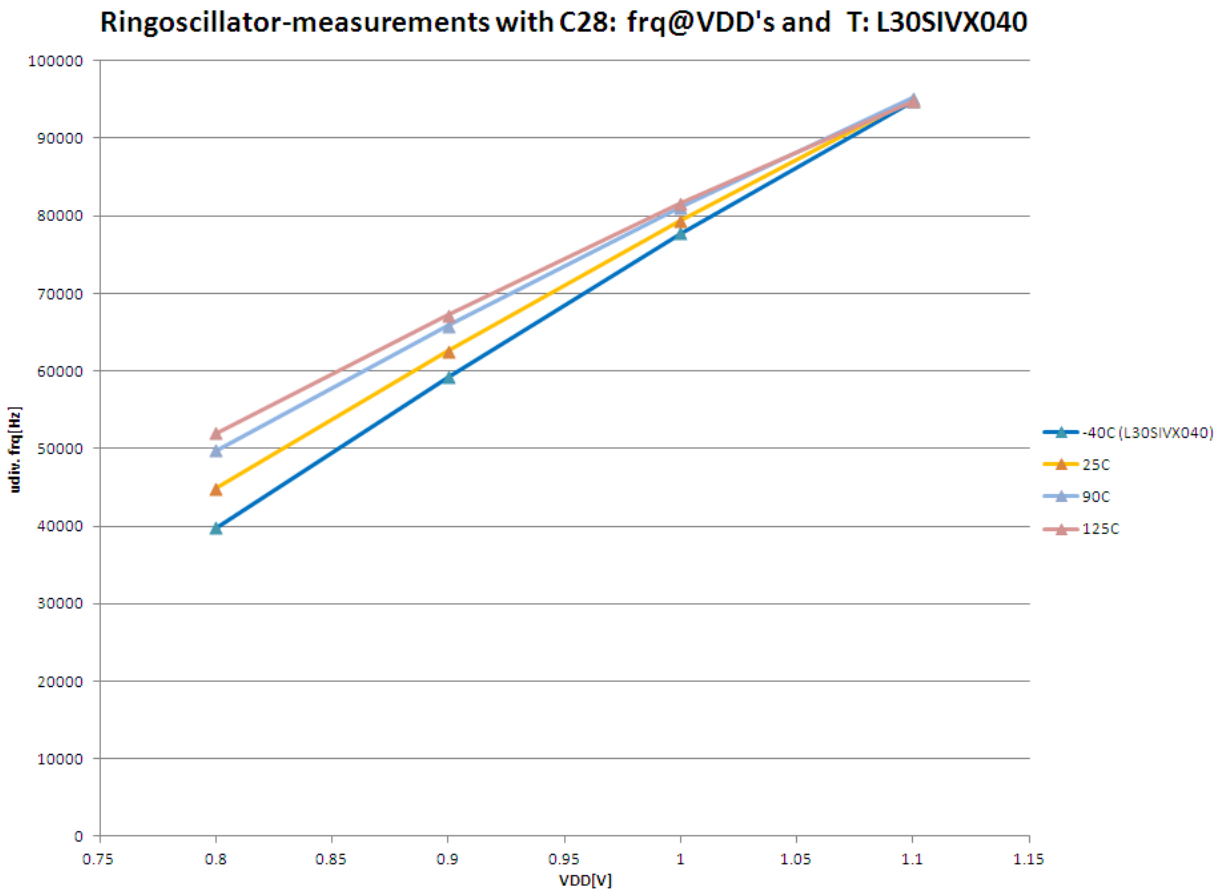


Figure 83 - Measured 28nm ring oscillator frequency [a.u.] vs. Vdd for different temperatures.

Figure 84 shows the relative difference between model and measurement data for 28nm ring oscillator frequency as function of temperature at different VDDs. The new PSP methodology exhibits a much smaller delta between measurements and simulation results than the previous models. The pure temperature effect is very well reflected in the PSP models (solid lines running predominantly horizontal, less than 2.5% delta, better than with previous methodology, which resulted in up to 10% delta), and the overall PSP model accuracy, which also covers VDD dependence and centering accuracy, is better than 8%.

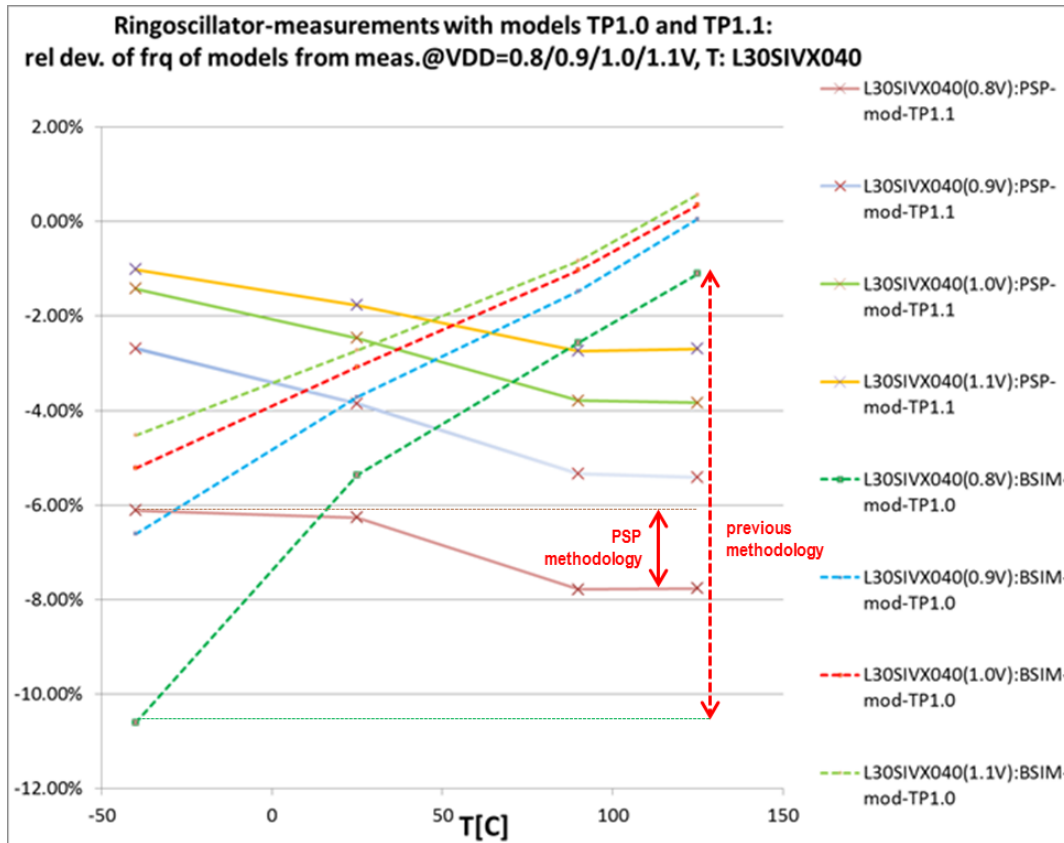


Figure 84 - Relative difference between model and measurement data for 28nm ring oscillator frequency vs. temperature at different VDDs. Dashed lines: previous, device-based methodology, solid lines: advanced, circuit-referenced PSP models.

6.4 Conclusions

New modelling capabilities to support accurate thermal analysis and simulation have been developed in the scope of WP1 and WP2. In this deliverable, models for advanced 40nm and 28nm technologies have been extracted and qualified with respect to hardware measurements on both device and circuit level.

As a consequence of the gate stack changes and reduced nominal gate length, 28nm exhibits a stronger temperature dependence between long and short devices than 40nm. Thus, an accurate temperature modelling is becoming more important from 40nm to 28nm and with further scaling.

In 28nm we have leveraged the advantage of employing a circuit-referenced temperature modelling methodology with the local model approach of PSP to increase the model accuracy over the full required geometry and temperature range. This novel PSP-methodology has lead

to a more accurate reflection of hardware behaviour than the previously used approach. Therefore, respective temperature models have been rolled out as part of the full-custom as well as semi-custom design flow to safeguard designs and to fulfil temperature specs of advanced products. The improved models allow to control, manage and compensate thermally induced effects on parameters such as timing and power; they positively impact reliability and yield.

The models have been proven to provide good accuracy on test chips and reference designs. As a consequence, they serve as basis for productive designs now.

The new circuit-referenced methodology exhibits smaller deltas between measurements and simulation results than the previous models. The quantifiable objective “deviation between measurement and model/simulation less than 20%” has been well achieved with ring oscillator frequencies in both technologies, 28 and 40nm - showing an effective delta of about +/- 2% over the whole temperature range of -40 to +125 °C.

7 TCAD of advanced and future MOSFETs (FHG, together with IMC)

7.1.1 Introduction

In Task 2.1, reported in deliverable D2.1.4 [7], Fraunhofer IISB investigated the self-heating of advanced SOI based MOSFETs and extracted compact models for a novel CMOS generation envisaged by the ITRS for 2015. The results on self-heating of advanced CMOS transistors were found to depend on the thermal conduction in the thin layers of silicon in which the transistors are realized and in the other materials that surrounds them. In the novel CMOS transistors, high-k-dielectrics are used instead of silicon dioxide. Also the CMOS transistors of the newest technology generation with 28 nm gate length used by IMC in the demonstrator circuits (Testcase 3) in this project have a gate isolation made from high-k-dielectrics. Therefore, the effect of high-k-dielectrics, which are the choice for the gate dielectrics for the future CMOS generations, on thermal properties of CMOS transistors had to be investigated. The effect of high-k-dielectrics was studied here in Task 7.1 by means of numerical simulation.

7.2 Impact of high-k gate isolation on temperature sensitivity of advanced MOSFETs

Identical geometrical shape and doping can easily be realized in numerical simulations, so that the effect of the material used for gate isolation can be studied separately from other factors causing differences in the thermal behaviour. Since an evaluation of the future CMOS technology generations is an important goal of this project, we took as an example of an advanced CMOS future technology the SOI based CMOS technology generation specified by the ITRS for 2015.

According to the ITRS [8], the gate length of CMOS transistors for 2015 will be 17 nm, the silicon body thickness in fully-depleted single-gate SOI-based transistors 5.5 nm, the supply voltage 0.81 V. We used the specifications of the 2009 version of the ITRS to allow a direct comparison to the results of D2.1.4 where the same specifications were used. Since the active area of SOI transistors is isolated from the silicon substrate by the buried silicon oxide layer, a larger self-heating effect is expected in SOI transistors compared to their bulk silicon counterparts. The upper part of the silicon body in SOI transistors is in an immediate thermal contact to metallic source and drain contacts. However, the channel region in CMOS transistors is separated from the metallic gate electrode by the thin gate isolation. While the traditional gate isolation was made from silicon dioxide, high-k-dielectric materials are used as gate isolation in novel CMOS technology nodes. Hafnium dioxide, HfO_2 , is a typical high-k-dielectric used in advanced CMOS transistors and we used this high-k-material in our simulations as an example of high-k-gate dielectrics. To separate specific effects induced by HfO_2 from other possible influences associated with the size of transistor elements and with the doping, completely identical sizes and doping of the devices were used except for the physical thickness of the gate dielectrics. To ensure as close as possible similarity of electrical performance of the devices under comparison, equal effective electrical thickness of silicon dioxide and of HfO_2 gate dielectrics was chosen. In both variants of the simulation, the effective gate oxide thickness, which is the thickness of the standard silicon dioxide that gives the same electrical capacitance as the capacitance of the high-k-isolated capacitor, was 0.53 nm, as specified by ITRS [8]. This value of the effective gate oxide thickness does not include the effect of quantum-mechanical depletion of the charge carriers near the silicon-to-gate-isolation interface. The effects of quantum depletion will be accounted for in the electrical device simulations presented below. The geometrical shape of the simulated SOI

based transistors and their doping distribution resulting from process simulation using the Sentaurus Process simulator [3] are depicted in Figure 85.

The electronic transport in these transistors was simulated solving the drift-diffusion transport equations and accounting for several special effects that are important for the electronic transport in nano-scaled CMOS transistors as presented in details in deliverable D2.1.4 [7] of this project. The effect of quantum-mechanical depletion of electrons in silicon, which is a very important effect in nano-scale devices because it influences both the leakage and the on-current, was accounted in the simulations using the modified local density approximation (MLDA) implemented in the Sentaurus Device simulator [9].

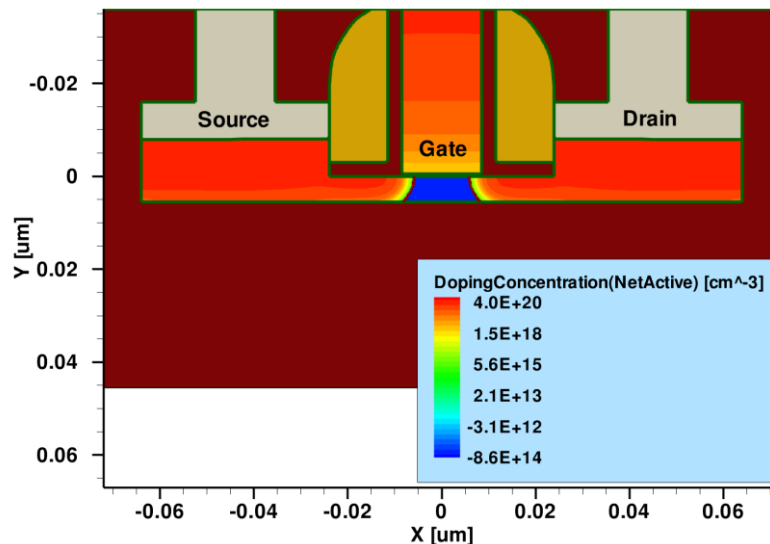


Figure 85: Simulated geometrical shape and doping distribution of a FD SOI NMOSFET as specified by the ITRS for the year 2015

The effect of self-heating in steady-state DC operation was accounted for by applying the Fourier equation for the heat transport in all regions of the transistors including both semiconductor material and isolation. For the thermal boundary conditions an environment temperature of 300 K was assumed. The thermal resistivities of the source, drain, and gate electrodes were calculated using approximate analytical models [10]-[11] that take into account that IC interconnects have a 3D nature and typically consists of many materials, for isolation, metal layers and plugs. The thermal conductivity of the silicon substrates was also calculated in advance using 3D simulations.

As it was shown in D2.1.4, it is very important in thermal simulations not to rely on the conventional thermal properties of materials compiled in handbooks but to use specific thermal properties of nano-scale layers. For example, the effective thermal conductivity of a 10 nm thick silicon layer is about 10 times lower than the thermal conductivity of a bulk silicon sample of macroscopic size [7]. Therefore, to study the differences in electrical and thermal behaviour of advanced CMOS transistors, we used the values of the thermal conductivities of silicon dioxide and of HfO_2 obtained from special measurements on nano-layers [12]. These measurements used thermal sensors in atomic force microscopy and measured thermal conductivity of the layers of thermally grown silicon dioxide with a thickness of 2 nm and of HfO_2 with a thickness of 3 nm on the surface of the silicon samples. The effective thermal conductivities of thin dielectric nano-layers extracted from these experiments were found to be 0.2 W/(K m) for SiO_2 and 0.27 W/(K m) for HfO_2 . These values for thermal conductivity of the gate isolation were used in the numerical simulations as mentioned above. Although the thermal resistivity of the gate isolation changes slightly when using HfO_2 , the overall effect of thermal resistivity modification on the self-heating in

advanced SOI based transistors is small because of the small thickness of the gate dielectric layer. Figure 86 shows a comparison of the temperature distributions inside of the advanced SOI-based NMOSFETs.

The maximum temperature due to self-heating amounts to 520 K near the drain-side edge of the channel in conventional NMOSFETs with silicon dioxide gate isolation and to 508 K in NMOSFETs with HfO₂ gate isolation. The difference in the maximum temperature amounts to only 12 K and the transistor with HfO₂ isolation has a lower temperature. Actually, due to a larger thickness of HfO₂ that is needed to obtain the same gate capacitance in comparison to SiO₂, there is a somewhat higher thermal resistivity between the channel and metal part of the gate electrode. This effect could lead to a certain increase of the self-heating but its influence is small because of the small thickness of the gate isolation in these devices.

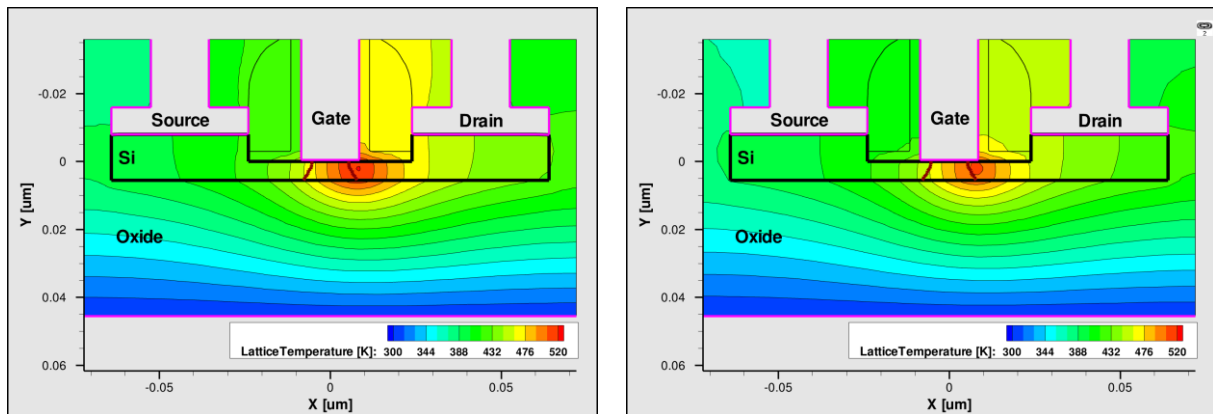


Figure 86: Temperature distributions due to self-heating in the on-state for the fully-depleted SOI MOSFET with a gate length of 17 nm. Left: Silicon dioxide gate isolation; right: HfO₂ gate isolation.

On the other hand, there are specific electrically active defects at the interface between the silicon and HfO₂ in HfO₂-gate-isolated transistors. The impact of these HfO₂-specific defects on the electrical behaviour of transistors was simulated in this work by two models, recently implemented in Sentaurus Device [9]: 1) Coulomb-type scattering of electrons at the immobile charges trapped at the HfO₂-to-silicon interface; 2) electron scattering at the special kind of phonons propagating in HfO₂ along the surface. Due to more intensive charge carrier scattering, a lower on-current results in HfO₂ transistors. And just this effect strongly dominates and is mainly responsible for the difference of the self-heating in the transistors with high-k gate dielectrics in comparison to those with silicon dioxide isolation.

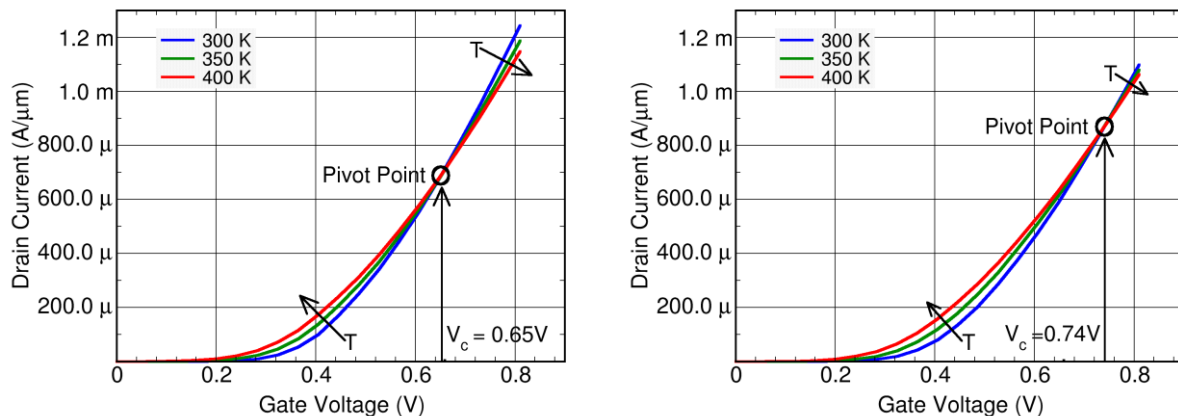


Figure 87: Transfer characteristics at drain voltage of 0.81 V for the fully-depleted SOI MOSFET with a gate length of 17 nm. Left: Silicon dioxide gate isolation; right: HfO₂ gate isolation.

Also due to the specific temperature dependence of the above mentioned scattering

mechanisms in transistors with HfO₂ gate isolation, the temperature dependence of the transistor current is modified. This effect is illustrated by Figure 87.

For the conventional MOS transistor with SiO₂ gate isolation, the temperature dependence of the transfer characteristics is shown in the left part of Figure 87. There is a pivot point in the transfer characteristics that corresponds to a gate voltage at which the drain current remains temperature independent. At lower gate voltages, the drain current increases with temperature, at higher it decreases. As it can be seen in the right part of Figure 3, such a pivot point is also observed for MOSFETs with HfO₂ isolated gate, but at a higher gate voltage of 0.74 V in comparison to 0.65 V for the conventional MOSFET. The physical reason for the higher gate voltage of the pivotal point of the transfer characteristics is the additional carrier scattering at the surface-trapped immobile charges and at HfO₂ specific phonons in transistors with HfO₂ gate isolation.

For an application-related characterization of the temperature effects, the temperature dependence of a so called effective current of a MOS transistor is relevant. The effective drain current is defined as a drain current averaged over gate and drain voltages according to the formula: $I_{D_{eff}} = [I_D(V_G=V_{DD}/2, V_D=V_{DD}) + I_D(V_G=V_{DD}, V_D=V_{DD}/2)]/2$. Here, V_{DD} is the supply voltage and V_G and V_D are voltages at gate and drain electrodes, respectively. Figure 88 shows the temperature dependence of the effective drain current for an advanced SOI NMOSFET as specified by the ITRS for the year 2015. Left is the result of the simulation for the NMOS transistor with conventional silicon dioxide isolation, right is the result for the same transistor with HfO₂ gate isolation. The supply voltage that results in a temperature independent effective current is 0.79 V for a conventional MOSFET and 0.94 V for a MOSFET with HfO₂-isolated gate. The pivot point voltage for effective drain current for the conventional transistor is very close to the supply voltage of 0.81 V recommended by the ITRS for 2015. On the other hand, the supply voltage for HfO₂ based transistors at which a temperature independent performance is expected is higher and amounts to 0.94 V. This somewhat higher voltage can be recommended for novel MOSFETs with a gate length of 17 nm with high-k gate isolation.

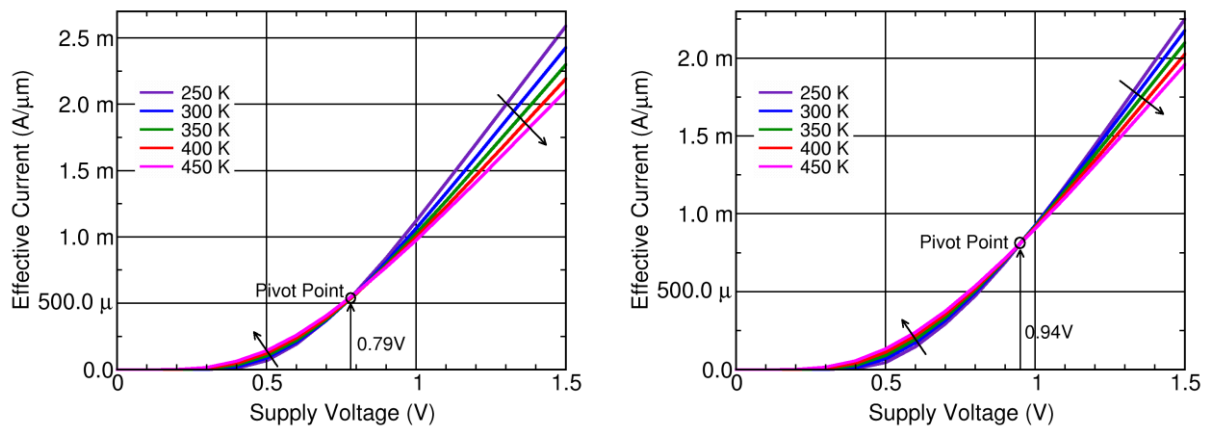


Figure 88: Effective drain current at different supply voltages for the fully-depleted SOI MOSFET with a gate length of 17 nm. Left: Silicon dioxide gate isolation; right: HfO₂ gate isolation.

Table 1 summarizes and compares the results on the temperature dependence of the main performance parameters of advanced MOSFET transistors. The first two lines of the table present experimental results obtained at IMC **Error! Reference source not found.** for NMOSFETs with gate lengths of 45 and 28 nm, respectively. The notation LVT means that a low threshold voltage high performance version of the MOSFETs was considered. The 45 nm MOSFETs have a SiON gate isolation while 28 nm MOSFETs have a high-k gate isolation. The third line shows the results of the simulations performed at IISB in task 7.1.1 for 28 nm bulk silicon MOSFETs that are similar to those used in experiments of IMC. HfO₂ was

assumed as gate isolation material in these simulations and the same simulation models as presented before for 17 nm SOI transistors were used. The two last lines present the simulation results of Fraunhofer IISB for the 17 nm gate length fully-depleted SOI-based n-channel MOSFETs. The third line is for conventional silicon dioxide gate isolation and the last, fourth, line is for the same kind of transistor but with a HfO₂ gate isolation.

Three temperature-related parameters that describe the evolution of the performance of the transistors with temperature are tabulated. The first parameter is the V_{tsat} *Temperature Coefficient* (VTC). This coefficient characterizes how much the threshold voltage of the transistors changes when the temperature increases by 1 K. Negative values mean that the threshold voltage lowers when the temperature increases. It is interesting to note that the VTC for novel 17 nm SOI based transistors with the traditional silicon dioxide isolation is equal to the VTC of 45 nm bulk silicon MOSFETs. Such a good agreement in the VTC for transistors with different gate lengths is expected because the VTC parameter is mainly determined by the silicon properties and the impact of the interface-located defects on scattering of the charge carriers is negligible in these transistors. In contrast, both transistors with high-k-gate-isolation exhibit somewhat higher values of VTC.

Table 1: Temperature sensitivity parameters for advanced NMOSFETs

Device Type	Gate Isolation	Gate Length (nm)	V_{tsat} Temperature Coefficient (mV/K)	On-Current Temperature Coefficient (%/100K)	Eff. Current Temperature Coefficient (%/100K)
LVT NFET	SiON	45	-0.47	-5.88	-2.4
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LVT NFET [5]	High-k	28	-0.65	-2.35	1.2
LVT NFET Sim.	HfO ₂	28	-0.52	-3.39	1.75
FD SOI NFET	SiO ₂	17	-0.47	-4.50	-1.05
FD SOI NFET	HfO ₂	17	-0.49	-1.73	5.98

The second temperature-related parameter is the *on-current temperature coefficient* (OCTC) and shows how much the on-current changes when the temperature increases by 100 K. This coefficient takes typically negative values and reflects the degradation of the charge carrier mobility due to the increase of scattering at thermal vibrations with increasing temperature. Comparing the oxide-isolated and high-k-isolated gates we observe that transistors with high-k-isolated gates have significantly lower absolute values of the on-current temperature coefficient. There is also a slight reduction of the absolute value of this coefficient with a reduction of the gate length, compare lines 2 and 5 of Table 1. This can be explained by the fact that in transistors with shorter gate length the relative role of the parasitic resistances, which are essentially temperature independent, increases. Observing this we can conclude that the effect of the on-current degradation with temperature diminishes for the future generations of CMOS transistors, partly because of shorter gate lengths and partly because of the high-k-dielectrics.

The third temperature-related parameter is the *temperature coefficient for the effective drain*

current (*ECTC*). This coefficient indicates by how many percent changes the effective drain current when temperature increases by 100 K. Since the effective drain current determines the switching velocity of the transistors in a circuit, near zero values of this coefficients are attractive for many applications. Here we should notice that measurements performed at IMC showed that this coefficient change its sign from negative for 45 nm bulk silicon MOSFETs with SiON gate isolation to positive for 28 nm bulk silicon MOSFETs with high-k gate isolation. Therefore, the question arose whether this sign change is because of the gate-length reduction or because of the new gate-isolation material. Comparing the results tabulated in the last column of Table 1 we see that for both transistors with high-k gate isolation a positive temperature coefficient for the effective drain current is observed. The positive values of this coefficient are seen both in experiment and in simulation for transistors with high-k gate isolation. We explain this by the contribution of the additional charge scattering during the electron transport in transistors with high-k-gate dielectrics.

A relatively high value of the temperature coefficient for the effective drain current as shown in Table 1 for 17 nm NMOSFET with HfO₂ gate isolation is not a real challenge for the application of future CMOS. In fact, as we can see from Figure 88, this coefficient can be reduced to values close to zero if instead of the recommended supply voltage of 0.81 V a supply voltage of 0.94 V is used. Generally, because of the new scattering mechanisms of the charge carriers in MOSFETs with high-k-isolated gates, higher supply voltages in comparison to thermal-oxide-isolated gates should be considered to take advantage of a low temperature dependence of the transistor performance.

To evaluate the accuracy of the simulation models in respect to their capability to predict the trends in device performance for changing temperature conditions, we compare here the results presented in lines 2 and 3 of Table 1. Let us assume that due to self-heating or due to external conditions temperature increased by 100 K. Taking the temperature sensitivity coefficients from Table 1 we can estimate how this change of temperature modifies the basic performance parameters of the transistors. The most important parameters of an MOS transistor are the threshold voltage and the effective drain current that determines the switching speed of the transistor. To estimate the difference between the simulation prediction and the measurement result for the threshold voltage ΔV_{tsat} we take the difference of VTC coefficients from lines 2 and 3 and multiply the result by 100 K: $\Delta V_{tsat} = 13$ mV. If the nominal threshold voltage is 0.3 V then the difference between prediction and measurement for V_{tsat} will be: $100 \cdot 13 / 300 = 4.3\%$. In a similar manner, the difference between prediction and measurement for the effective drain current can be calculated. Taking into account two independent sources of deviation due to deviation of V_{tsat} and due to deviation in *ECTC*, the result for the deviation of effective current prediction is $\Delta I_{eff} = [(I_{eff} \cdot dI_{eff}/dV_{tsat})^2 + (\Delta ECTC \cdot \Delta T)^2]^{1/2} = 5.8\%$. The average accuracy of the model can be estimated as the mean squared average of ΔV_{tsat} and of ΔI_{eff} and it amounts to 5.1%. This value is inside of the accuracy range of 10% required by the measurable criterion MO7.1.11 of model accuracy in Testcase 3.

7.2.1 Conclusions

The comparison of the temperature-related coefficients of the three CMOS generations can be summarized as follows:

- The threshold voltage of all transistors considered lowers when the temperature increases. The temperature dependence of the threshold voltage of MOSFETs with silicon oxide isolation remains constant, independent on gate length scaling.

MOSFETs with high-k gate isolation have a tendency to a higher temperature sensitivity of the threshold voltages.

- When transfer characteristics of MOSFETs at different temperatures are compared, there is a pivot point at a certain gate voltage at which the drain current is temperature independent. At lower gate voltages the drain current increases with temperature, at higher it decreases. The gate voltage corresponding to the temperature-independent drain voltage is higher for MOSFETs with high-k gate isolation. This is the effect of the charge carrier scattering at immobile charges trapped at the high-k-to-silicon interface and at high-k-material-phonons.
- The temperature dependence of the effective drain current which determines the switching speed of the transistors is similar to that of the transfer characteristics. At low supply voltages, the effective drain current grows with temperature, at higher supply voltages it diminishes with the temperature. There is also a pivot point at which the effective current is temperature independent. The optimum supply voltage at which a near zero temperature sensitivity is observed is higher for MOSFETs with high-k gate dielectrics in comparison to MOSFETs with silicon oxide isolation.
- The predictions of the simulations for the temperature sensitivity of future CMOS generations continue the trends observed in experimental measurements of this project, quantify the temperature sensitivity for future SOI based CMOS generations and elucidate the difference in the temperature sensitivity of MOS transistors with the silicon oxide and the high-k gate dielectrics.

8 DC and AC thermal-characterization of FinFETs (UNIBO)

8.1 Introduction

This part of the deliverable compares the results of numerical device simulations accounting for self-heating, with the results of experimental DC and AC characterization of small geometry MOSFETs. This activity is performed within WP7, with the aim to confirm the accuracy of the simulation procedure developed by UNIBO in the frame of WP2, and applied to the analysis of the impact of self-heating on the figures of merit for AC and digital operation [13]; our declared measurable objective MO7.1.12 is a 10% maximum deviation between the results of simulations and available experimental data.

In particular, we present detailed DC and AC numerical simulations of thermal effects in nano-scale FinFET devices. Three-dimensional electro-thermal numerical simulations, including a realistic description of the source, drain and gate interconnections, are validated by comparison with experimental DC I-V and AC small-signal parameters. The importance of a realistic description of interconnect in AC simulations of FinFETs is discussed. The large frequency dispersion of AC parameters, suggests small signal analysis as a powerful method for the experimental characterization of self-heating effects, particularly in the case of low-power devices, for which the sensitivity of DC I-V curves to thermal effects is rather small.

8.2 Simulated devices

N-channel FinFET devices have been simulated using the Sentaurus device simulator[14]; the results obtained from measurements performed on similar devices are presented and widely discussed in [15].

Three different gate lengths have been considered: $L_G=1\ \mu\text{m}$, 190 nm and 70 nm. The main characteristics of the simulated transistors are listed in Table 2.

Table 2- Key parameters of the nominal device

Gate Work-function ϕ_G [eV]	4.4
Gate Oxide Thickness t_{OX} [nm]	1.8
Gate Oxide Dielectric Constant ϵ_{OX}	3.9
Fin Width W_{fin} [nm]	30
Fin Height H_{fin} [nm]	60
S/D Extension Length L_{ext} [nm]	35
Channel Doping Conc. N_{ch} [cm^{-3}]	10^{15}
S/D Doping Conc. $N_{S/D}$ [cm^{-3}]	10^{20}
BOX thickness t_{BOX} [nm]	50
Passivation layer thickness t_{PAS} [nm]	200
Inter-fins distance Δ_{fin} [nm]	200

The gate oxide thickness is uniform for the lateral gates and for the top gate; an abrupt junction is assumed between the S/D regions and the substrate. The device is covered by a SiO_2 passivation layer, whose thickness t_{PAS} is kept constant and equal to 200 nm. Beneath the BOX, a 1.8 μm thick Silicon layer is included in the simulation.

From a thermal point of view, the temperature distribution inside the transistor is a function of the fin position, the inner fins being hotter than the peripheral ones. In our case, the simulated structure is representative of an inner fin. Regarding the thermal

boundary conditions that have been adopted in our simulations, the source, drain and gate interconnects have been defined as metal wires; in particular, source and drain are designed as copper wires, featuring rectangular cross section and a length equal to the healing length, which is the characteristic length for exponential temperature attenuation due to heat exchange with the ideal sink through the insulator–semiconductor stack [16]. At the end of such wires, a 300 K isothermal boundary condition is set. These wires act as cooling fins, exchanging heat in the vertical direction, toward the substrate heat sink, through a stack of inter–metal insulator, BOX, and silicon substrate. Finally, the gate contact has been modeled as a poly-silicon wire, whose length is limited by the inter–fins distance (Δ_{fin} , see Table 2).

Figure 89 presents a simple sketch of the “intrinsic” simulated device: the interconnect is not shown. In Figure 90a, 2D-section of the whole simulation domain is described, including the metal wires, the passivation layer as well as the inter–metal dielectrics (IMD).

In order to correctly match the experimental data, parasitic series resistances have been added to the S/D contacts ($R_{S/D}=11.8 \text{ kW}$); moreover, the saturation velocity parameters have been calibrated for very short devices in order to account for velocity overshoot, according to the approach suggested by Bude[17]. Table 3 reports the values adopted for the different structures.

3D E–T simulations require a large computational burden, in terms of CPU time and allocated memory: in order to perform feasible tasks, quantum corrections are not taken into account.

Moreover, in order to minimize the node count of the structures, the simulation domain is one–half of the complete transistor (i.e. only $W_{fin}/2$ is considered). This is possible by exploiting the symmetries of the simulated structures. The silicon thermal conductivity κ_{Si} is treated as a decreasing function of film thickness and temperature according to the model proposed by Liu[18]. Moreover, the thermal conductivity of the gate oxide has been calibrated in order to take into account for surface effects at both the silicon–dielectric and dielectric–gate interfaces.

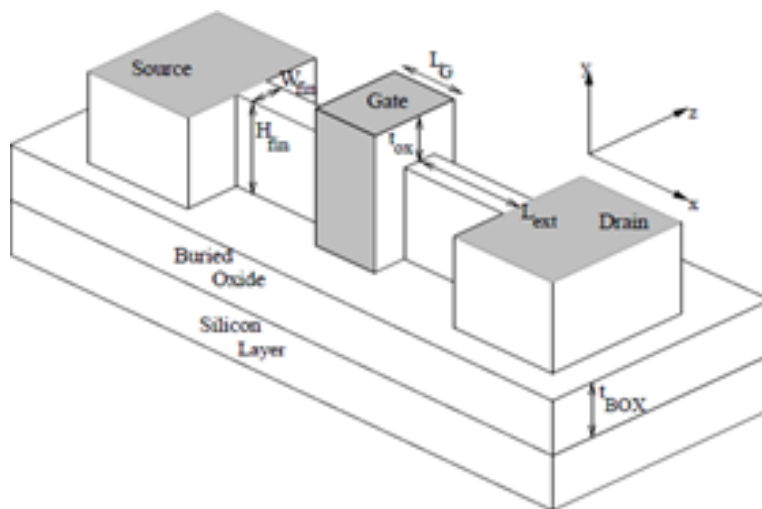


Figure 89-Simple sketch of the simulated FinFET. The does no show the metallization lines, and it is not in scale.

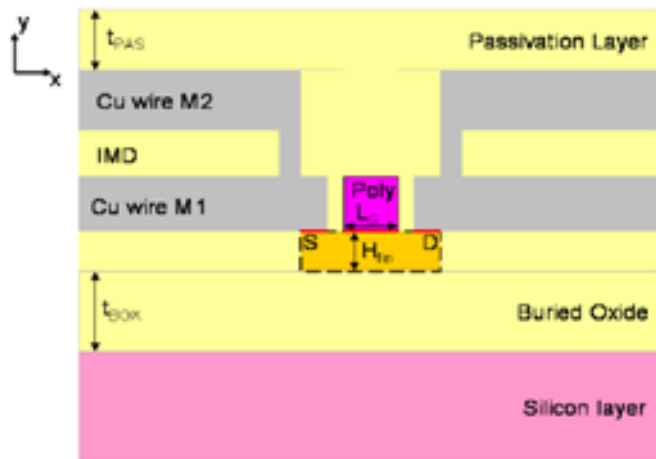


Figure 90- Cross section along the x-y plain of the whole simulation domain: the figure is not in scale. The yellow dashed—contoured region is the intrinsic FinFET (see Figure 89)

Table 3 – Saturation velocity values adopted for the transistor under analysis.

Gate Length L_G [nm]	Sat. velocity [cm/s]
1 μm	$1.07 \cdot 10^7$
190 nm	$1.25 \cdot 10^7$
70 nm	$1.40 \cdot 10^7$

8.3 Model verification

In order to validate our model, we compared the DC output characteristics: Figure 91- Figure 93 show the I_{DS} – V_{DS} curves for the considered structures and for different V_{GS} values. The simulation results are in good agreement with the experiments, for the whole range of the considered L_G , demonstrating the achievement of the measurable objective of 10% maximum deviation of electro-thermal simulations with respect to experimental data.

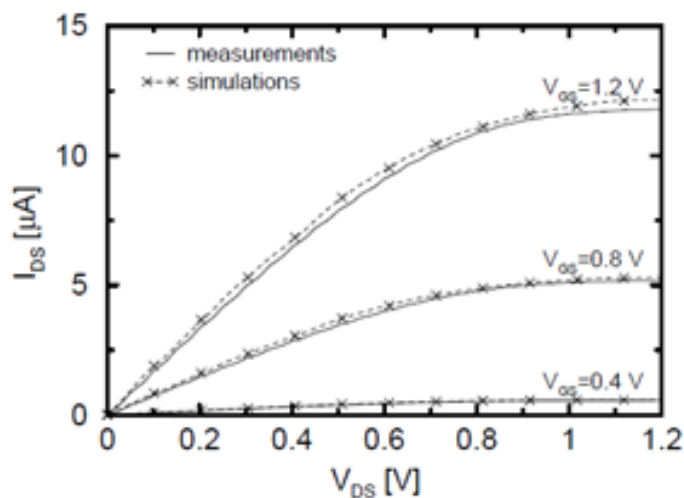


Figure 91 – I_{DS} - V_{DS} characteristics for the 1 μm gate length device, for different V_{GS} .

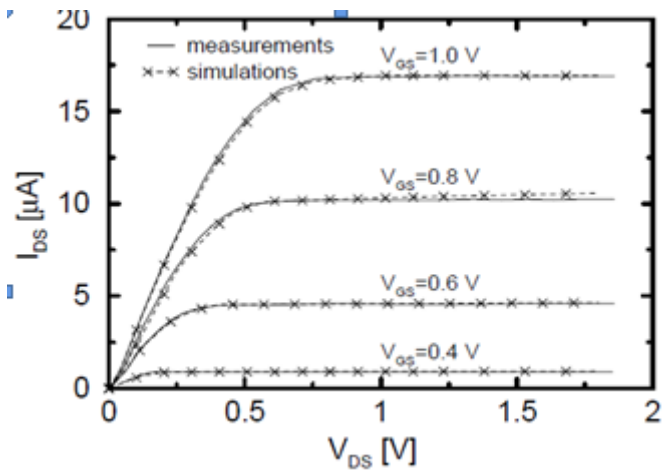


Figure 92 - I_{DS} - V_{DS} characteristics for the 190nm gate length device, for different V_{GS} .

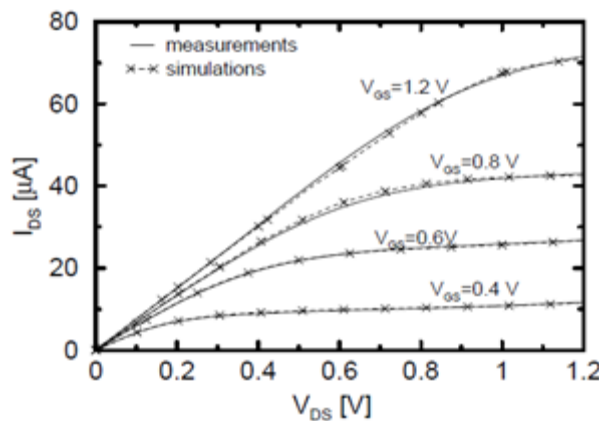


Figure 93- I_{DS} - V_{DS} characteristics for the 70nm gate length device, for different V_{GS} .

In addition, a small signal AC analysis has been performed for the transistors featuring $L_G=1 \mu\text{m}$ and 70 nm. The output conductance g_{DS} , the trans-conductance g_m , the drain–drain capacitance C_{DD} and the drain–to–gate capacitance C_{DG} have been compared to the experimental data reported in [15]. Figure 94 and Figure 95 report C_{DD} and C_{DG} for the FinFET featuring $L_G=1 \mu\text{m}$, biased at $V_{GS}=V_{DS}=1.2 \text{ V}$. The figures show a very good agreement between the experimental data and our simulations for the long–channel device, confirming that the 10% maximum deviation objective MO7.1.12 is met at frequencies larger than 1 MHz; the same level accuracy is confirmed even for g_{DS} and g_m (not reported here).

The results point out that the C_{DD} and C_{DG} are extremely sensitive to self-heating and suffer a large dispersion in frequency, as confirmed by the measurements [15]. Thermal effects respond to signal that are “slow” with respect to the thermal time constants, but are unable to follow fast excitations. For this reason, at high frequencies the C_{DG} and C_{DD} values converge to the isothermal values, where thermal effects are negligible. On the other hand, at low frequencies the impact of self-heating is evident and the capacitances are orders of magnitude larger than the isothermal case.

Moreover, it could be noted that in the case of C_{DG} (Figure 95) also the sign of the capacitance changes. The frequency dependence of C_{DG} and C_{DD} are due to the delay of the heat transport from the active region to the heat sinks; this effect is confirmed and explored in detail in [15], where such dispersion is exploited in order to derive the device thermal impedance and develop a 4th order thermal network of the FinFET. The reported

results suggest AC analysis as a powerful method for the experimental characterization of self-heating effects in small-geometry low-power devices.

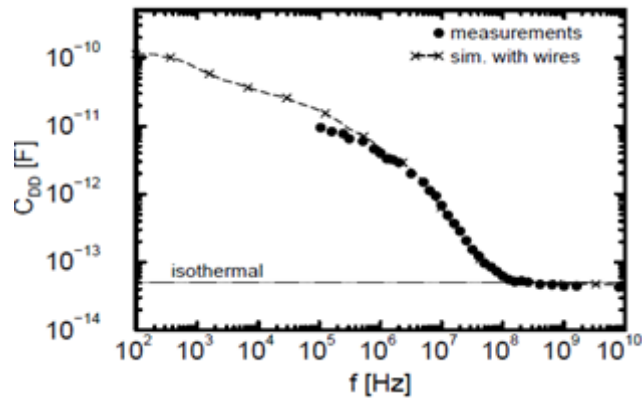


Figure 94 – Drain-to-drain capacitance C_{DD} for the $1\mu\text{m}$ FinFET biased at $V_{GS}=V_{DS}=1.2\text{V}$.

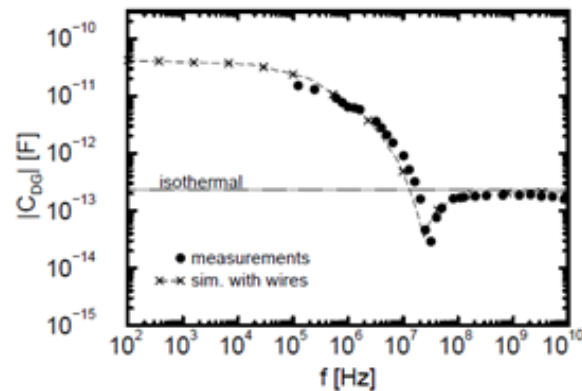


Figure 95- Drain-to-gate capacitance C_{DG} for the $1\mu\text{m}$ FinFET biased at $V_{GS}=V_{DS}=1.2\text{V}$.

A more extensive analysis has been performed for the short-channel transistor: Figure 96- Figure 99 present the AC parameters for the 70 nm -FinFET biased at $V_{GS}=V_{DS}=1.2\text{ V}$. In these figures, the contacts are treated as metal wires, as described in the previous paragraph; moreover, a different simulation approach is presented, where only the intrinsic device (Figure 89) is simulated, but lumped thermal resistances $R_{lum.TH}$ are connected to the contacts. These $R_{lum.TH}$ account for the thermal resistance determined by the interconnects, and their values are defined as a function of the healing length [4]. In the case of metal interconnects we obtain a good agreement between simulations and experimental results even for the short-channel transistor, with maximum deviation below the 10% objective (MO7.1.12).

When we consider lumped thermal resistances, while a very good agreement is obtained in DC (not shown) the agreement in terms of AC parameters degrades significantly, well below our measurable objective: in particular, the simulated capacitances at low frequencies are much lower than the measurements and the frequency at which the sign of C_{DG} changes, is significantly underestimated (see Figure 98 and Figure 99). These results point out that the use of lumped gate, drain and source thermal resistances, although adequate for DC analysis, severely underestimates the thermal capacitance featured by the transistor at low frequency, leading to a wrong estimation of the thermal time constants.

The very good agreement with experiments in terms of transistor AC parameters, obtained when the cooling through metal interconnects is accounted for, confirms that similar accuracy may be obtained while comparing figures of merit such as F_T and available voltage gain, providing confidence on the predictive capabilities of the simulation procedure proposed and applied in Deliverable D2.1.3 [13].

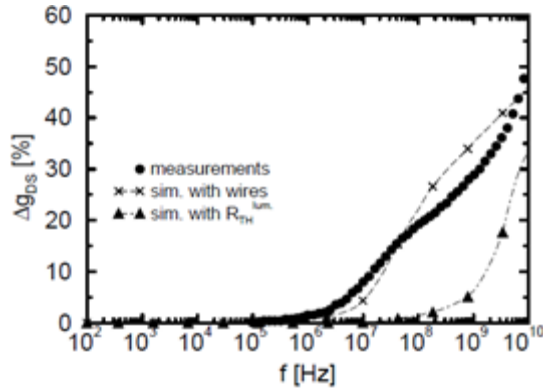


Figure 96- Relative change in output conductance g_{DS} for the 70 nm FinFET, biased at $V_{GS}=V_{DS}=1.2V$. No thermal dispersion occurs in the isothermal simulation for the considered range of frequencies.

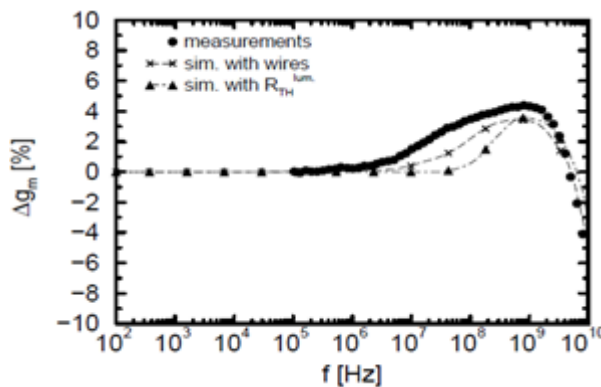


Figure 97 – Relative change in trans-conductance g_m for the 70 nm FinFET, biased at $V_{GS}=V_{DS}=1.2V$. No thermal dispersion occurs in the isothermal simulation for the considered range of frequencies.

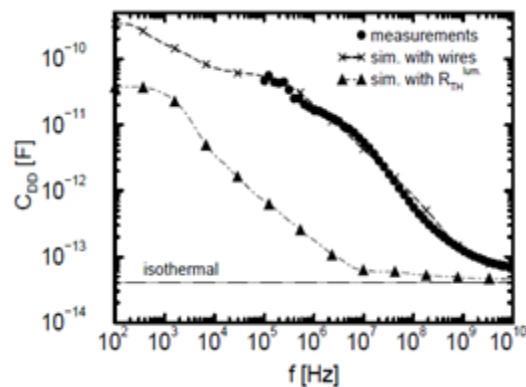


Figure 98 – Drain-to-drain capacitance C_{DD} for the 70 nm FinFET biased at $V_{GS}=V_{DS}=1.2V$.

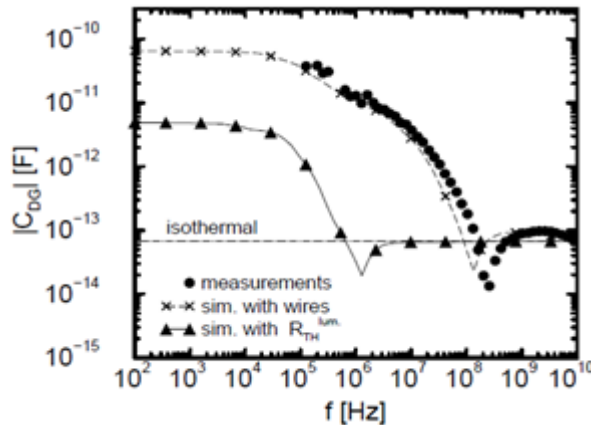


Figure 99- Drain-to-gate capacitance C_{DG} for the 70 nm FinFET biased at $V_{GS}=V_{DS}=1.2V$.

8.4 Conclusions

In this part of the deliverable, we performed realistic numerical electro–thermal simulations of FinFETs, including the source, drain and gate interconnects, in order to analyze the impact of self–heating both on DC I–V characteristics and small–signal AC parameters, with the aim to confirm the achievement of our 10% maximum deviation with respect to experimental data.

Our analysis pointed out that a “simple” approach consisting of lumped thermal resistances severely underestimates the C_{DD} and C_{DG} capacitances at low frequencies, and therefore the correct thermal capacitance associated to the transistor.

In conclusion, a detailed modelling of the metal interconnection wires is essential for AC analysis.

A correct modelling of device cooling through metal interconnects allows to achieve the 10% maximum deviation, representing the objective (MO7.1.12) of our simulation activity within Therminator.

The reported results put in evidence that AC characterization, thanks to the large sensitivity of capacitance parameters to thermal effects, emphasized by the change in sign of C_{DG} , represents a more powerful approach to the analysis of self-heating in low-power devices, than conventional ones based on I-V curves and pulsed measurements.

9 Validation thermal compact models for 3D-ICs (IMEC)

9.1 Introduction

3D-IC stacking is a promising technique for miniaturization and performance enhancement through the reduction of interconnect lengths in electronic systems [19],[20]. Thermal management issues in the 3D stacks are considered as one of the main challenges for 3D integrations [21],[22],[23]. These issues are caused by the use of bonding adhesives with poor thermal conductivity, by the vertical stacking of the chips and by the reduced thermal spreading due the aggressively thinned dies (down to 25 μm). In case of hot spots, these thermal issues are even more pronounced [24],[25]. As a result, the same power dissipation in a 3D IC stack will lead to higher temperatures and more pronounced temperature peaks with respect to a 2D, single die IC [26]. The presence of local interconnect structures such as TSVs (through-silicon vias), μ bumps, backside RDL and BEOL has an impact on the thermal behaviour in 3D-ICs. The optimization of those structures can lead to a temperature reduction in the die stack. Therefore, a detailed thermal analysis of 3D architectures is thus necessary to predict the temperature distribution and to prevent excessive die temperatures. There is thus a clear need for fast modelling tools to accurately model the impact of materials and structures in stack to allow optimization. In task **T6.2 of WP6**, a thermal compact model has been developed to accurately and quickly calculate the temperature distribution in 3D stacks. This model allows evaluating the impact of technology and design options and allows a thermal-aware design optimization thanks to the direct coupling to and feedback from design optimization tool.

Innovation metric:

Status before the start of the Therminator project:

- Time consuming finite element simulations required for each test case: different power maps, cooling conditions, material properties, geometrical parameters,...
- Commercial thermal finite element tools do not allow direct coupling to and feedback from design optimization tool.

During the Therminator project, a thermal analysis engine for 3D-ICs including TSV is developed to improve those aspects.

Measurable objective:

This deliverable describes the experimental validation of the thermal compact models for 3D-ICs developed in T6.2 using test structures including TSVs (through-Silicon vias). The quantification of the measurable objective MO7.1.13 that the developed thermal models have to meet is the following:

The relative difference between the thermal simulation results and the experimental temperature measurements should be less than 5%.

Selected test case

Test case 6: test structures including TSVs to determine influence materials and density of interconnect

9.2 Technical results

9.2.1 3D-SIC technology

For the experimental validation of the thermal models for 3D-ICs, developed in task T6.2, a dedicated test chip with integrated thermal structures is used. This test chip mimics the power dissipation of a real chip and at the same time monitors the temperature at different locations in the die stack. In this experiment, 3D stacked ICs using through-silicon vias (TSVs) are considered. The connection between the different tiers is achieved by Cu-Cu thermo-compression bonding. A schematic of the 3D-SIC architecture is shown in Figure 100 and an in-depth description of the 3D-SIC process can be found in [19] and [28]. The diameter of the TSVs is 5 μm . The 5 mm x 5 mm top dies are thinned down to 25 μm , to expose the TSVs at the backside; the top dies are then stacked face-up on the bottom dies contained in the full thickness (725 μm) landing wafer; a collective hybrid bonding process in a die-to-wafer approach [29] is adopted. The Cu-Cu thermo-compression bonding results in a typical stand-off height of 700 nm to 1 μm between the chips. Figure 100 shows the technology parameters adopted for this process.

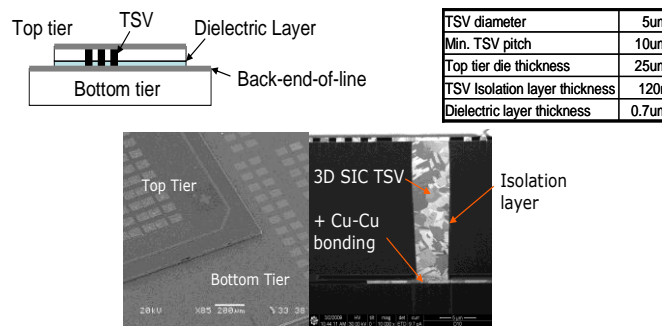


Figure 100. 3D Stacked-IC technology with 10 μm TSV pitch and key technology parameters.

9.2.2 Test structures description

The dedicated thermal test chip contains local heaters to mimic the power dissipation and temperature sensor to monitor the temperature distribution in the chip. **Heaters** made by Cu meander resistors in the metal 2 layer (M2) of the Back End (BEOL) of the top die are used to mimic the power dissipation of an active chip area in the die stack. Heater sizes of 50x50 and 100x100 μm^2 are used to study the impact of the hot spot size. The electrical resistance of the meander heaters is 3400 \pm 750 Ω and 800 \pm 18 Ω for the 100 x 100 μm^2 and 50 x 50 μm^2 heaters, respectively. Figure 101 shows the layout of the test chip with the location of the test structures. Diodes in both top and bottom die are used as **temperature sensors**. The forward voltage drop over the diode is temperature dependent. If a constant current is applied through the diode, the relation between voltage drop and temperature is linear and after calibration the diodes can be accurately used as thermal sensors. A constant diode current of 10 μA is used for the diode measurements since in this case the power dissipation of the diode itself is negligible compared to the power in the die and self heating in the diode is avoided. In this way the die temperature is not affected by the diode measurement. A lower current has a better ‘V-T’ sensitivity, but the ‘V-T’-curves might become non-linear. For 10 μA , the sensitivity of the diodes is around 1.7 mV/ $^{\circ}\text{C}$. At the position of each heater, a set of 5 diodes at different distances (0, 60, 80, 120 and 160 μm respectively) from the hot spot centre are added to capture the local temperature peak. This allows for characterization of the narrow temperature peak at the hot spot and of the effect of hot spot size and interface layers on the peak shape. The position of diodes in the top die overlaps with diodes in the bottom to study the vertical heat conduction in the stack. This can be used to characterize the thermal properties of the polymer glue layer between the top and bottom die. With this set of diodes

and heaters both the horizontal and vertical heat spreading in the stack can be accurately studied.

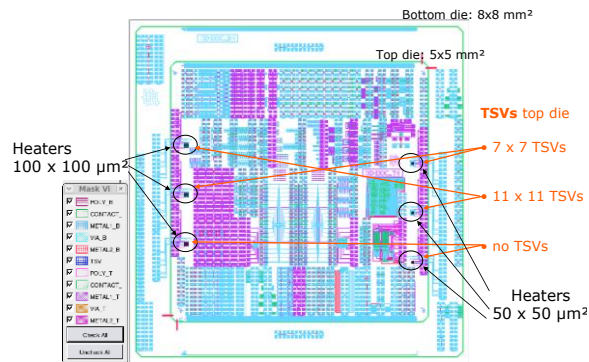


Figure 101. Thermal test chip layout with 6 test structures: 2 heater dimensions and 3 TSV densities.

Structures with TSV arrays of different densities below the heaters are also available to characterize the potential TSV capability to locally enhance the heat transfer; in particular, arrays of 7x7 TSVs (5%) and 11x11 TSVs (12%) are available together with a reference structure without TSVs. The test die contains in total 6 thermal test modules that represent a combination of 2 heater sizes and 3 TSV densities). Figure 102 gives an overview of the location of these 6 modules on the test chip. Figure 102 (a) shows a schematic representation of the cross-section of the test structures. In Figure 102(b), a detail of the layout at the location of a test structure is shown to reveal the location of the heater, diodes and TSV array.

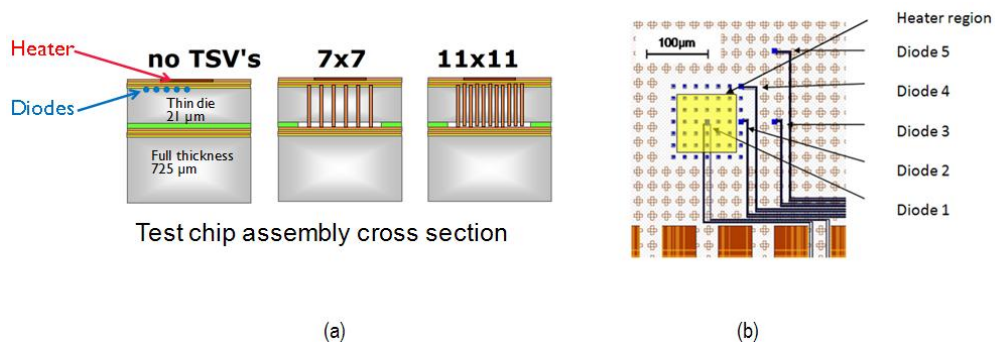


Figure 102. (a) Schematic cross-section of the die stack at the location of the test structures, revealing the TSV array density. (b) Detail of the design layout showing the heater, diodes and TSV array.

To apply the power to the heaters and measure the diode voltages, the stack is connected to a PCB. Using four connections to the heater, the voltage can be supplied to the heater and simultaneously the current is monitored to calculate the dissipated power. To be able to connect all the wires from the thermal test structures in the top and bottom die of the stack, a dedicated two-level PCB is designed. The wire bonds of the bottom die are connected to the lower part of the PCB and the wire bonds of the top die to the upper part of the PCB. Figure 4 shows a schematic representation of the cross-section of the experimental setup and a picture of the PCB with the connected die stack.

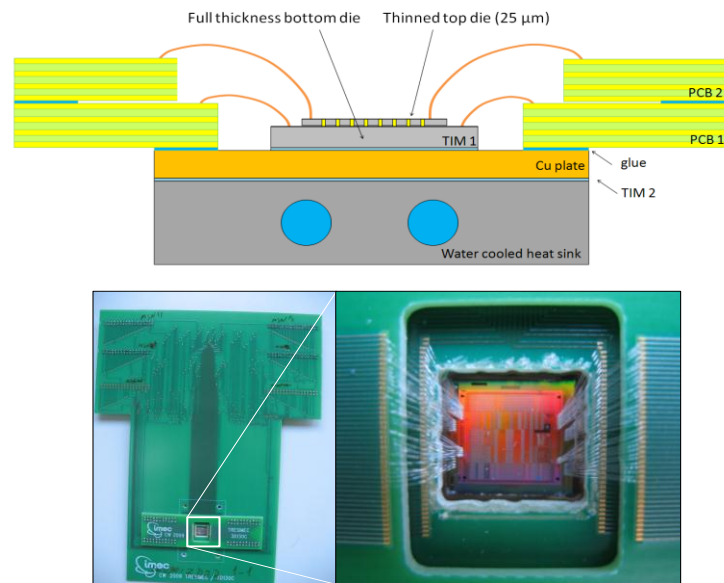


Figure 103. (Top) Schematic cross-section of the test vehicle. (Bottom) Picture of the 2-level PCB – Detail of the cavity in the PCB containing the die stack to reveal the wirebond connections from the PCB to the top and bottom die of the 3D stack.

9.2.3 Experimental validation of the thermal models

First, the temperature profile for a hot spot is compared for a 2D reference case and a 3D stack. The 2D reference case is a full thickness single die with the integrated heaters and temperature sensors. In the 3D case, the heater is in the thinned top die stacked on top of a full thickness bottom die. Figure 104 shows a schematic representation of the 2D and 3D configuration. The temperature effect is compared for both the 100 μm x 100 μm as the 50 μm x 50 using a power density of 12 W/mm² in the hot spot. In the large heater, this amounts to a power dissipation of 120 mW and to a power of 30 mW in the smaller heater.

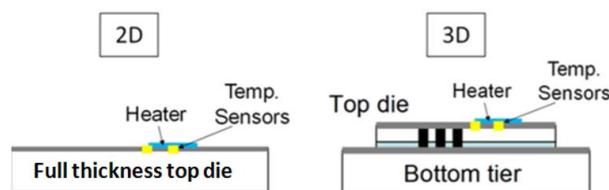


Figure 104. Schematic representation of the 2D and stacked 3D configuration with power dissipation in the top tier.

9.2.3.1 Test structures without TSVs

Figure 105 shows the temperature distribution in the top chip calculated by the thermal model for a power dissipation of 12 W/mm² in the heat sources of the top chip. In Figure 106, the local simulated temperature profile around the heater is compared with the temperatures measured in the 5 diodes for the test structures without TSVs. From this figure a very good agreement between the modeling and experimental temperature measurements can be observed. In Table 4, the relative difference between the modeling results and the experimental results is shown at the location of the 5 diodes for the 4 cases. These result show that the measurable objective MO7.1.13 of maximum 5% difference between measurement and simulation has been met for the thermal model developed in task T6.2.

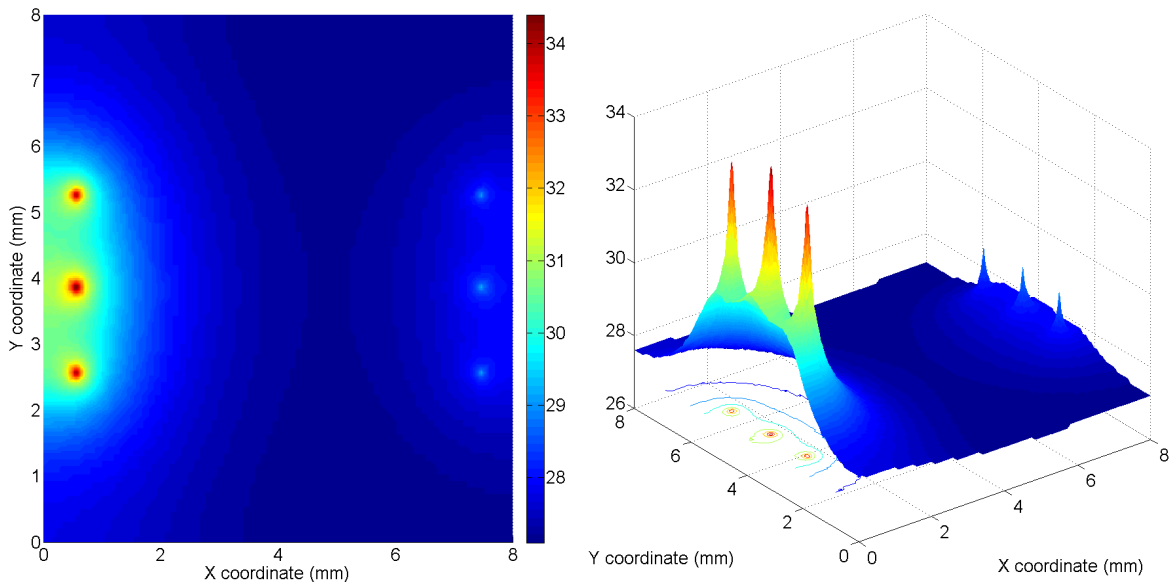


Figure 105. Simulation result from the thermal model from T6.2 for the temperature distribution in the top chip of a two die stack for a power density of $12\text{W}/\text{mm}^2$ in all heat sources shown in the layout in Figure 101.

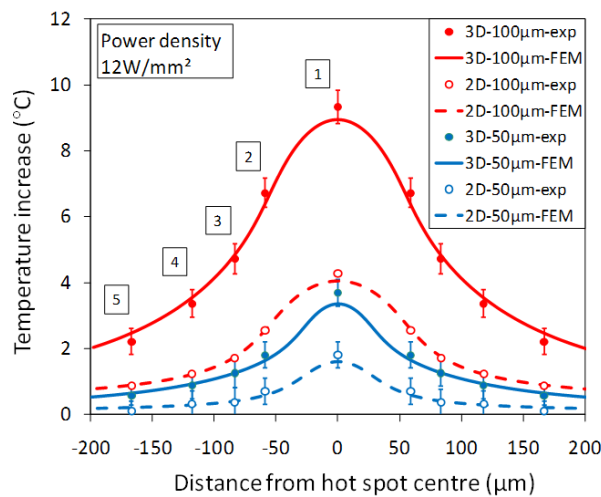


Figure 106. Temperature profile simulation (solid lines) and experimental (markers and error bars) results for a power dissipation of $12\text{ W}/\text{mm}^2$ in $100\times 100\text{ }\mu\text{m}^2$ and $50\times 50\text{ }\mu\text{m}^2$ heaters in the 2D and 3D configuration for the test structures without TSVs.

Table 4. Relative difference between the modeling and experimental results at the diode locations for the temperature profiles of Figure 106.

Case	100x100 3D	100x100 2D	50x50 3D	50x50 2D
Diode 1	4.11%	5.14%	5.06%	4.97%
Diode 2	3.72%	-3.41%	4.72%	4.29%
Diode 3	-4.73%	-4.50%	-2.93%	-4.44%
Diode 4	-4.76%	-3.50%	-4.15%	4.12%
Diode 5	-6.32%	-2.69%	-4.65%	-5.45%

9.2.3.2 Test structures with TSVs

The thermal model predicts a local temperature reduction for an increasing TSV density compared to the no TSV case. A reduction of the local temperature increase of 7% and 20% is predicted for the 7x7 array and 11x11 array respectively. This is shown by the dashed lines in Figure 107 for the 100µm heater. However, a temperature increase (7x7 array) and a less than predicted temperature reduction (11x11 array) have instead been observed experimentally in all test samples. This discrepancy could be explained by processing issues of the TSV-sample. A detailed FIB-SEM analysis of the cross-section of the die-die interface revealed non-connected TSV in the outer ring of the arrays, slight variations in the stand-off height and non-uniform distribution of the polymer adhesive. The thermal model has been extracted for the updated geometry taking into account these deviations from the designed geometry. The updated simulation results are able to correctly predict the expected impact of TSVs density (solid lines in Figure 107). After the adaptation of the model to the reality of the test chip as observed on the cross-sectional images, a good agreement between the thermal model and the measurements results. We can therefore conclude that for the TSV-case the measurable objective MO7.1.13 of maximum 5% difference between measurement and simulation has been met as well as can be observed in Table 5.

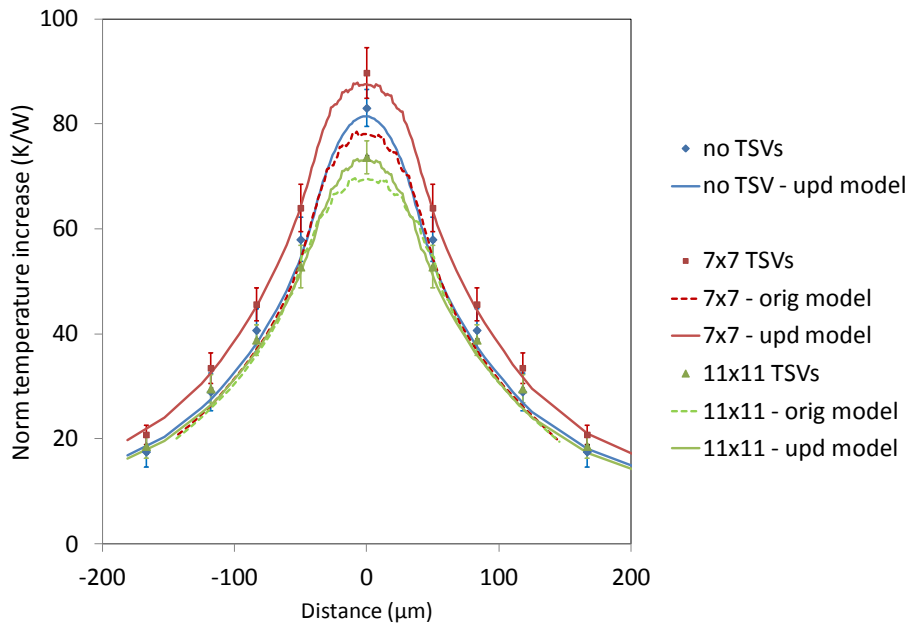


Figure 107. Comparison of the temperature profiles simulated by the updated model and the experimental results for the 100 µm x 100 µm heater.

Table 5. Relative difference between the modeling and experimental results at the diode locations for TSV test structures shown in Figure 102(a).

Case	T0	T 7x7	T 11x11
Diode 1	2.01%	3.66%	0.70%
Diode 2	3.68%	-1.02%	2.98%
Diode 3	4.66%	-0.68%	4.33%
Diode 4	4.56%	2.58%	5.19%
Diode 5	-2.83%	-0.17%	-2.22%

9.3 Conclusions

This part of the deliverable presents the experimental validation of the thermal models for 3D stacked integrated components with TSVs (through-Silicon vias), that are developed in task T6.2 and discussed in deliverable D6.2.2. The developed modeling framework is validated using a test chip with integrated heaters and temperature sensors, and different TSV densities (no TSVs, 7x7 TSV array and 11x11 TSV array) and different heat source sizes (50 and 100µm).

For the test structures without TSVs, the simulation results and experimental results, measured in 5 diodes around each heater, match within 5% over the complete temperature profile of the heat source for both a 3D stack and a reference single die structure. For the case of test structures with TSVs, initially a discrepancy was observed between the modeling and experimental results. It was found that this discrepancy was caused by processing issues related to the 3D stacking. After adaptation of the model to the real geometry, as observed on cross-sectional images, it is shown that the difference between the modeling and experimental results is within 5% for all test TSV densities.

The validation study, described in this part of the deliverable, demonstrates that the thermal models for 3D-ICs, developed in task **T6.2** and reported in deliverable **D6.2.2**, meet the measurable objective MO7.1.13 that states that the accuracy of these models developed in the Therminator Project should be within 5% with respect to the experimental results.

10 Thermal resistance measurements and modeling of packaged discretes (BME, together with NXP-D)

10.1 Samples

The samples were prepared by NXP-D and received at the end of November 2012.

The discrete devices were soldered on a JEDEC standard JESD51-3 compliant printed circuit boards, each device on two boards with different layout. On boards marked *RTH0* the standard footprint and track sizes were used, on *RTH1* marked boards cathodes were mounted on a 1cm² mounting pad. One of the board pairs can be seen on **Error! Reference source not found.**

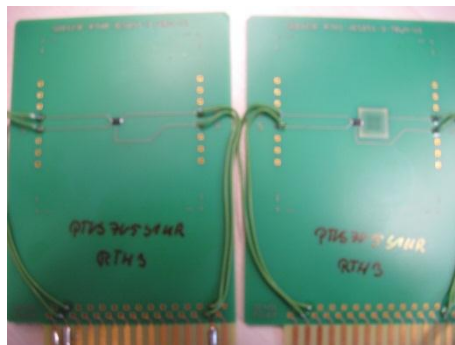


Figure 108 - Devices mounted on RTH0 and RTH1 PCB-s

The package and device types are summarized in Table 6.

Package	Device	Type
SOD123W	PTVS7V5S1UR	Supressor diode
SOD882	BZX884C7V5	Zener diode
SOT23	BAS40	Schottky diode
SOT89	BZV49C10	Zener diode
SOT1061	PMEG2020EPA	Schottky diode

Table 6: Device and package types

10.2 Thermal transient measurements

All measurements were carried out in accordance with the JEDEC standard JESD51-1 static thermal test method. After a step change of power, the transient temperature response was recorded of the device under test. The temperature change was monitored by the electrical test method; the forward voltage change of the pn or Schottky junction at constant current was used as temperature sensitive parameter. All boards have been measured in a standard 1 ft³ JESD51 - 2 compliant still air chamber.

T3Ster thermal transient tester was used for the measurements and the recorded thermal transients were evaluated by T3Ster-Master 2.2 software. [30]

The main features of T3Ster are:

Maximal sampling rate	1 μs
Sampling	logarithmic, 64k samples
A/D conversation	12 bit
Temperature resolution	0.01°C (at TSP 2mV/°C)
SNR	> 70dB

Table 7: The main features of the T3Ster instrument

All measurements have been carried out in common cathode diode configuration. The schematic for the measurements can be seen on Figure 109. The forward current of the diode switched between a high (heat) and a low (sense) current state. The recorded transients were cooling transients for practical reasons.

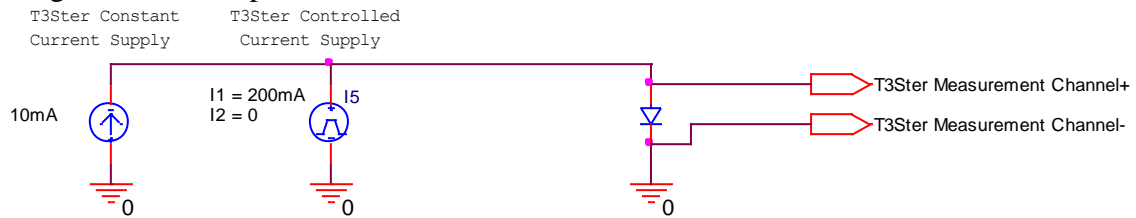


Figure 109 - Schematic of the grounded cathode configuration

The switched power can be calculated as:

$$\Delta P \cong I_{high}U_{high} - I_{low}U_{low}$$

In order to increase the signal-to-noise ratio, the heating current of the devices were set close to the datasheet absolute maximum limits, or to generate about 50 or 100mV forward voltage change, which fits well within the T3Ster instrument’s hardware limit. For sensing 1mA was chosen for the pn junction diodes and 10mA was used in case of Schottky diodes. The thermal coefficients were calculated between 25-100°C. The temperature-voltage characteristic of Schottky diodes tended to be more nonlinear, therefore 2nd order approximation was used in the calculations. The measurement parameters can be seen in Table 8.

Package	Device	Heat current	Sense current	Thermal coefficient	Fit order	R ²
SOD123W	PTVS7V5S1UR	210mA	1mA	-1.885mV/°C	1	0.9999
SOD882	BZX884C7V5	160mA	1mA	-1.748mV/°C	1	0.9996
SOT23	BAS40	100mA	10mA	-0.85mV/°C	2	0.9999
SOT89	BZV49C10	250mA	1mA	-1.701mV/°C	1	0.9995
SOT1061	PMEG2020EPA	750mA	10mA	-1.734mV/°C	2	0.9999

Table 8. The measurement parameters

10.3 Evaluation of the measurements

The measured transients were processed with the T3Ster-Master 2.2 software. The software is capable to generate so called structure functions from measured transients. The measured thermal impedance and the calculated structure functions can be found in section 10.4.1.

The cumulative structure function $C_{\Sigma}(R_{\Sigma})$ shows the cumulative heat capacitance as a function of the cumulative thermal resistance from the heat source to the ambient. It is the one dimensional representation of the heat path, that can be easily converted into a Cauer type network of heat resistances and capacitances, for direct use in compact modelling.

The effect of the 1cm² mounting pad can be easily seen in both the thermal transients and the structure functions. However the determination of the separation point, i.e. the R_{th} value, where the structure function is to be split package and board part is not straightforward.

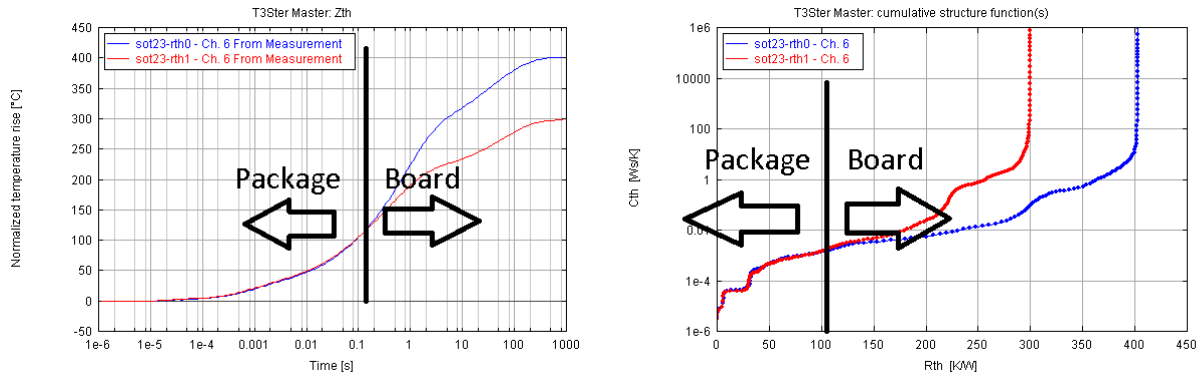


Figure 110 - Thermal impedance and structure functions of the SOT-23 package

From a thermal transient measurement it is only possible to create a one-dimensional model of the heat path. In case of real devices, the heat spread is three dimensional. The heat path inside the package changes with the different boundary conditions (different board layouts) which can be only approximately modelled in a one dimensional compact model.

Furthermore the measurements were carried out on two device instances, the effect of geometry or material differences, mostly the die attach and soldering differences, also differences in the electrical characteristics are affecting both the measured thermal transients and the calculated structure functions.

For determination of the separating point three different methods were investigated:

1. Difference of the structure functions. In case of perfect one dimensional heat conduction the difference of structure functions would be zero until the heat reaches the 1cm² copper area of the RTH1 board, then the difference in heat capacitance would show monotone rise, as it can be seen on Figure 110. In the case of real samples the difference of the structure functions is affected by noise.
2. Difference of the derivative da/dz curves, as suggested by the somewhat similar transient dual interface method [32]. By plotting the difference of the derivatives vs. the Z_{th} value of *RTH0* board, it can be used to identify the point of separation. For an example see Figure 111. The advantage of this method is the insensitivity for offset errors in Z_{th} measurements.
3. Using the differential structure functions (the derivative of the cumulative structure function) as suggested in [33]. In the differential structure function the interface surfaces are represented as inflexion points between a local maximum and minimum. This is the less applicable method for these packages; because of the limited resolution of the structure function prohibits the detection of the inflexion points.

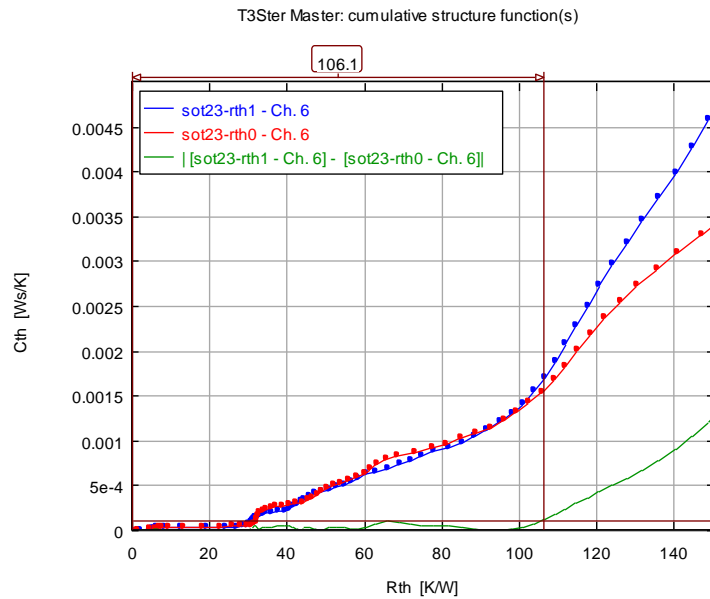


Figure 111 - The difference of the structure functions

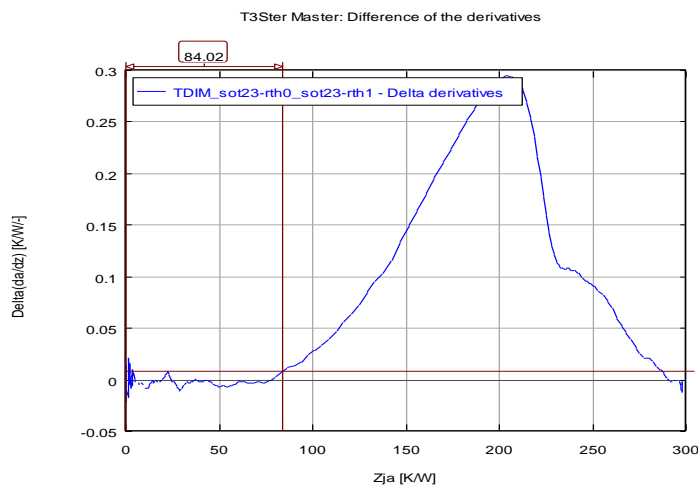


Figure 112 - Difference of the derivatives method

Not all of the proposed methods are applicable on all samples; also the different methods lead to different results, with unacceptable large deviation, despite the repeatability of the measurement, which usually lies in the range of few percent. In case of the measured plastic surface-mountable packages, the structure function methods resulted in higher and more realistic R_{TH} values.

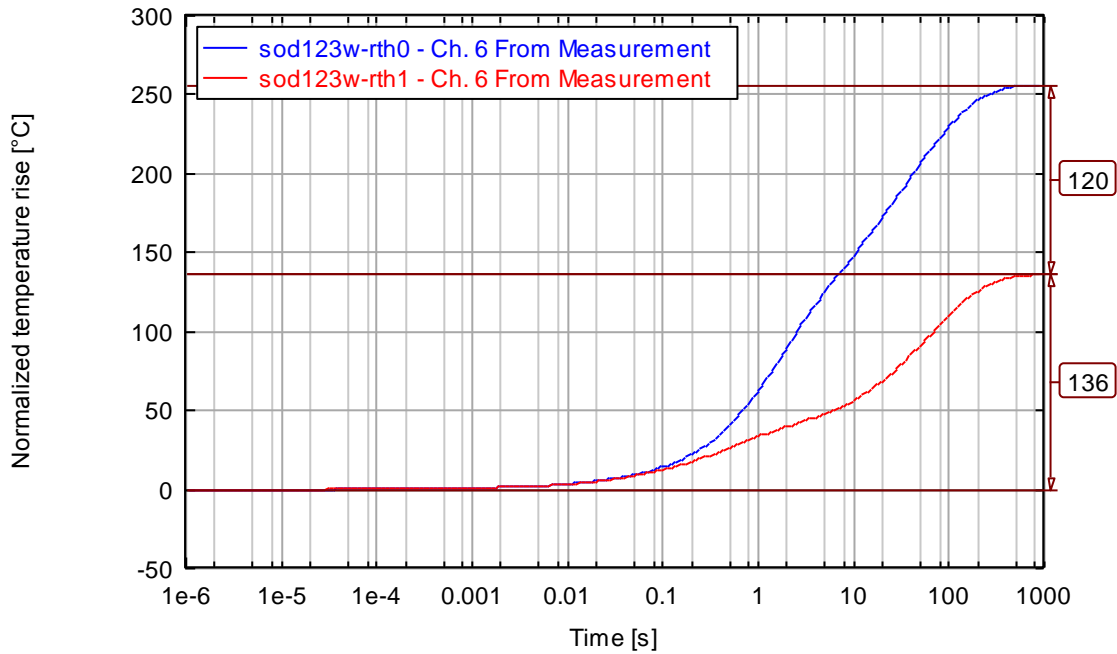
To overcome the uncertainty of the separation methods, the $R_{thpackage}$ values generated by these methods are treated only as first assumption. For creating the compact models, the package-board separation point was changed in the neighbourhood of the separation point to minimize the difference from the measured and modelled thermal transients for each boundary condition in an equidistant logarithmic time scale.

10.4 Overview measurement results

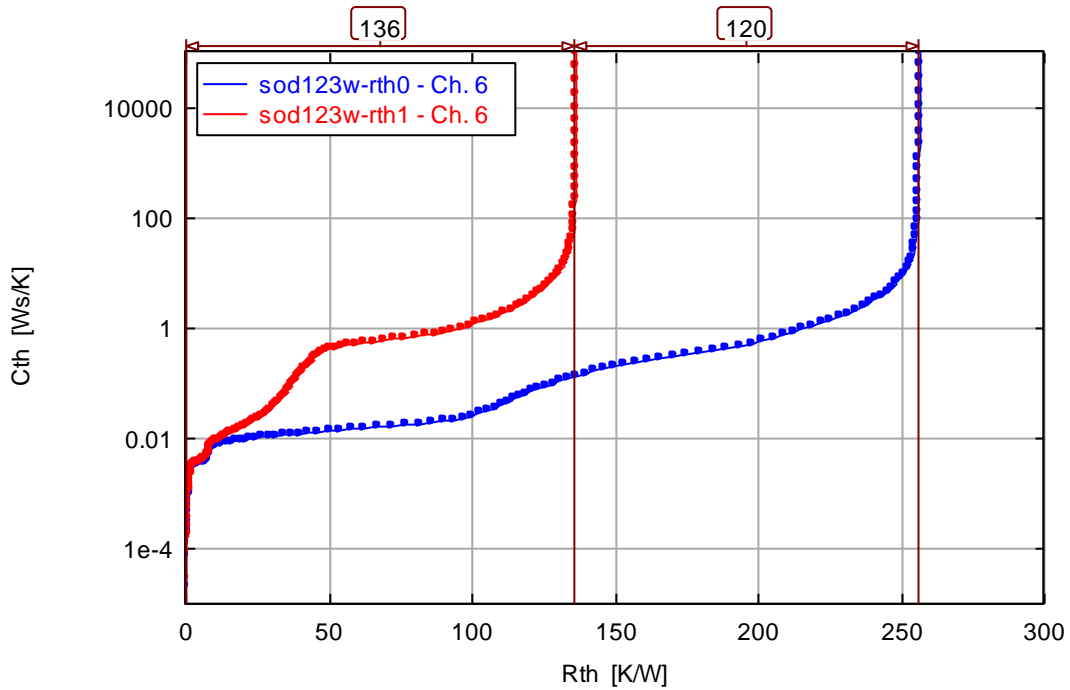
10.4.1 The $Z_{th}(t)$ and the structure functions of the measured devices.

10.4.1.1 SOD123W

T3Ster Master: Zth

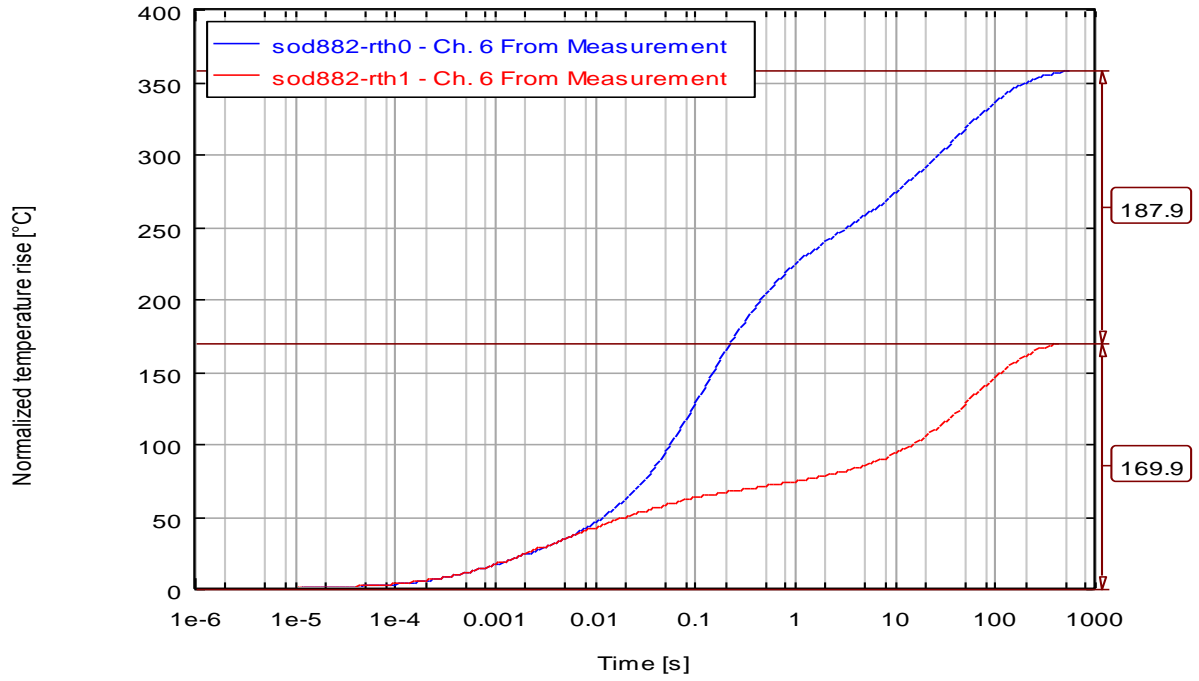


T3Ster Master: cumulative structure function(s)

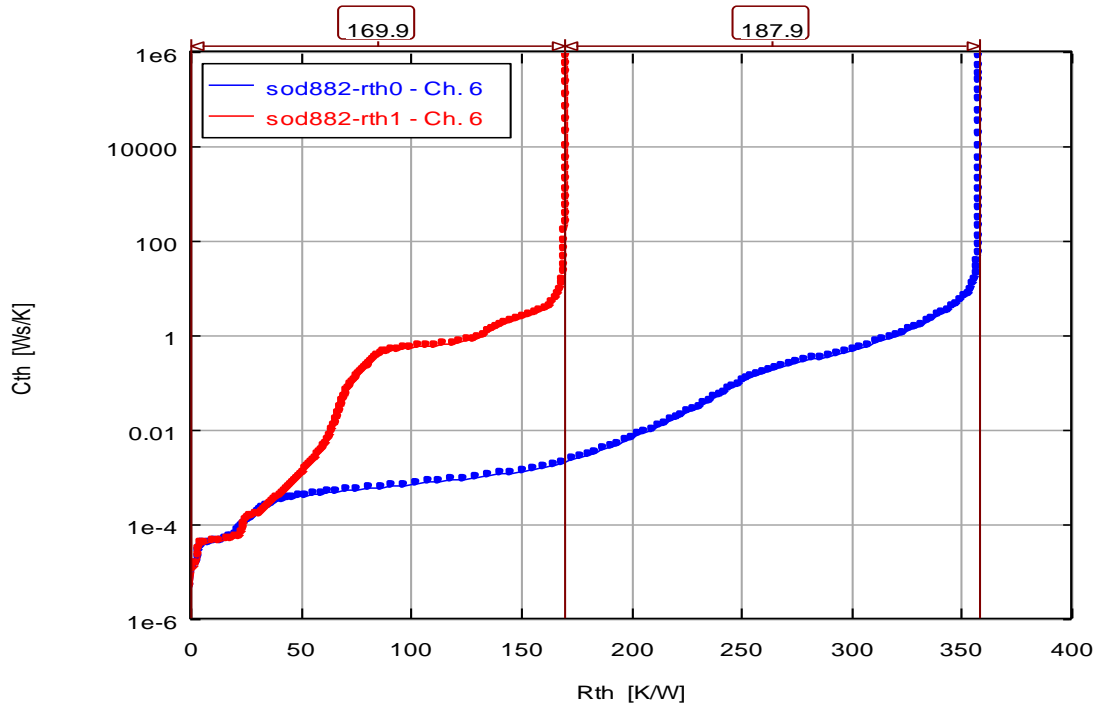


10.4.1.2 SOD882

T3Ster Master: Zth

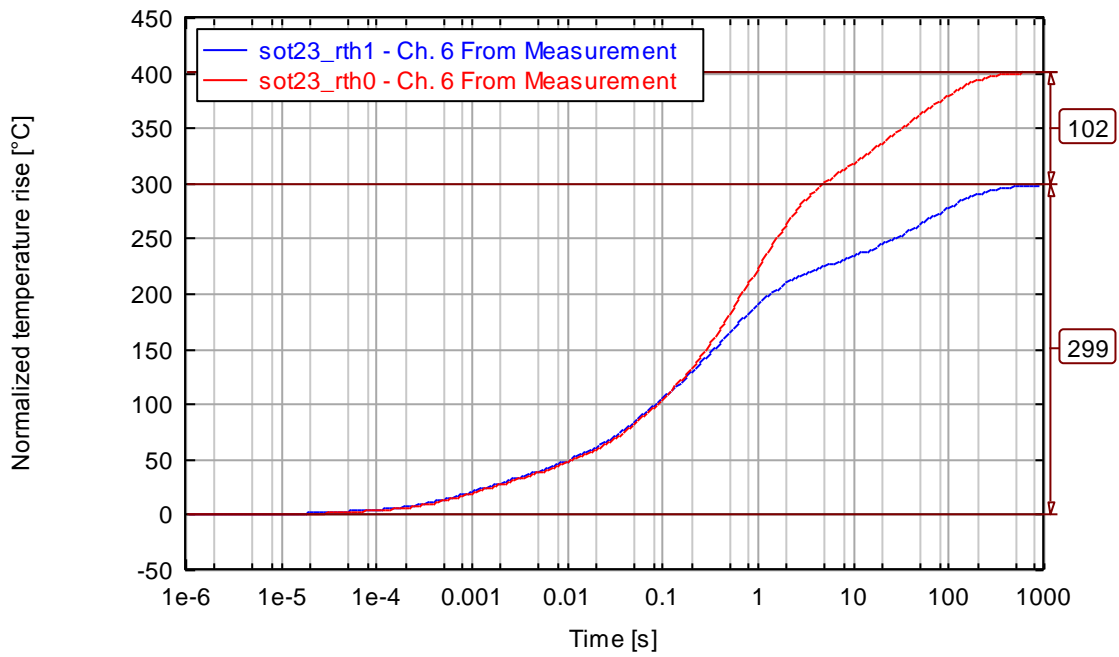


T3Ster Master: cumulative structure function(s)

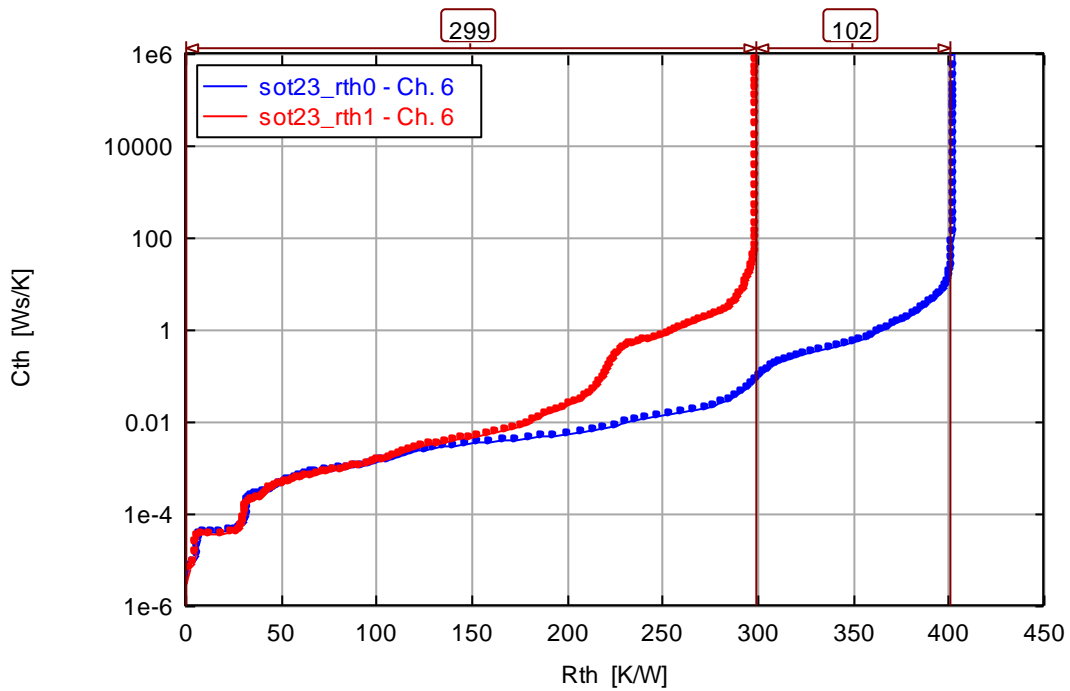


10.4.1.3 SOT23

T3Ster Master: Zth

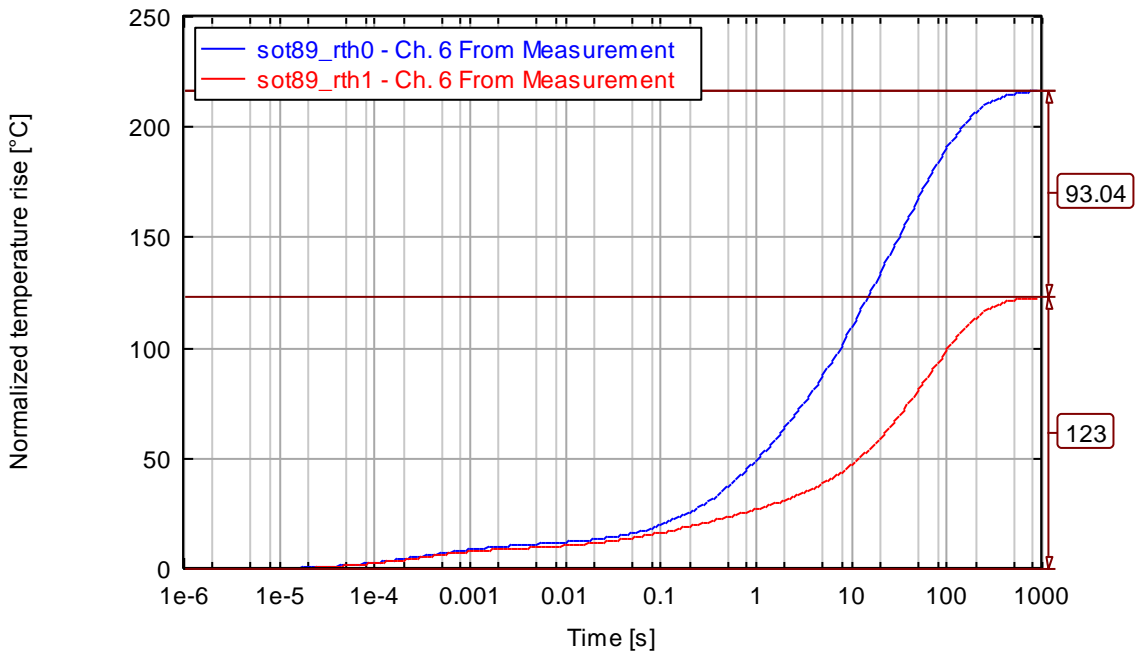


T3Ster Master: cumulative structure function(s)

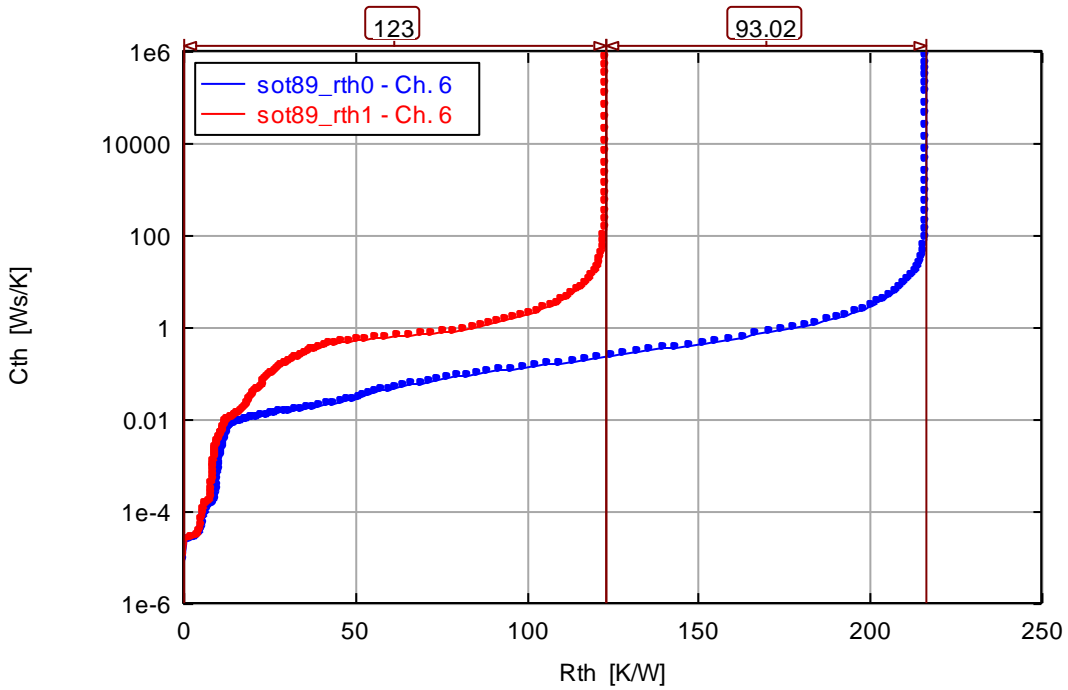


10.4.1.4 SOT89

T3Ster Master: Zth

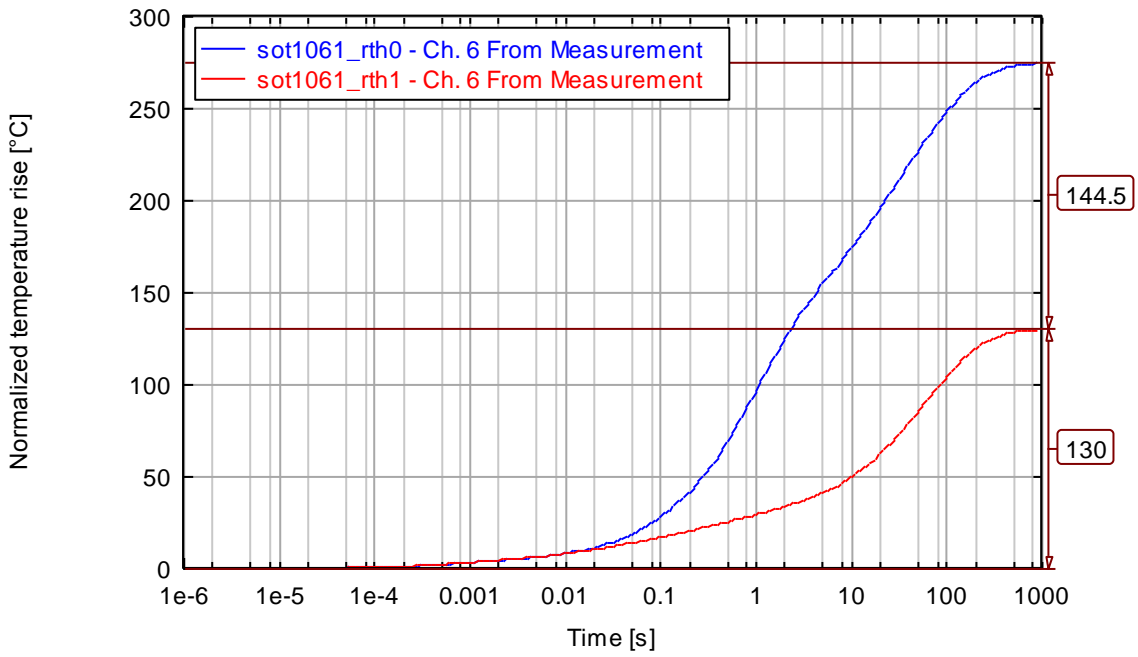


T3Ster Master: cumulative structure function(s)

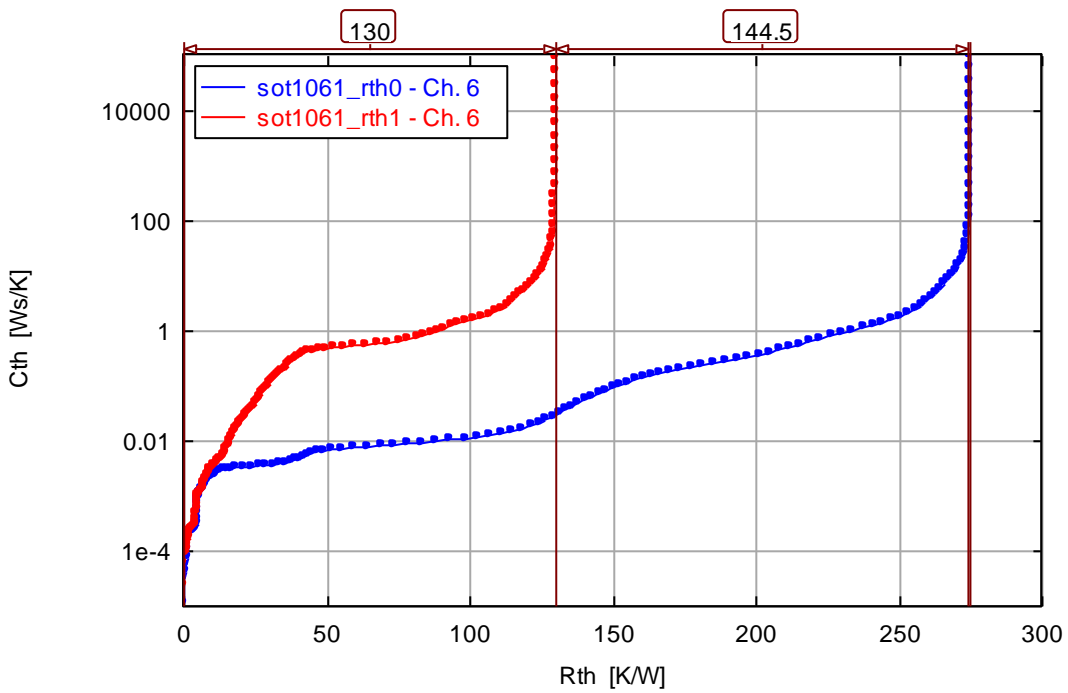


10.4.1.5 SOT1061

T3Ster Master: Zth

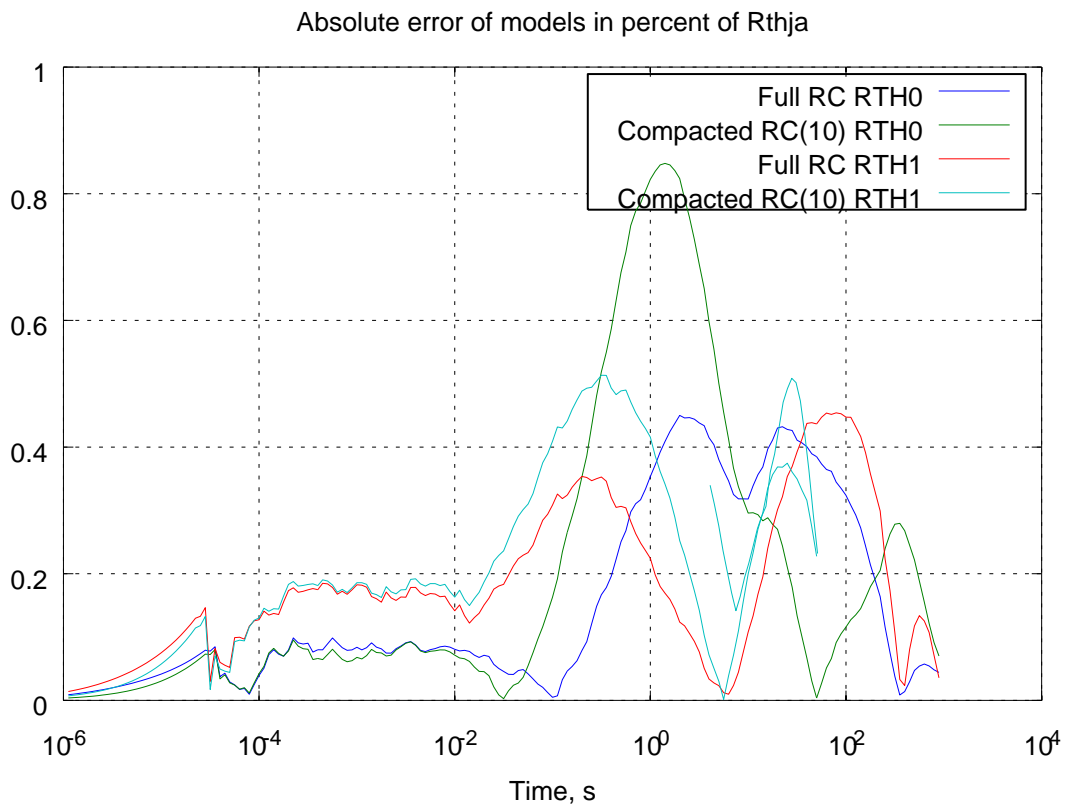
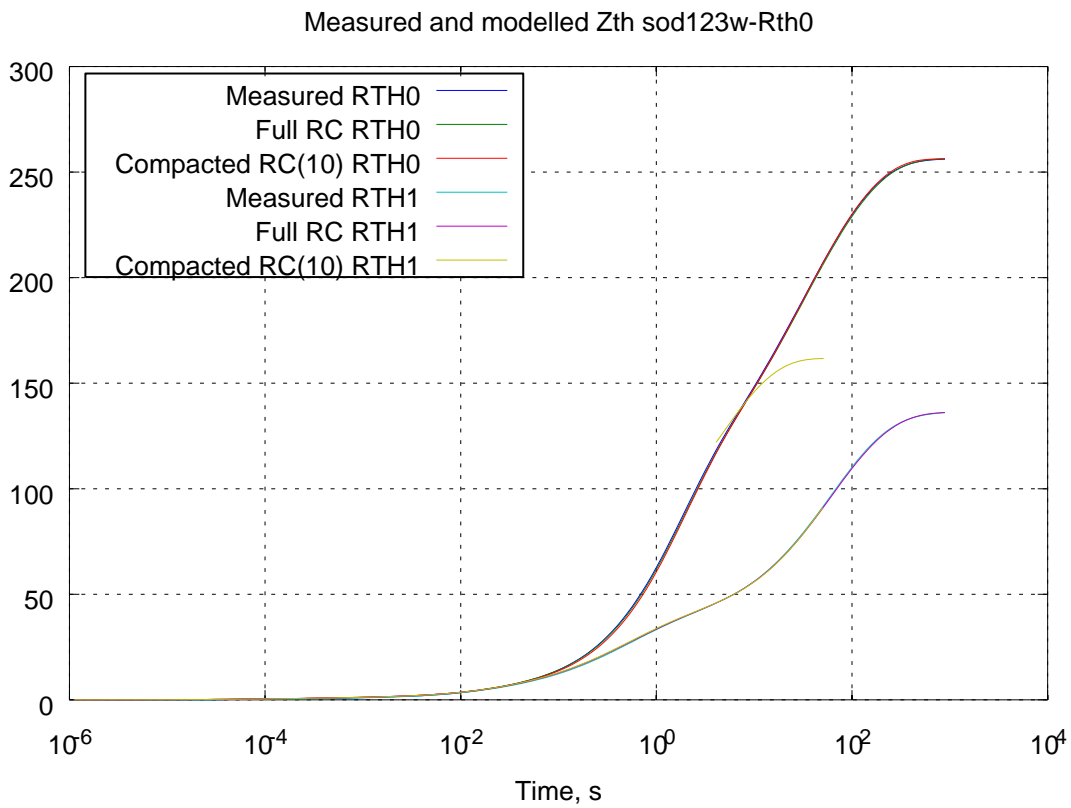


T3Ster Master: cumulative structure function(s)



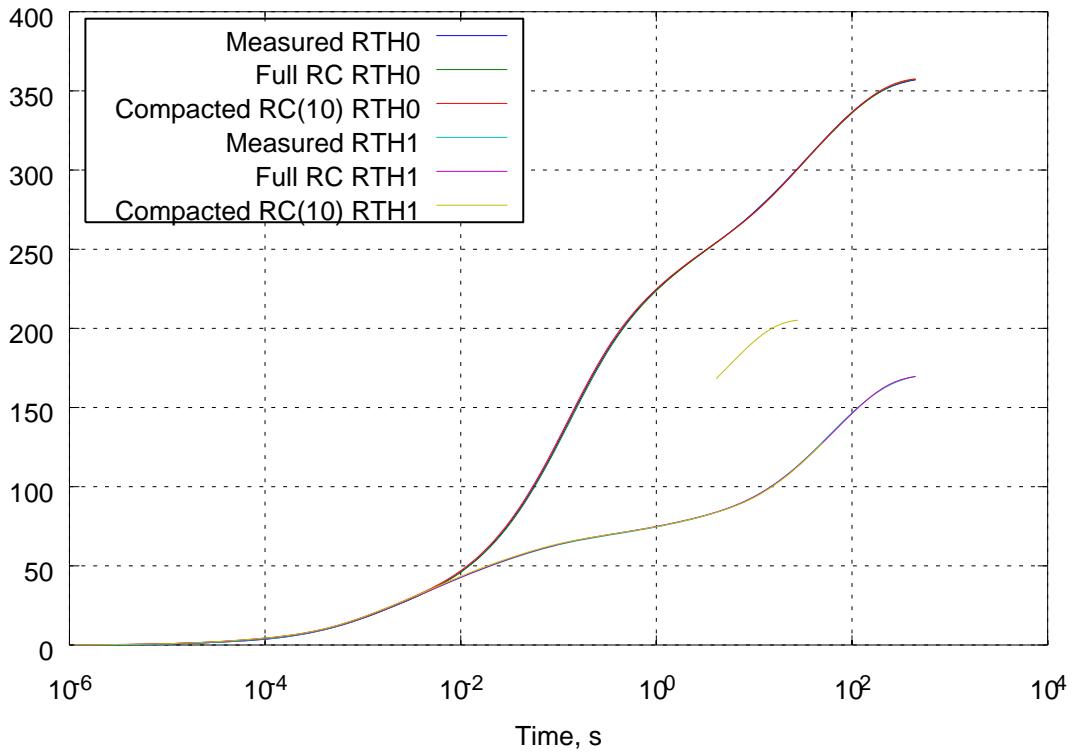
10.4.2 The measured and modelled thermal transients

10.4.2.1 SOD123W

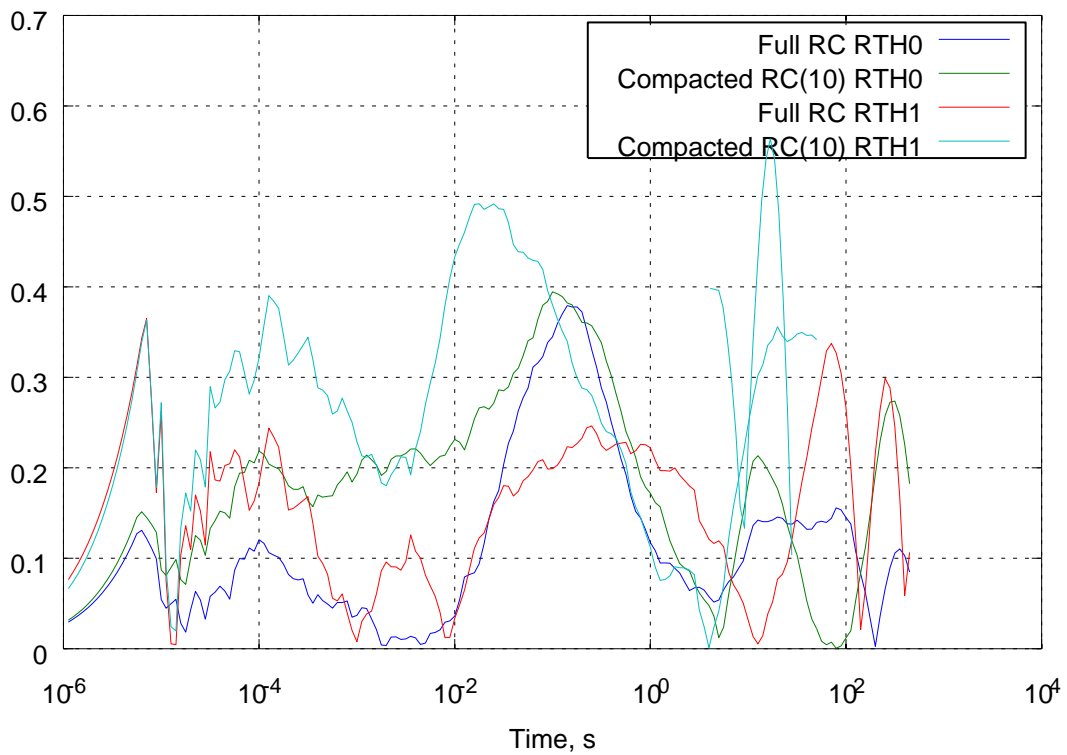


10.4.2.2 SOD882

Measured and modelled Zth sod882-Rth0

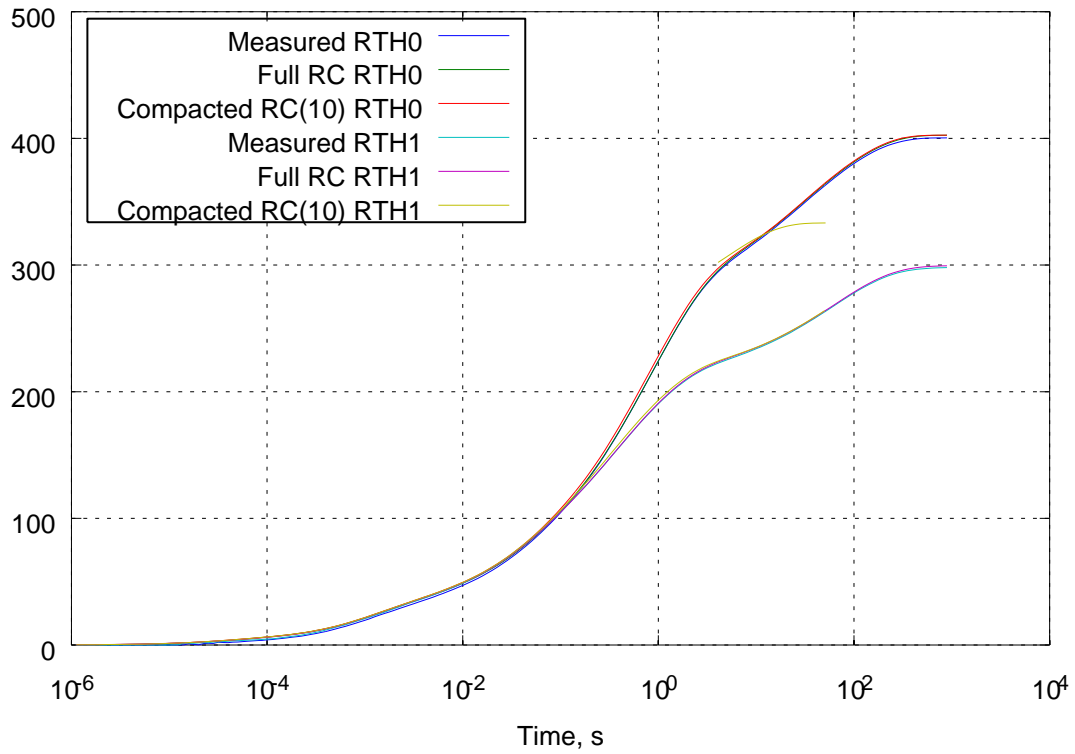


Absolute error of models in percent of Rthja

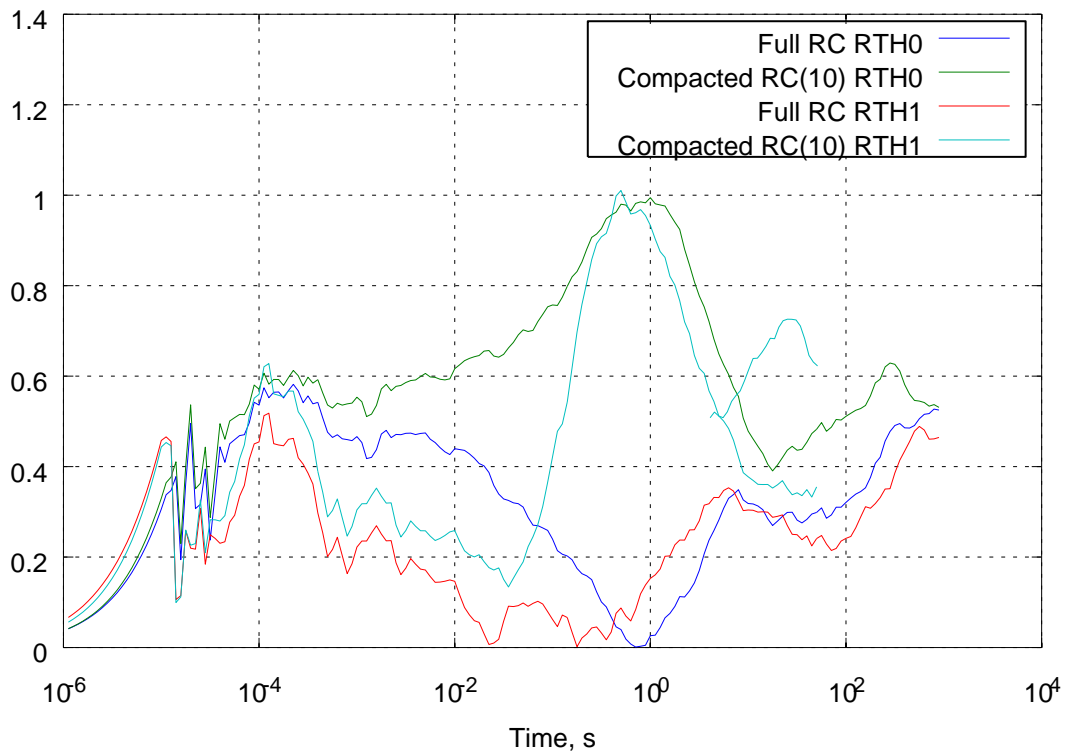


10.4.2.3 SOT23

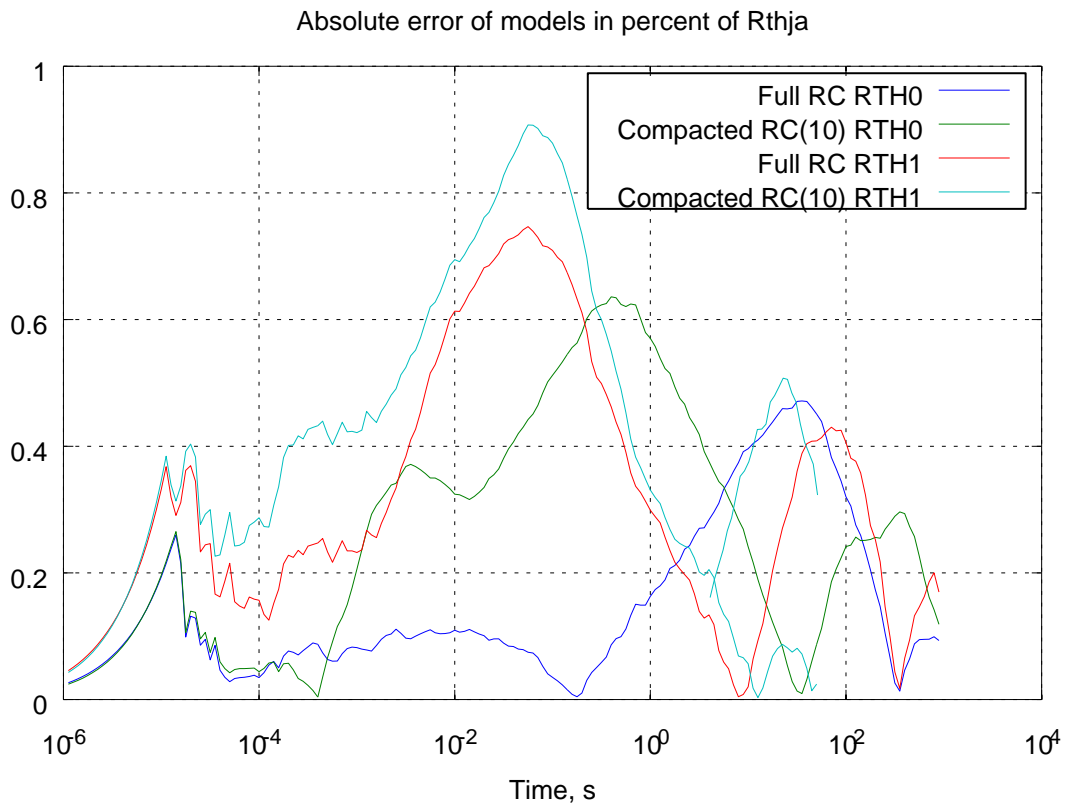
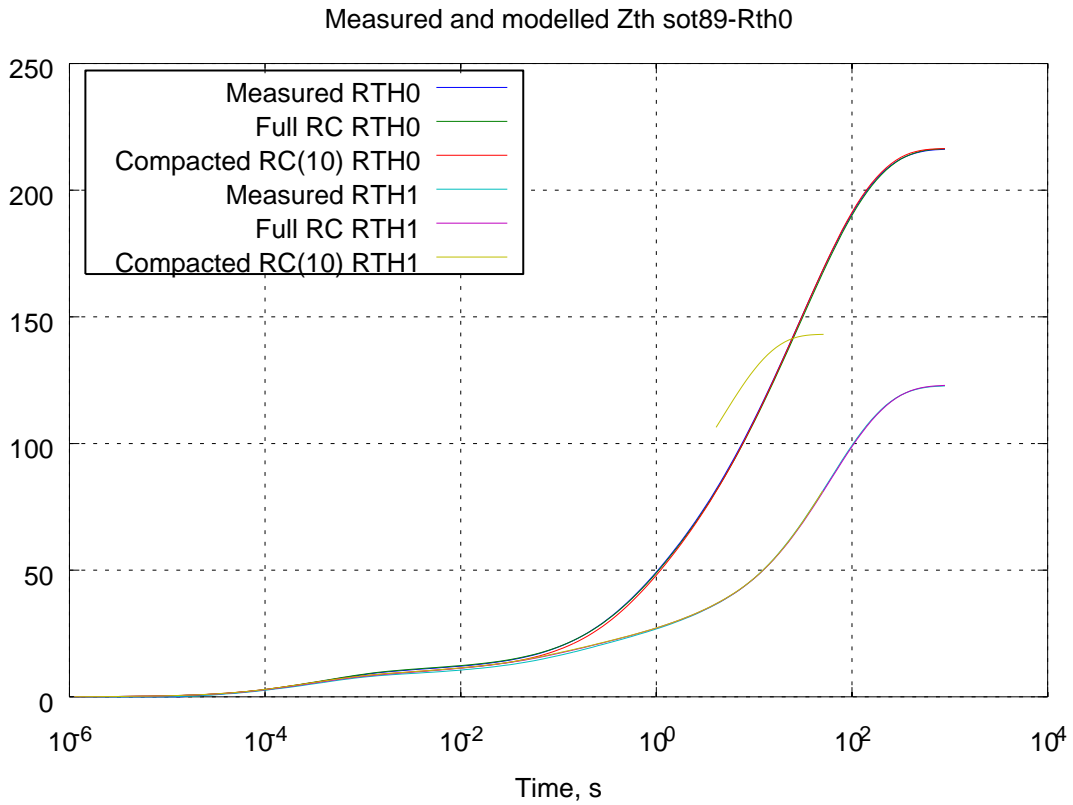
Measured and modelled Zth sot23-Rth0



Absolute error of models in percent of Rthja

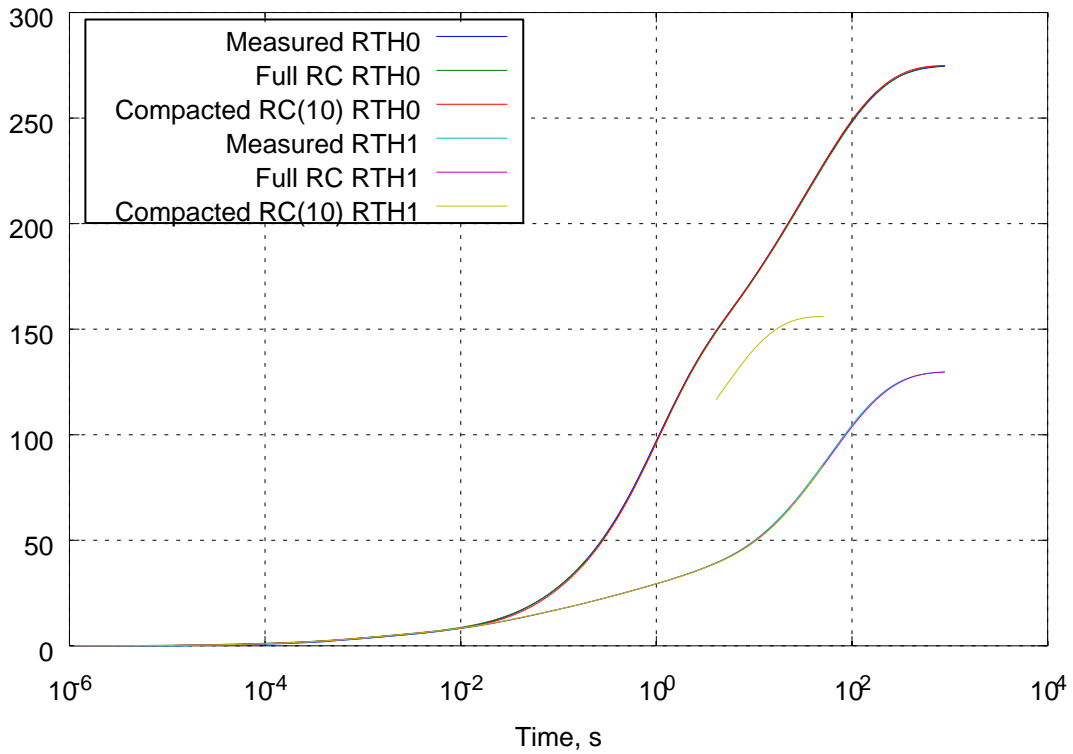


10.4.2.4 SOT89

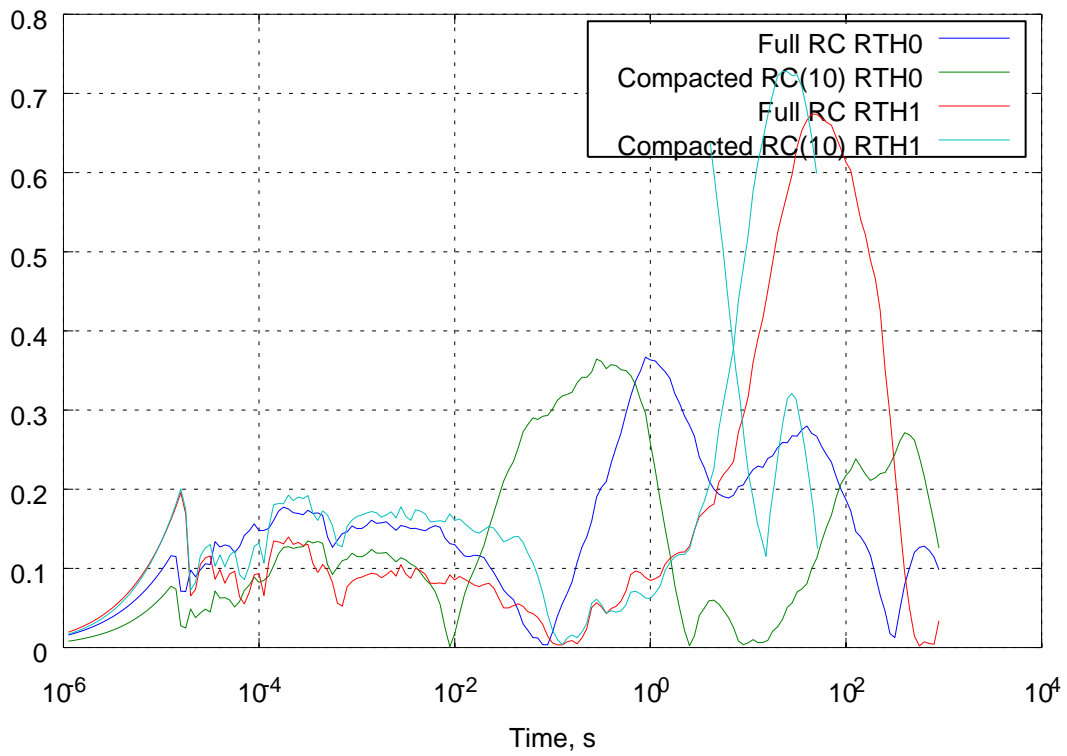


10.4.2.5 SOT1061

Measured and modelled Zth sot1061-Rth0



Absolute error of models in percent of Rthja



10.5 Conclusions

The static thermal resistance of the different packages and boards can be seen in Table 9.

Package	R _{THJA} Board- RTH0	R _{THJA} Board-RTH1	R _{THJP}
SOD123W	256 K/W	136 K/W	11 K/W
SOD882	358 K/W	170 K/W	38.2 K/W
SOT23	401 K/W	200 K/W	105 K/W
SOT89	216 K/W	123 K/W	13.8 K/W
SOT1061	274.5 K/W	130 K/W	7.9 K/W

Table 9: The static thermal resistances of the different packages and boards

From the separated package/board structure functions equivalent Cauey type models were generated. The package models have about 29-51, the board models have 94-115 RC stages. In order to increase the usability of these behaviour models in other simulators, the RC ladders have been further compacted to contain ten RC elements for the package and the boards.

Error (%)	Board- RTH0				Board-RTH1			
	full		compact		full		compact	
	mean	max	mean	max	mean	max	mean	max
SOD123W	0.15	0.45	0.19	0.84	0.18	0.45	0.21	0.51
SOD882	0.11	0.38	0.18	0.39	0.15	0.37	0.26	0.53
SOT23	0.32	0.58	0.56	0.99	0.23	0.51	0.42	1.01
SOT89	0.15	0.47	0.26	0.63	0.32	0.75	0.37	0.90
SOT1061	0.15	0.37	0.13	0.36	0.16	0.67	0.18	0.73

Table 10: The average and the maximum of the error of compact models respect to the R_{THJA}

The error between measured and modelled Zth is defined as:

$$error = |T_{measured} - T_{model}| / R_{THJA}$$

The average value is calculated on an equidistant logarithmic scale from 1µs- to the length of the thermal transient measurement.

Both maximal and average errors are in less or equal to 1 percent of the measured transients. Using the compact model does not introduce significant errors.

11 Conclusions

In this deliverable, the validation of models and tools addressing the thermal behaviour of electronic devices in many different technologies of relevance for the European semiconductor industry has been demonstrated. The models and tools have been developed in WP2, 3, 4, 5, and 6 on advanced and new devices, technologies, and materials. The validation was carried out on the test cases of WP1 and other examples provided by individual partners. The validation activities concentrated on validation of TCAD tools and verification of compact models, since the validation in T7.1 focussed on devices and elementary building blocks. In this final conclusion, the major results are summarized, while a more detailed overview of the results on each subject can be found in the conclusions section of each chapter. The results in terms of measurable objectives and contributions to conferences and journals are given in chapters 12 and 13, respectively.

In the validation activities, there has been a close cooperation between TCAD vendors, universities, research institutes, and the European semiconductor industry. These collaborations in Therminator have been very effective in terms of exchanging concepts and ideas between partners, creating a valuable innovation infrastructure between universities, research institutes, and the industry. Results of these collaborations include verified TCAD for power devices (SNPS-CH, ST), devices in contactless identification ICs (SNPS-CH, FHG, NXP-D), and advanced CMOS (SNPS-CH, IMC). Moreover, the cooperation between BME and NXP-D has resulted in compact thermal models for packaged discretely validated against measurements. Furthermore, there have been several activities to study and improve the understanding of electronic devices of the (near) future, resulting in accurate models for 3D ICs (IMEC), compact models for GaN-HEMTs (NXP-NL), and a capacitance-based thermal characterization technique for low-power devices (UNIBO). Finally, the industrial partners have shown the usefulness of the tools developed in Therminator by demonstrating their integration into design flows. Examples include the integration of PSP models for advanced CMOS devices into the IMC design flow, the RF-LDMOS electro-thermal models into the NXP design tools, and the thermal-aware design framework of ST for high-voltage transistors in automotive applications. The integration of the developed tools into the (existing) design flows of the industrial partners is an important step in the commercial exploitability of the Therminator project, resulting in an advantageous position of the partners with respect to the competition.

12 Measurable objectives

The Therminator project objectives are

1. New modeling and simulation capabilities to support accurate circuit thermal analysis and simulation
2. Innovative thermal-aware design techniques, methodologies and prototype tools for controlling, compensating and managing thermally-induced effects on parameters such as timing, (dynamic and leakage) power, reliability and yield
3. Demonstration of the accuracy and ease of integration within existing design flows of the new models by validation against measured data obtained on ad-hoc silicon structures
4. Demonstration of the applicability and effectiveness of the new design solutions through manufacturing of test-chips featuring leading-edge silicon technology, as available from some of the project partners
5. Demonstration of the usability and effectiveness of the new design methodologies and tools by their application to industry-strength design cases made available by some of the project partners

In order to quantify the output of the validation work presented in this deliverable, measurable objectives have been defined. In the table below, all the measurable objectives of T7.1 are summarized. In this table, it is also shown to which test case of WP1, and to which Therminator’s project objectives the measurable objectives are related. Since T7.1 focuses on validation and verification of models and tools of devices and elementary building block, the majority of the measurable objectives are related to Therminator’s project objective 1. In T7.2 and T7.3, the measurable objectives will be more connected to the other Therminator’s project objectives (2-5).

Area	Measurable objective	Innovation Metric	Quantification	Test case	Project objective
7.1 Validation of models on test structures	MO7.1.1	Thermal resistance measurements on power devices	Validation thermal models RF-LDMOS and GaN-HEMT (yes/no) [NXP-NL]	Test structures: Testcase 2	1
	MO7.1.2	Reuse by adapting electro-thermal modeling developed on RF power technologies for other types of devices	Reuse and adapt electro-thermal model GaN-HEMT for GaN Schottky diodes. Reuse and adapt electro-thermal model RF-LDMOS for SOI-LDMOS Error within 15% [NXP-NL]	Test case 2	3
	MO7.1.3	Integration and demonstration of tools on industry-strength designs	Integration of the electro-thermal model for RF-LDMOS, developed within Therminator, into design tools and validation on large signal application data. (yes/no) [NXP-NL]	Test case 2	5
	MO7.1.4	WP5: Validate thermal	Error between measurements and	Testcase 2	1

		models of discrete power devices developed in WP5 (not existing before Therminator) with measurements	simulation within 10% . [ST,SNPS-CH]		
	MO7.1.5	Validate 3D TCAD model for 28nm/32nm CMOS developed in WP2	Error between measurements and simulation within 20% . [SNPS-CH]	Testcase 3	1
	MO7.1.6	Validate the high-k metal gate 28nm CMOS models developed in WP2, with cross-technology reference to 40 nm	Error between measurements and simulation within 20 % [IMC]	Testcase 3	1
	MO7.1.7	Innovative thermal-aware design techniques, methodologies and prototype tools for controlling, compensating and managing thermally-induced effects on parameters such as timing, (dynamic and leakage) power, reliability and yield	Determine the temperature inversion intersection point of two temperatures corresponding supply voltage within 20% for relevant parameters as performance and Ion. [IMC]	Test case 3	2
	MO7.1.8	Validate the high-k metal gate 28nm CMOS models developed in WP2, with cross-technology reference to 40 nm	Error between Testcase 3 measurements and simulation within 20 % . [IMC]	Test chse 3	3
	MO7.1.9	Demonstration of the applicability and effectiveness of the new design solutions through manufacturing of test-chips featuring leading-edge silicon technology, as available from some of the project partners	Demonstration of model hardware correlation based on 40nm and 28nm testchips (one or more testchips per technology). [IMC]	Test case 3	4
	MO7.1.10	Demonstration of the	The circuit-referenced PSP-	Test case 3	5

		usability and effectiveness of the new design methodologies and tools by their application to industry-strength design cases made available by some of the project partners	methodology is 100% compatible to the IMC design flow. [IMC]		
	MO7.1.11	Validation of self-heating models for advanced CMOS developed in D2.1.4	Accuracy of models versus measurements Error within 10% [FHG]	Testcase 3 Levels 2 to 4	1
	MO7.1.12	verify numerical distributed models for self-heating in substrates (not existing before Therminator) with experimental data	10% maximum deviation with measured figures of merit, relevant for specific application (available gain and Ft for analog applications, oscillation frequency of ring oscillators, switching delay for digital circuits). [UNIBO]	Testcase 2	1
	MO7.1.13	Thermal analysis engine 3D including TSV	Accuracy versus Measurement data, error less than 5C [IMEC]	Test structures to determine influence materials and density of interconnect Testcase 6	1

13 Publications and presentations

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- Wei Liu, V. Tenace, A. Calimera, A. Macii, E. Macii, M. Poncino, “*NBTI Effects on Tree-Like Clock Distribution Networks*”, GLSVLSI-12: accepted for publication
- A. Sassone, W. Liu, A. Calimera, A. Macii, E. Macii, M. Poncino, “*Modeling of thermally induced skew variations in clock distribution network*”, THERMINIC-11: IEEE Thermal Investigations of ICs and Systems, 2011.

- L. M. de Lima Silva, A. Calimera, A. Macii, E. Macii, M. Poncino, "Power Efficient Variability Compensation Through Clustered Tunable Power-Gating", IEEE Journal on Emerging and Selected Topics in Circuits and Systems, vol.1, no.3, Sept. 2011
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